Si2493/57/34/15/04 (Revision D) and Si2494/39 Modem Designer's Guide

1. Introduction

The Si2494/93/57/39/34/15/04 ISOmodem chipset family consists of a 38-pin QFN (Si2494/39) or 24-pin TSSOP (Si2493/57/34/15/04) or 16-pin SOIC (Si2493/57/34/15/04) low-voltage modem device, and a 16-pin SOIC line-side DAA device (Si3018/10) connecting directly with the telephone local loop (Tip and Ring). This modem solution is a complete hardware (controller-based) modem that connects to a host processor through a UART, parallel or SPI interface. Parallel and EEPROM interfaces are available only on the 38-pin QFN or 24-pin TSSOP package option. Refer to Table 4, "ISOmodem Capabilities," on page 10 for available part number, capability and package combinations. Isolation is provided by Silicon Laboratories' isolation capacitor technology, which uses high-voltage capacitors instead of a transformer. This isolation technology complies with global telecommunications standards including FCC, ETSI ES 203 021, JATE, and all known country-specific requirements.

Additional features include programmable ac/dc termination and ring impedance, on-hook and off-hook intrusion detection, Caller ID, loop voltage/loop current monitoring, overcurrent detection, ring detection, and the hook-switch function. All required program and data memory is included in the modem device. When the modem receives a software or hardware reset, all register settings revert to the default values stored in the on-chip program memory. The host processor interacts with the modem controller through AT commands used to change register settings and control modem operation. Country, EMI/EMC, and safety test reports are available from Silicon Laboratories representatives and distributors.

This application note is intended to supplement the Si2494/39 Revision A, Si2493 Revision D, and the Si2457/34/15/04 Revision D data sheets. It provides all the hardware and software information necessary to implement a variety of modem applications, including reference schematics, sample PCB layouts, AT command and register reference, country configuration tables, programming examples and more. Particular topics of interest can be easily located through the table of contents or the comprehensive index located at the back of this document.
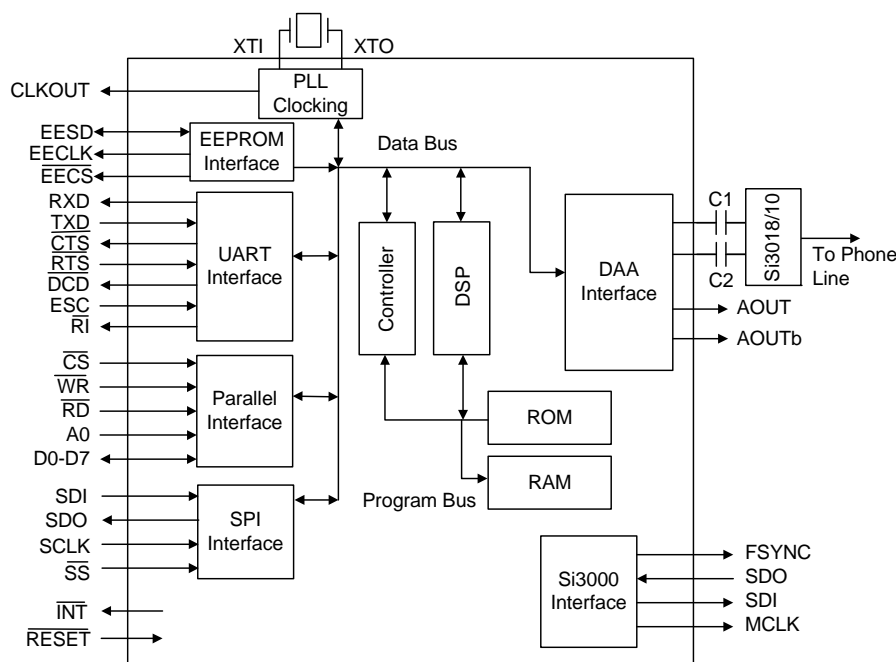

Figure 1. Functional Block Diagram

This information applies to a product under development. Its characteristics and specifications are subject to change without notice.

TABLE OF CONTENTS

SILICON LABS

SILICON LABS

SILICON LABS

SILICON LABS

1.1. Selection Guide

Tables 1 through 3 list the modulations, protocols, carriers, tones and interface modes supported by the Si2494/39 and Si2493/57/34/15/04 ISOmodem family. The Si2493 supports all modulations and protocols from Bell 103 through V.92. The Si2457 supports all modulations and protocols from Bell 103 through V.90. The Si2434 supports all modulations and protocols from Bell 103 through V.34. The Si2415 supports all modulations and protocols from Bell 103 through V.32bis. The Si2404 supports all modulations and protocols from Bell 103 through V.22bis.

Table 1. Modulations

Modulation	Data Rates (bps)	Modulation	Si2494/93	Si2457	Si2439/34	Si2415	Si2404
V.92*	48k, 40k, 32k, 24k	PCM	✔				
V.90*	56k, 54.6k, 53.3k, 52k, 50.6k, 49.3k, 48k, 46.6k, 45.3k, 44k, 42.6k, 41.3k, 40k, 38.6k, 37.3k, 36k, 34.6k, 33.3k, 32k, 30.6k, 29.3k, 28k	PCM	✔	✔			
V.34*	33.6k, 31.2k, 28.8k, 26.4k, 24k, 21.6k, 19.2k, 16.8k, 14.4k, 12k, 9600, 7200, 4800, 2400	TCM	✔	✔	✔		
V.32bis*	14.4k, 12k, 9600, 7200, 4800	TCM	✔	✔	✔	✔	
V.32*	9600 9600, 4800	TCM QAM	✔	✔	✔	✔	
V.29FC*	9600	QAM	✔	✔	✔	✔	✔ *
V.23	1200	FSK	✔	✔	✔	✔	✔
V.22bis	2400, 1200	QAM	✔	✔	✔	✔	✔
V.22	1200	DPSK	✔	✔	✔	✔	✔
Bell 212A	1200	DPSK	✔	✔	✔	✔	✔
V.21	300	FSK	✔	✔	✔	✔	✔
Bell 103	300	FSK	✔	✔	✔	✔	✔
*Note: With the Si3018 DAA only.							

Table 2. Protocols

Protocol*	Function	Si2494/93	Si2457	Si2439/34	Si2415	Si2404
V.44	Compression	✔				
V.42bis	Compression	✔	✔	✔	✔	✔
V.42	Error Correction	✔	✔	✔	✔	✔
MNP5	Compression	✔	✔	✔	✔	
MNP2-4	Error Correction	✔	✔	✔	✔	✔
*Note: The Si2494/93/57/39/34/15/04 family allows any supported protocol combined with any modulation.						

Table 3. Carriers and Tones

Specification	Transmit Carrier (Hz)	Receive Carrier (Hz)	Answer Tone (Hz)	Carrier Detect (Acquire/Release)
V.92	Variable	Variable		per ITU-T V.92
V.90	Variable	Variable		per ITU-T V.90
V.34	Variable	Variable		per ITU-T V.34
V.32bis	1800	1800	2100	per ITU-T V.32bis
V.32	1800	1800	2100	per ITU-T V.32
V.29	1700	1700		per ITU-T V.29
V.22bis, V.22 Originate/answer	1200 2400	2400 1200	2100	–43 dBm/–48 dBm –43 dBm/–48 dBm
V.21 Originate/answer (M/S)	1180/980 1850/1650	1850/1650 1180/980	2100	–43 dBm/–48 dBm –43 dBm/–48 dBm
Bell 212A Originate/answer	1200 2400	2400 1200	2225	–43 dBm/–48 dBm –43 dBm/–48 dBm
Bell 103 Originate/answer (M/S)	1270/1070 2225/2025	2225/2025 1270/1070	2225	–43 dBm/–48 dBm –43 dBm/–48 dBm

Table 4. ISOmodem Capabilities

Part Numbers	Package	UART	EEPROM	SPI	Parallel	SSI/Voice
Si2493/57/34/15/04[1]	SOIC-16	✔		✔		
Si2493/57/34/15/04[1]	TSSOP-24	✔	✔ [2]	✔	✔	
Si2494/39	QFN-38	✔	✔	✔	✔	✔

Notes:
1. Die Revision D or later
2. The EEPROM interface option is available only when the UART or SPI interface is selected.

SILICON LABS

2. Modem (System-Side) Device

The Si24xx ISOmodem system-side devices contain a controller, a DSP, program memory (ROM), data memory (RAM), UART, SPI and parallel interfaces, a crystal oscillator, and an isolation capacitor interface. The following sections describe the reset sequence, the host interface, the isolation interface, low-power modes, SSI/voice mode and the EEPROM interface.

2.1. Resetting the Device

Reset is required after power-on or brownout conditions (the supply dropping to less than the data sheet minimum). The supply must be stable throughout the minimum required reset time described here and thereafter. A reset is also required in order to come out of the power down mode.

Some operational choices, including the crystal oscillator frequency used and the command interface used (e.g. UART vs SPI), is made during the reset time according to pull-down resistors placed on some modem pins. These pins are modem output lines, but, during reset, the modem places them into a high-impedance mode with weak internal pull-ups, then reads the user's strapping choices. It is important that the resultant state changes of these pins during reset are not misinterpreted by the host.

For example the INT output pin of the modem (and perhaps others) can be strapped low with a 10 kΩ resistor to request SPI operation. If that mode is chosen, the host should take care not to enable this interrupt input before the modem reset since the INT signal will transition from high to low and back up during reset in this case and can generate an unexpected interrupt.

If an external clock signal is provided instead of a crystal attached to the modem, it is important that this external clock signal be stable before the reset ends.

2.1.1. Reset Sequence

After power-on, the modem must be reset by asserting the RESET pin (low) for the required time then waiting a fixed 300 ms before sending the first AT command. The reset recovery time of 300 ms is also applicable if the reset is a SW triggered event, such as an ATZ command.

If a 4.9152 MHz crystal or an external 27 MHz clock is used, the reset must be asserted for 5 ms, and a wait of 300 ms duration must happen before an AT command is issued. If a 32 kHz crystal is used, the reset pulse must be 500 ms long and followed by the same 300 ms duration wait as that used for higher frequency clocks.

This is adequate to reset all the on-chip registers. Note that 16 μs after the customer-applied reset pulse starts, the I/O pins will be tri-stated with a weak pull-up, and, 16 μs after the end of this reset pulse, the IO pins will switch to inputs or outputs as appropriate to the mode indicated by the pull-down strapping. This 16 μs delay is for newer revs of the modem parts (those parts that introduce a 32 kHz crystal and SPI operation); older revs exhibit a delay of only nanoseconds.

The reset sequence described above is appropriate for all user modes of the modem including UART, SPI, and Parallel bus operation.

A software reset of the modem can also be performed by issuing the command ATZ or by setting U-register 6E bit 4 (RST) high using AT commands. After issuing a software or hardware reset, the host must wait for the reset recovery time before issuing any subsequent AT commands.

There is no non-volatile memory on the ISOmodem other than program ROM. When reset, the ISOmodem reverts to the original factory default settings. Any set-up or configuration data and software updates must be reloaded after every reset. This is true whether the reset occurs due to a power-down/power-up cycle, a power-on reset through a manual reset switch, by writing U6E [4] (RST) = 1, or by executing ATZ.

A suggested reset sequence is as follows:

1. Apply an active-low pulse to the RESET pin; write RST bit or ATZ<CR>.
2. Wait at least the reset recovery time.
3. Load firmware updates (if required).
4. Set non-default DAA interface parameters—DCV, ACT, ILIM, OHS2, OHS, RZ, RT, (U67), LIM, (U68).
5. Set non-default cadence values—Busy Tone, Ringback, Ring.

6. Set non-default frequency values—Ring.

7. Set non-default filter parameters.

8. Set non-default S-register values.

The modem is now ready to detect rings, answer another modem, call, or dial out to a remote modem.

Some key default settings for the modem after reset or powerup include the following:

■ V.92 and fall-backs enabled (Si2494/93)

■ V.90 and fall-backs enabled (Si2457)

■ V.34 and fall-backs enabled (Si2439/34)

■ V.32bis and fall-backs enabled (Si2415)

■ V.22bis and fall-backs enabled (Si2404)

■ V.42/42bis enabled

■ +++ escape sequence enabled

■ Answer-on-ring is disabled

■ Speaker off

■ DTE echo enabled

■ Verbal result codes enabled

■ CTS only enabled

■ FCC (US) DAA and call progress settings

2.1.2. Reset Strapping: General Considerations

The different options available in the Si24xx ISOmodem family are selected by means of 10 kΩ pulldown resistors placed at certain pins. During power-on or pin reset, the ISOmodem's signal pins are read and the option resistors are taken into account to determine the required configuration. After reset, the ISOmodem assumes the functionality selected by the corresponding combination of pulldown resistors.

Below is a summary of reset-strap options. Not all options are available on all part number or packages. Refer to Table 4, "ISOmodem Capabilities," on page 10 for details.

■ Host interface: UART, parallel or SPI

■ Input clock frequency: 32 kHz, 4.9152 MHz or 27 MHz

■ Autobaud mode or fixed-rate UART communication (when UART interface is selected). Disabling the autobaud feature at reset sets the rate to 19,200 baud.

■ EEPROM interface

■ Three-wire EEPROM or four-wire EEPROM when EEPROM interface is selected

Refer to "2.6. EEPROM Interface (24-Pin TSSOP and 38-Pin QFN Only)" on page 31 for more details on the various ISOmodem EEPROM options.

The next few sections describe the various reset options that must be selected for each package. In all the tables, the following conventions apply:

■ 0 means a 10 kΩ pulldown resistor to ground.

■ 1 means the pin is left open. If a pin is left open, the internal pullup resistor is normally sufficient as long as the pin is not driven externally during reset. If there is noise or special power-sequencing situations, then an external pullup resistor may be needed.

SILICON LABS

2.1.3. Reset-Strap Options for 16-Pin SOIC Package

The clock frequency and interface on the 16-pin SOIC package are selected according to Table 5 below. The parallel interface, EEPROM and autobaud options are not available in the 16-pin SOIC package.

Table 5. SOIC-16 Reset-Strap Options

Mode		Reset-Strap Pins				
Interface	Input Clock	Pin 3 RI	Pin 5, RXD/MISO	Pin 7, $\overline{\text{CTS}}$/SCLK	Pin 11 INT	Pin 15 DCD
UART	32 kHz	0	X	1	1	X
	4.9152 MHz	1	X	1	1	1
	27 MHz	1	X	1	1	0
SPI	32 kHz	1	1	X	0	1
	4.9152 MHz	0	1	X	0	X
	27 MHz	1	1	X	0	0

2.1.4. Reset-Strap Options for 24-Pin TSSOP Package

The pin-strapping options for the 24-pin TSSOP package are described in the three subsections below, depending on the interface mode selected.

2.1.4.1. Reset Strapping Options for TSSOP-24 with UART-Interface

UART-interface options for the 24-pin TSSOP package are shown in Table 6 below.

Table 6. TSSOP-24 UART-Interface Options

Mode			Reset-Strap Pins				
Input Clock	**Autobaud Disabled?**	**Three-Wire EEPROM Interface?**	**Pin 4** $\overline{\text{FSYNC}}$	**Pin 11, $\overline{\text{CTS}}$ Pin 15, AOUT Pin 16, $\overline{\text{INT}}$**	**Pin 17** $\overline{\text{RI}}$	**Pin 18 SDI/EESD**	**Pin 23** $\overline{\text{DCD}}$
32 kHz	No	No	1	1	0	1	X
		Yes	0	1	0	1	X
	Yes	No	1	1	0	0	X
		Yes	0	1	0	0	X
4.9152 MHz	No	No	1	1	1	1	1
		Yes	0	1	1	1	1
	Yes	No	1	1	1	0	1
		Yes	0	1	1	0	1
27 MHz	No	No	1	1	1	1	0
		Yes	0	1	1	1	0
	Yes	No	1	1	1	0	0
		Yes	0	1	1	0	0

2.1.4.2. Reset Strapping Options for TSSOP-24 with Parallel-Interface

Parallel-interface options for the 24-pin TSSOP package appear in Table 7 below. The EEPROM and autobaud options are not available when the parallel interface is selected.

Table 7. TSSOP-24 Parallel-Interface Options

Mode	Reset-Strap Pins		
Input Clock	**Pin 9, $\overline{\text{RD}}$ Pin 10, $\overline{\text{WR}}$**	**Pin 11 SCLK**	**Pin 15 INT**
27 MHz	1	0	0
4.9152 MHz	1	1	0

SILICON LABS

2.1.4.3. Reset Strapping Options for TSSOP with SPI-Interface

Table 8 lists the SPI-interface options for the 24-pin TSSOP package.

Table 8. TSSOP-24 SPI-Interface Clock-Frequency Options

Mode		Reset-Strap Pins				
Input Clock	Three-Wire EEPROM Interface?	Pin 4 $\overline{\text{FSYNC}}$	Pin 9, RXD Pin 11, SCLK Pin 15, AOUT Pin 18, SDI/EESD	Pin 16 $\overline{\text{INT}}$	Pin 17 $\overline{\text{RI}}$	Pin 23 $\overline{\text{DCD}}$
32 kHz	No	1	1	0	1	1
	Yes	0	1	0	1	1
4.9152 MHz	No	1	1	0	0	X
	Yes	0	1	0	0	X
27 MHz	No	1	1	0	1	0
	Yes	0	1	0	1	0

2.1.5. Reset Strapping Options for QFN Parts

2.1.5.1. Reset Strapping Options for QFN Parts with UART Operation

Table 9 lists the reset strapping options for QFN parts with UART operation.

Table 9. Reset Strapping Options for QFN Parts with UART Operation

Input Clk	Auto-Baud Disable	Three-Wire EEPROM Interface	$\overline{\text{FSYNCH}}$	$\overline{\text{CTS}}$	AOUT	EECLK	$\overline{\text{INT}}$	$\overline{\text{RI}}$	SDI	$\overline{\text{DCD}}$
			Pin 2	Pin 21	Pin 15	Pin 13	Pin 35	Pin 19	Pin 8	Pin 28
32 kHz	No	No	1	1	1	1	1	1	1	1
		Yes	0	1	1	1	1	1	1	1
	Yes	No	1	1	1	1	1	1	0	1
		Yes	0	1	1	1	1	1	0	1
4.9152 MHz	No	No	1	1	1	1	1	0	1	X
		Yes	0	1	1	1	1	0	1	X
	Yes	No	1	1	1	1	1	0	0	X
		Yes	0	1	1	1	1	0	0	X
27 MHz	No	No	1	1	1	1	1	1	1	0
		Yes	0	1	1	1	1	1	1	0
	Yes	No	1	1	1	1	1	1	0	0
		Yes	0	1	1	1	1	1	0	0

2.1.5.2. Reset Strapping Options for QFN Parts with SPI Operation

Table 10 lists the reset strapping options for QFN parts with SPI operation.

Table 10. Reset Strapping Options for QFN parts with SPI Operation

Input Clk	Three-Wire EEPROM Interface	$\overline{\text{FSYNCH}}$	AOUT	EECLK	$\overline{\text{INT}}$	$\overline{\text{RI}}$	SDI	$\overline{\text{DCD}}$	MISO
		Pin 2	Pin 15	Pin 13	Pin 35	Pin 19	Pin 8	Pin 28	Pin 22
32 kHz	No	1	1	1	0	1	1	1	1
	Yes	0	1	1	0	1	1	1	1
4.9152 MHz	No	1	1	1	0	0	1	X	1
	Yes	0	1	1	0	0	1	X	1
27 MHz	No	1	1	1	0	1	1	0	1
	Yes	0	1	1	0	1	1	0	1

2.1.5.3. Reset Strapping Options for QFN Parts with Parallel Operation

Table 11 lists the reset strapping options for QFN parts with parallel operation.

Table 11. Reset Strapping Options for QFN Parts with Parallel Operation

Input Clk	$\overline{\text{CS}}$	AOUT	EECLK	$\overline{\text{RD}}$
	Pin 21	Pin 15	Pin 13	Pin 22
32 kHz	1	0	1	1
	1	0	1	1
4.9152 MHz	1	0	0	1
	1	0	0	1
27 MHz	0	0	1	1
	0	0	1	1

2.2. System Interface

The ISOmodem can be connected to a host processor through a UART, SPI or parallel interface. Connection to the chip requires low-voltage CMOS signal levels from the host and any other circuitry interfacing directly. The following sections describe the digital interface options in detail.

2.2.1. Interface Selection

The interface is selected during reset, as described in "2.1. Resetting the Device". Tables 12, 13, and 14 show the functions of the affected pins for possible interface modes for 16-, 24- and 38-pin packages, respectively.

Table 12. Pin Functions vs. Interface Mode (SOIC-16)

Pin #	UART Mode	SPI Mode
3	$\overline{RI}$	$\overline{RI}$
5	RXD	MISO
6	TXD	MOSI
7	$\overline{CTS}$	SCLK
11	$\overline{INT}$	$\overline{INT}$
14	ESC	ESC
15	$\overline{DCD}$	$\overline{DCD}$
16	$\overline{RTS}$	$\overline{SS}$

Table 13. Pin Functions vs. Interface Mode (TSSOP-24)

Pin #	UART Mode	SPI Mode	Parallel Mode
2	$\overline{FSYNC}$ (SSI)	$\overline{FSYNC}$ (SSI)	D6
3	CLKOUT (SSI)	CLKOUT (SSI)	A0
8	$\overline{RTS}$	$\overline{SS}$	D7
9	RXD	MISO	$\overline{RD}$
10	TXD	MOSI	$\overline{WR}$
11	$\overline{CTS}$	SCLK	$\overline{CS}$
15	AOUT	AOUT	$\overline{INT}$
16	$\overline{INT}$	$\overline{INT}$	D0
17	$\overline{RI}$	$\overline{RI}$	D1
18	SDI (SSI)	SDI (SSI)	D2
22	ESC	ESC	D3
23	$\overline{DCD}$	$\overline{DCD}$	D4
24	SDO (SSI)	SDO (SSI)	D5

Table 14. Pin Functions vs. Interface Mode (QFN-38)

Pin #	UART Mode	SPI Mode	Parallel Mode
35	$\overline{\text{INT}}$	$\overline{\text{INT}}$	$\overline{\text{INT}}$
34	GPIO18	GPIO18	D0
33	GPIO17	GPIO17	D1
32	GPIO16	GPIO16	D2
31	GPIO23	GPIO23	D3
30	GPIO24	GPIO24	D4
29	ESC		D5
28	$\overline{\text{DCD}}$		D6
24	RTS	$\overline{\text{SS}}$	D7
23	TXD	MOSI	$\overline{\text{WR}}$
22	RXD	MISO	$\overline{\text{RD}}$
21	$\overline{\text{CTS}}$	SCLK	$\overline{\text{CS}}$
20	GPIO11	GPIO11	A0
19	$\overline{\text{RI}}$		

SILICON LABS

2.2.2. Interface Signal Description

The following tables describe each set of UART, parallel and SPI interface signals:

Table 15. UART-Interface Signals

Signal	Direction	Description
TXD	Input	Data input from host TXD pin
RXD	Output	Data output to host RXD pin
$\overline{RTS}$	Input	Active-low request-to-send input for flow control
$\overline{CTS}$	Output	Clear to send: Si2493 is ready to receive data on the TXD pin (active low)

Table 16. SPI-Interface Signals

Signal	Direction	Description
SCLK	Input	Serial data clock
MISO	Output	Serial data output
MOSI	Input	Serial data input
$\overline{SS}$	Input	Chip select (active low)
$\overline{INT}$	Output	Interrupt (active low)

Table 17. Parallel-Interface Signals

Signal	Direction	Description
A0	Input	Register selection (address input)
$\overline{CS}$	Input	Chip select (active low)
$\overline{RD}$	Input	Read enable (active low)
$\overline{WR}$	Input	Write enable (active low)
D[7:0]	Bidirectional	Parallel data bus
$\overline{INT}$	Output	Interrupt (active low)

2.2.3. UART Interface Operation

The UART interface allows the host processor to communicate with the modem controller through a UART driver. In this mode, the modem is analogous to an external "box" modem. The interface pins are 5 V tolerant and communicate with TTL-compatible, low-voltage CMOS levels. RS232 interface chips, such as those used on the modem evaluation board, can be used to make the UART interface directly compatible with a PC or terminal serial port.

2.2.3.1. UART Options

The DTE rate is set by the autobaud feature after reset. When autobaud is disabled, the UART is configured to 19.2 kbps, 8-bit data, no parity and 1 stop bit on reset. The UART data rate is programmable from 300 bps to 307.2 kbps with the AT\Tn command (see Table 42, "Extended AT\ Command Set," on page 81). After the AT\Tn command is issued, the ISOmodem echoes the result code at the old DTE rate. After the result code is sent, all subsequent communication is at the new DTE rate.

The DTE baud clock is within the modem crystal tolerance (typically ±50 ppm), except for DTE rates that are uneven multiples of the modem clock. All DTE rates are within the +1%/–2.5% required by the V.14 specification. Table 18 shows the ideal DTE rate, the actual DTE rate, and the approximate error.

The UART interface synchronizes on the start bits of incoming characters and samples the data bit field and stop bits. The interface is designed to accommodate character lengths of 8, 9, 10, and 11 bits giving data fields of 6, 7, 8, or 9 bits. Data width can be set to 6, 7, or 8 bits with the AT\Bn command. Parity can be set to odd, even, mark, or space by the AT\Pn command in conjunction with AT\B2 or AT\B5. Other AT\Bn settings have no parity.

Table 18. DTE Rates

Ideal DTE Rate (bps)	Actual DTE Rate (bps)	Approximate Error(%)
300	300	
600	600	
1200	1200	
2400	2400	
7200	7202	0.01
9600	9600	
12000	12003	0.02
14400	14400	
19200	19200	
38400	38400	
57600	57488	0.2
115200	115651	0.4
230400	228613	0.8
245760	245760	
307200	307200	
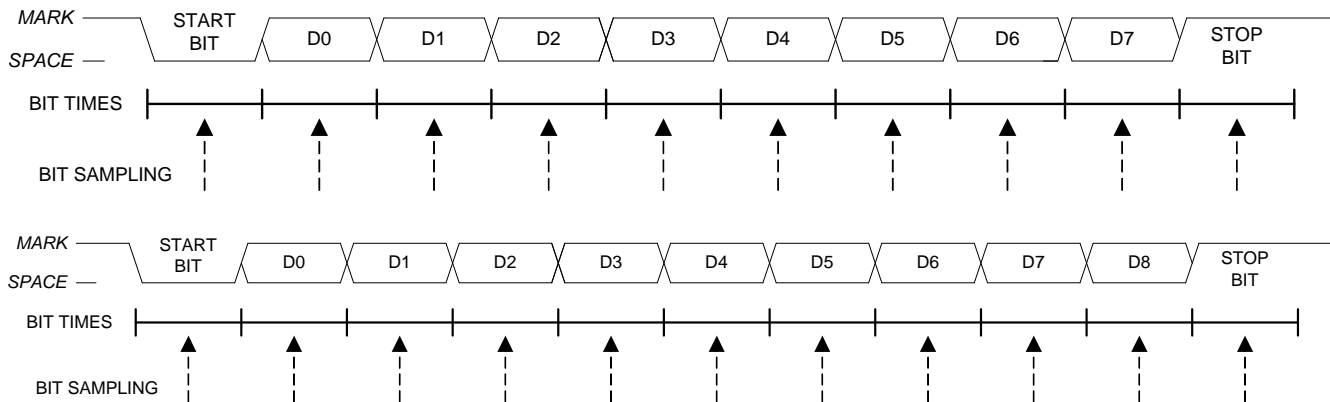
Figure 2. Asychronous UART Serial Interface Timing Diagram

2.2.3.2. Autobaud

When set in UART interface mode, the ISOmodem includes an automatic baud rate detection feature that allows the host to start transmitting data at any standard DTE rate from 300 bps to 307.2 kbps. This feature is enabled by default. When autobaud is enabled, it continually adjusts the baud rate, and the ISOmodem always echoes result codes at the same baud rate as the most recently received character from the host. Autobaud can be turned off using AT commands \T0 through \T15, and \T17. Host software should disable autobaud operation once the DTE rate has been established. This prevents transients on TXD to cause inadvertent baud rate changes.

Autobaud is off when dialing, answering, and in data mode. When autobaud mode is off, the baud rate is set to the most recently-active baud rate prior to entering one of these states. When autobaud mode is on, autoparity is performed when either "at" or "AT" is detected. Autoparity detects the formats listed in Table 19.

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Table 19. Serial Formats Detected in Autobaud Mode

Symbol	Data bits	Parity	Stop bits
7N1	7	None (mark)	1
7N2	7	None (mark)	2
7S1	7	None (space)	1
7O1	7	Odd	1
7E1	7	Even	1
8N1	8	None (mark)	1
8E1	8	Even	1
8O1	8	Odd	1
9N1	9	None (mark)	1

Note: For 7N1, the modem is programmed to 7 data bits, mark parity and one stop bit. This may be changed with the AT\P and AT\B commands. In autobaud mode, 7N1 is properly interpreted and echoed, but the AT\P and AT\B commands must be sent prior to dialing in order to lock the parity and format to 7N1. Otherwise, the ISOmodem locks to 7 bits, mark parity and two stop bits (7N2).

2.2.3.3. Flow Control

The ISOmodem supports flow control through $\overline{RTS}/\overline{CTS}$ and XON/XOFF. $\overline{RTS}$ (request-to-send) is a control signal from the terminal (DTE) to the modem (DCE) indicating data may be sent from the modem to the terminal. $\overline{CTS}$ (clear-to-send) is a control signal from the modem (DCE) to the terminal (DTE) indicating data may be sent from the terminal to the modem for transmission to the remote modem. This arrangement is typically referred to as hardware flow control. There is a 14-character FIFO and a 1024 character elastic transmit buffer (see Figure 3). $\overline{CTS}$ goes inactive (high) when the 1024 character buffer reaches 796 characters, then reasserts (low) when the buffer falls below 128 characters. There is no provision to compensate for FIFO overflow. Data received on TXD when the FIFO is full are lost.

XON/XOFF is a software flow control method in which the modem and terminal control the data flow by sending XON characters (^Q/0x11) and XOFF characters (^S/0x13). XON/XOFF flow control is enabled on the ISOmodem with AT\Q4.

$\overline{DCD}$ does not de-assert during a retrain (see Table 45: S9, Carrier presence timer and S10, Carrier loss timer). $\overline{CTS}$ always deasserts during initial training, retrain, and at disconnect regardless of the \Qn setting. For \Q0 $\overline{CTS}$, flow control is disabled; $\overline{CTS}$ is inactive during data transfer. The modem remains in the data mode during normal automatic retrains. The host can force a retrain by escaping to the command mode and sending ATO1 or ATO2.

The $\overline{DCD}$ and $\overline{RI}$ pins can be used as hardware monitors of the carrier detect and ring signals. Additionally, the $\overline{INT}$ pin can be programmed to monitor the bits in register U70 listed in Table 20. The RI, PPD, OCD, CID, and RST bits are sticky, and the AT:I command reads and clears these signals and deactivates the $\overline{INT}$ pin if $\overline{INT}$ is enabled.

Table 20. Register U70 Signals $\overline{\text{INT}}$ Can Monitor

Signal	U70 Bit	Function
DCD	0	Data Carrier Detect—active high (inverse of $\overline{\text{DCD}}$ pin)
RI	1	Ring Indicator—active high (inverse of $\overline{\text{RI}}$ pin)
PPD	2	Parallel Phone Detect
OCD	3	Overcurrent Detect
CID	4	Caller ID Preamble Detect

1024 Character Elastic Tx Buffer
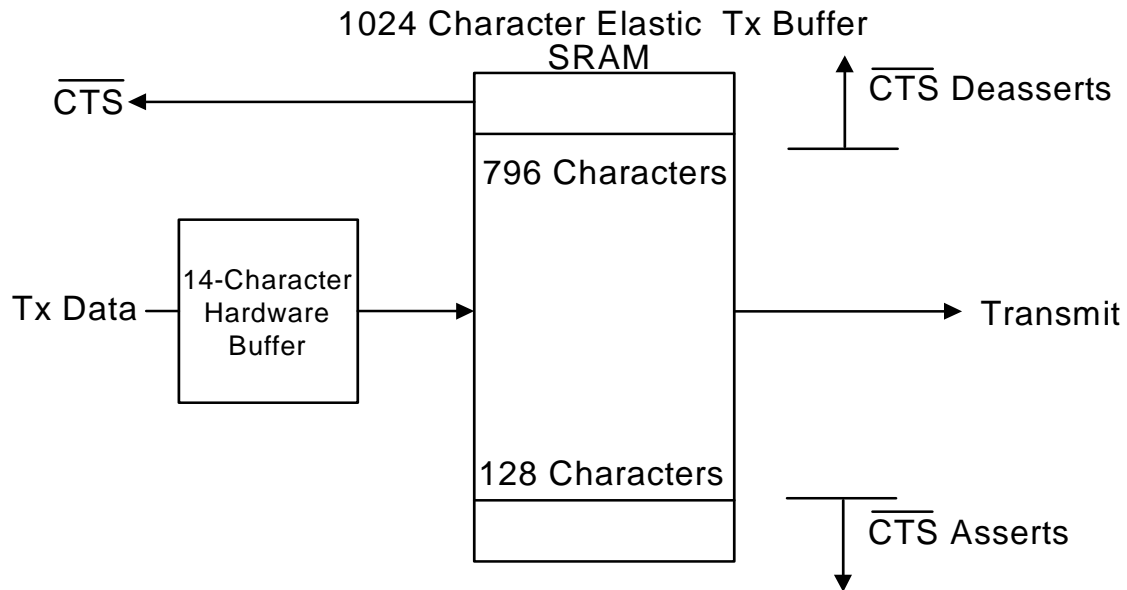
Figure 3. Transmit Data Buffers

1024 Character Elastic Rx Buffer
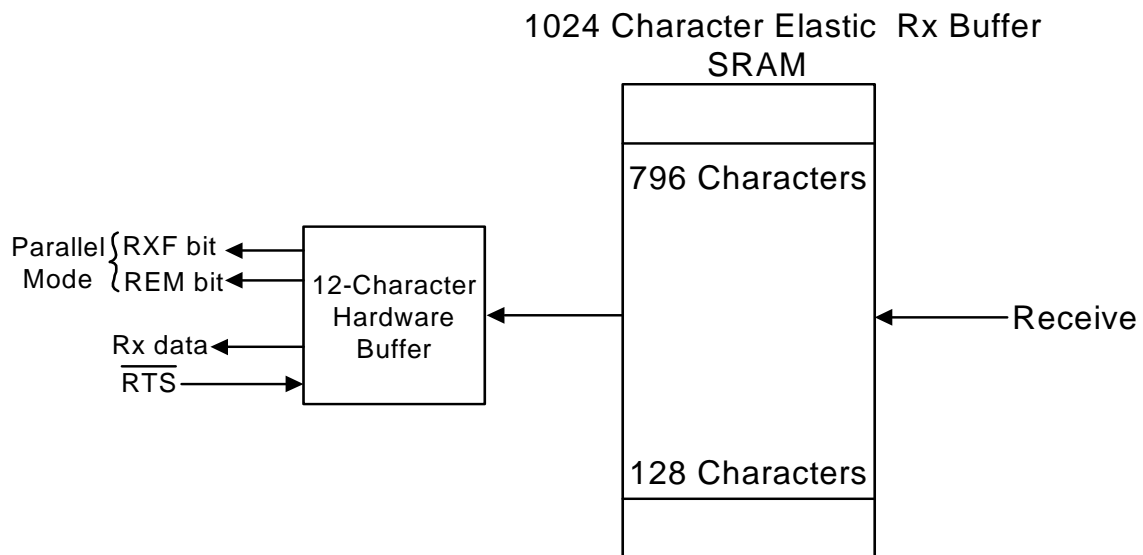
Figure 4. Receive Data Buffers

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A block diagram of the UART in the serial interface mode is shown in Figure 5.
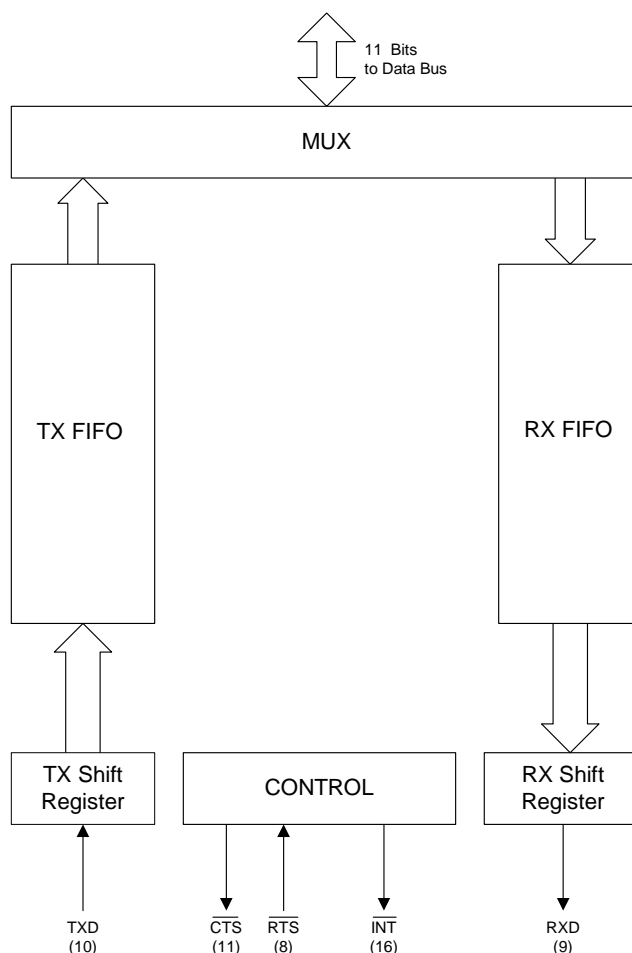
Figure 5. UART Serial Interface

2.2.4. Parallel and SPI Interface Operation

Refer to "2.1. Resetting the Device" on page 11 for interface selection. The parallel interface has an 8-bit data bus and a single address bit. The SPI likewise operates with 8-bit data transfers, using a single address bit. When the parallel or SPI interface mode is selected, the modem must be configured for a DTE interface or 8N1 only. The host processor must calculate parity for the MSB. The modem sends bits as received by the host and does not calculate parity. Refer to "Appendix C—Parallel/SPI Interface Software Implementation" on page 290 for detailed parallel or SPI interface application information.

The parallel or SPI interface uses the FIFOs to buffer data in the same way as in UART mode, with the addition of Hardware Interface Registers 0 (HIR0) and Hardware Interface Register 1 (HIR1). The Hardware Interface Registers were formerly called Parallel Interface Registers (PIR0 and PIR1) in older products, because those products would support only a parallel interface. Flow control must be implemented by monitoring REM and TXE in HIR1. There is no protection against FIFO overflow. Data transmitted when the transmit FIFO is full are lost. Figure 6 shows the interaction of the transmit and receive FIFOs with the Hardware (Parallel) Interface Registers in the case of a parallel interface. The arrangement is similar when the SPI interface is selected. Table 21 on page 25 shows a bit map of HIR0 and HIR1.

UART oriented control lines, such as RTS and CTS, are not used in Parallel and SPI Interface mode. They are replaced by bits in the HIR1 register.

SPI and parallel operation only supports 8-bit data words. The longer words that are implied by the \B5 (8P1) & \B6 8X1 commands are not allowed. These commands should not be used.
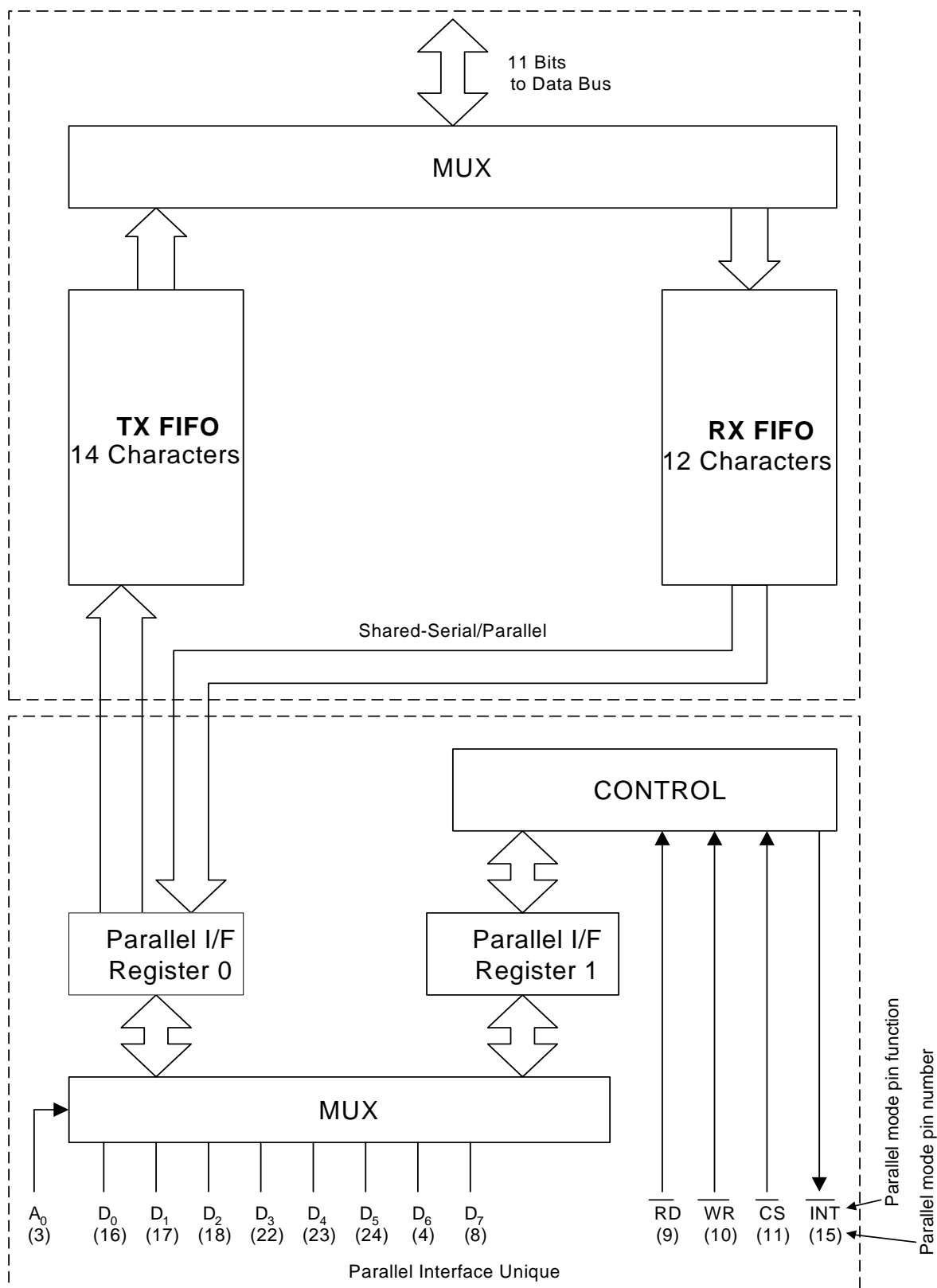
Figure 6. Parallel Interface

Table 21. Hardware Interface Register Bit Map

A0	$\overline{RD}$	$\overline{WR}$	Action	Register	D7	D6	D5	D4	D3	D2	D1	D0
0	0	1	Read	HIR0	Modem data or command from receive FIFO							
0	1	0	Write		Modem data or command to transmit FIFO							
1	0	1	Read	HIR1	RXF	TXE	REM	INTM	INT	ESC	$\overline{RTS}$	$\overline{CTS}$
1	1	0	Write		RXF	TXE	*Note	INTM	*Note	ESC	$\overline{RTS}$	n/a
*Note: REM and INT are read-only bits.												

2.2.4.1. Hardware Interface Register 0

Hardware Interface Register 0 (HIR0) is the eight-bit wide read/write location where modem data and commands are exchanged with the host. Writing a byte to the HIR0 adds that byte to the modem's transmit FIFO (AT command buffer in command mode or data transmission in data mode). If data are available (modem data in data mode or command responses, such as OK, in command mode), reading from the HIR0 fetches data from the modem's receive FIFO. The maximum burst data rate is approximately 350 kbps (45 kBps).

2.2.4.2. Hardware Interface Register 1

Hardware Interface Register 1 (HIR1) contains various status and control flags for use by the host to perform data flow control, to escape to command mode and to query various interrupt conditions. The HIR1 bit map is described in Table 22. This register is reset to 0x63.

Table 22. Hardware Interface Register 1

Bit	Name	R/W	Reset	Function
7	RXF	R/W	0	**Receive FIFO Almost Full**
6	TXE	R/W	1	**Transmit FIFO Almost Empty**
5	REM	R	1	**Receive FIFO Empty**
4	INTM	R/W	0	**Interrupt Mask** 0 = INT pin triggered on rising edge of RXF or TXE only 1 = INT pin triggered on rising edge of RXF, TXE or INT (bit 3 below)
3	INT	R	0	**Interrupt** 0 = No interrupt 1 = Interrupt triggered
2	ESC	R/W	0	**Escape**
1	$\overline{RTS}$	R/W	1	**Request-to-Send** (active low) — **Deprecated** — for flow control, use the TXE and REM bits for polling- or interrupt-based communication. **This bit must be written to zero.**
0	$\overline{CTS}$	R	1	**Clear-to-Send** (active low) — **Deprecated** — for flow control, use the TXE and REM bits for polling- or interrupt-based communication.

Bit 7 (RXF) is a read/write bit that gives the status of the 12-byte deep receive FIFO. If RXF = 0, the receive FIFO contains less than 10 bytes. If RXF = 1, the receive FIFO contains more than 9 bytes and is full or almost full. Writing RXF = 0 clears the interrupt.

Bit 6 (TXE) is a read/write bit that gives the status of the 14-byte deep transmit FIFO. If TXE = 0, the transmit FIFO contains three or more bytes. If TXE = 1, the transmit FIFO contains two or fewer bytes. Writing TXE = 0 clears the interrupt but does not change the state of TXE.

Bit 5 (REM) is a read-only bit that indicates when the receive FIFO is empty. If REM = 0, the receive FIFO contains valid data. If REM = 1, the receive FIFO is empty. The timer interrupt set by U6F ensures that the receive FIFO contents $\leq$ 9 bytes are serviced properly.

Bit 4 (INTM) is a read/write bit that controls whether or not INT (bit 3) triggers the $\overline{\text{INT}}$ pin.

Bit 3 (INT) is a read-only bit that reports Interrupt status. If INT = 0, no interrupt has occurred. If INT = 1, an interrupt due to CID, OCD, PPD, RI, or DCD (U70 bits 4, 3, 2, 1, 0, respectively) has occurred. This bit is reset by :I.

Bit 2 (ESC) is a read/write bit that is functionally equivalent to the ESC pin in the serial mode. The operation of this bit, like the ESC pin, is enabled by setting U70 [15] (HES) = 1.

The use of bits 1 and 0 ($\overline{\text{RTS}}$ and $\overline{\text{CTS}}$) has been deprecated for both parallel and SPI interfaces. Instead, the use of bits 6 and 5 (TXE and REM) is recommended for polling- and interrupt-based communication.

2.2.4.3. Parallel Interface Operation

When the device is powered up for parallel interface, the pins include eight data lines (D7–D0), a single address (A0), a read strobe ($\overline{\text{RD}}$), a write strobe ($\overline{\text{WR}}$), an interrupt line ($\overline{\text{INT}}$), and chip select ($\overline{\text{CS}}$). Table 23 summarizes the parallel-interface signals:

Table 23. Parallel Interface Signals

Signal	Function	Direction
$\overline{\text{CS}}$	Chip Select (active low)	Input
A0	Register address	Input
$\overline{\text{RD}}$	Read strobe (active low)	Input
$\overline{\text{WR}}$	Write strobe (active low)	Input
D[7:0]	Data bus	Bidirectional
$\overline{\text{INT}}$	Interrupt (active low)	Output

Refer to the device data sheet for timing characteristics. Address pin A0 allows the host processor to choose between the two interface registers, HIR0 and HIR1. The timing diagrams below show typical parallel-interface operation. Refer to the respective product data sheets for timing specifications.

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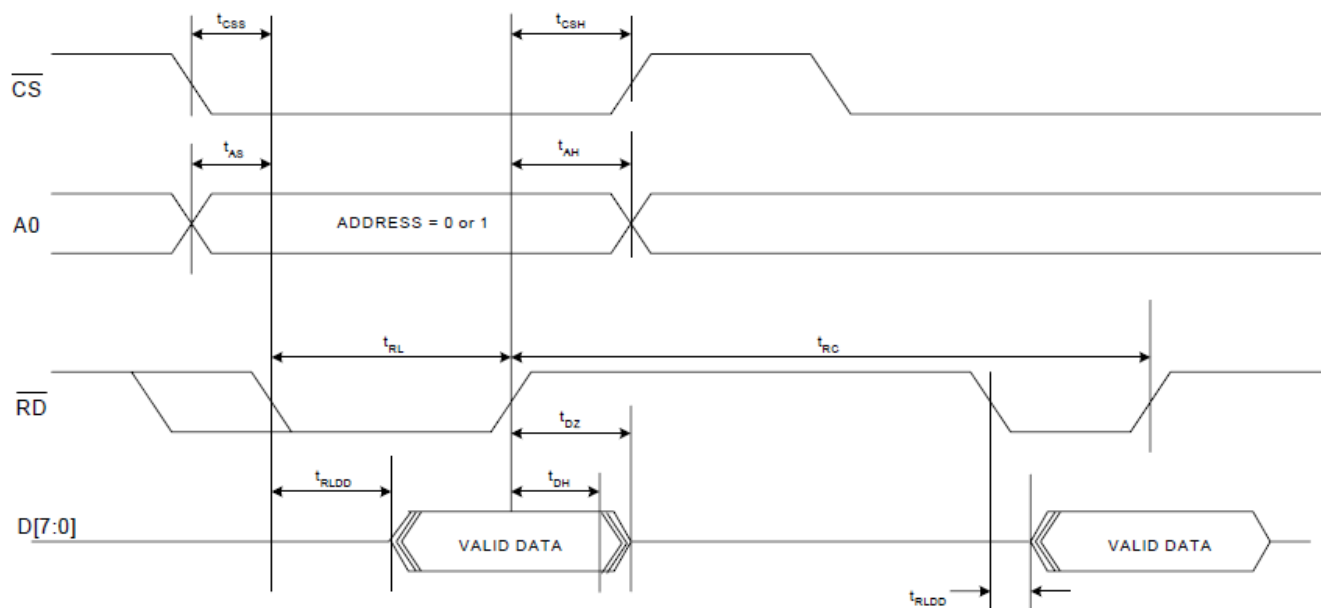
Figure 7. Parallel Interface Read Timing
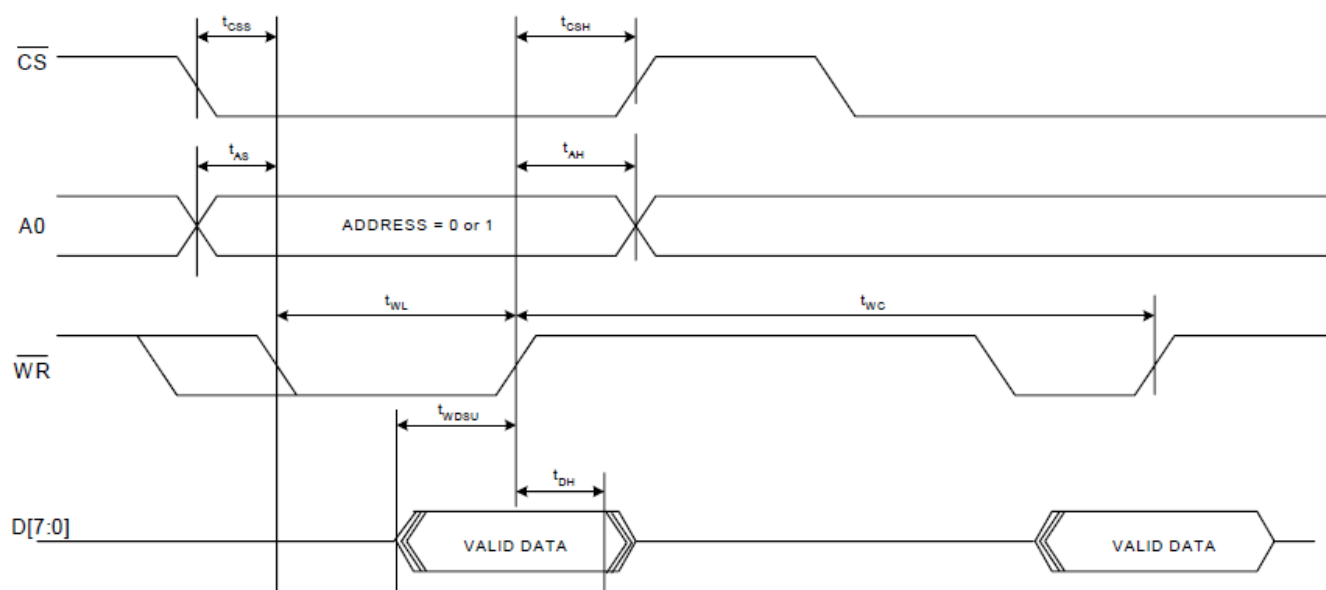
Figure 8. Parallel Interface Write Timing

2.2.4.4. SPI Interface Operation

SPI interface operation is supported in the Si2493/57/34/15/04 Revision D or later and the Si2494/39 Revision A or later. When the device is powered up for SPI interface, the modem becomes an SPI slave, and the pins are configured to $\overline{SS}$ (chip select input, active low), MOSI (serial data input to modem), MISO (serial data output from modem) and SCLK (serial data clock input). The HIR0 and HIR1 registers described above are also available in SPI mode. Each SPI operation consists of a control-and-address byte and a data byte. The bit definitions of the control-and-address byte are shown in Table 24. The timing diagrams that follow show SPI read and write waveforms. Refer to the device data sheet for timing characteristics.

Table 24. SPI Control-and-Address Bit Definitions

Bit	Function	Meaning when High	Meaning when Low
7	Address	Access HIR1	Access HIR0
6	Read/Write	Read register	Write register
5:0	Reserved	Not allowed	Must be all zeroes

SPI 2-Byte Write Protocol

SPI 2-Byte Read Protocol
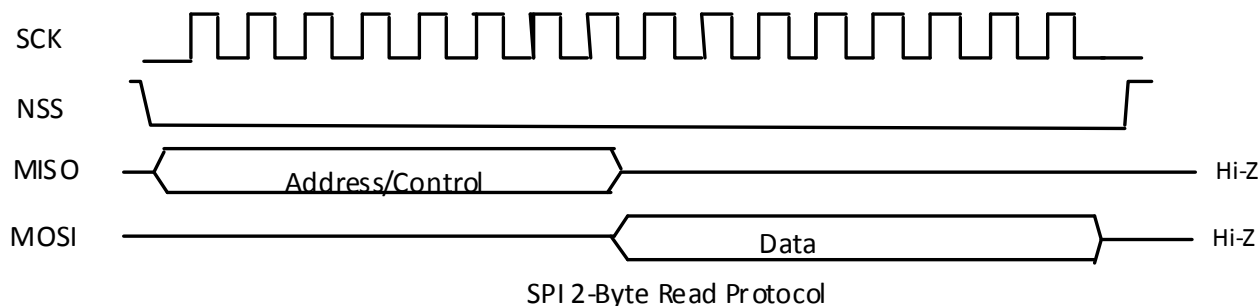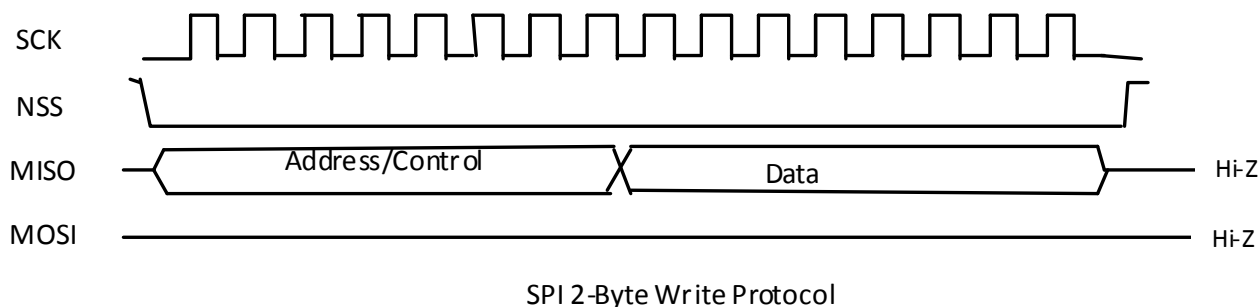
Figure 9. SPI Read and Write Timing Diagrams

2.2.4.5. Interface Communication Modes

Data flow control is implemented in the SPI and parallel interfaces differently from UART mode. When parallel or SPI mode is selected, data communication may be driven by interrupts or by polling. Refer to "Appendix C— Parallel/SPI Interface Software Implementation" on page 290 for implementation details for both methods. The parallel and SPI interfaces have four sources of interrupts and only one interrupt pin. The four interrupts are:

1. RXF Interrupt: receive FIFO almost full

2. TXE Interrupt: transmit FIFO almost empty

3. Timer Interrupt: receive FIFO not empty

4. U70 Interrupt: various conditions, such as ringing, parallel phone pickup, etc. as defined in register U70

The source of the interrupt can be determined by reading HIR1.

2.3. Isolation Capacitor Interface

The isolation capacitor is a proprietary high-speed interface connecting the modem chip and the DAA chip through a high-voltage isolation barrier provided by two capacitors. It serves three purposes. First, it transfers control signals and transmit data from the modem chip to the DAA chip. Second, it transfers receive and status data from the DAA chip to the modem chip. Finally, it provides power from the modem chip to the DAA chip while the modem is in the on-hook condition. The signaling on this interface is intended for communication between the modem and the DAA chips and cannot be used for any other purpose. It is important to keep the length of the ISOcap™ path as short and direct as possible. The layout guidelines for the pins and components associated with this interface are described in "4.4. Layout Guidelines" on page 49 and must be carefully followed to ensure proper operation and avoid unwanted emissions.

2.4. Low-Power Modes

2.4.1. Power-Down Mode

The Power-Down mode is a lower power state than sleep mode. It is entered immediately upon writing U65 [13] (PDN) = 1. Once in the Power-Down mode, the modem requires a hardware reset via the $\overline{\text{RESET}}$ pin to become active again.

2.4.2. Wake-on-Ring Mode

The ISOmodem can be set to enter a low-power wake-on-ring mode when not connected. Wake-on-ring mode is entered using the command AT&Z. The ISOmodem returns to the active mode when one of the following happens:

- There is a 1 to 0 transition on TXD in the UART mode
- There is a 1 to 0 transition on $\overline{\text{CS}}$ in the parallel mode
- There is a 1 to 0 transition on $\overline{\text{SSS}}$ in the SPI mode
- An incoming ring is detected
- A parallel telephone is picked up
- Line polarity reversal

2.4.3. Sleep Mode

The ISOmodem can be set to enter a low-power sleep mode when not connected and after a period of inactivity determined by the S24 register.

The ISOmodem enters the sleep mode S24 seconds after the last DTE activity, after the transmit FIFO is empty, and after the last data are received from the remote modem. The ISOmodem returns to the active mode when one of the following happens:

- There is a 1 to 0 transition on TXD in the UART mode
- There is a 1 to 0 transition on $\overline{\text{CS}}$ in the parallel mode
- There is a 1 to 0 transition on $\overline{\text{SSS}}$ in the SPI mode
- An incoming ring is detected
- A parallel telephone is picked up
- Line polarity reversal

The delay range for S24 is 1 to 255 seconds. The default setting of S24 = 0 disables the sleep timer and keeps the modem in the normal power mode regardless of activity level.

2.5. SSI/Voice Mode (24-Pin TSSOP and 38-Pin QFN Only)

Voice mode is supported in the Si2439 and the Si2494. Table 25 lists the pin connections for the ISOmodem SSI interface. This interface enables Voice Mode operation. See "7. Handset, TAM, and Speakerphone Operation" on page 173 for additional information.

Table 25. SSI Interface Pin Connection

Signal	Pin Number (TSSOP-24)	Pin Number (QFN-38)
CLKOUT	3	3
$\overline{\text{FSYNC}}$	4	2
SDI	18	8
SDO	24	9
$\overline{\text{RESET}}$	12	16

The Si3000 is used in conjunction with the ISOmodem to transmit and receive 16-bit voice samples to and from telephone lines as shown in Figure 10.
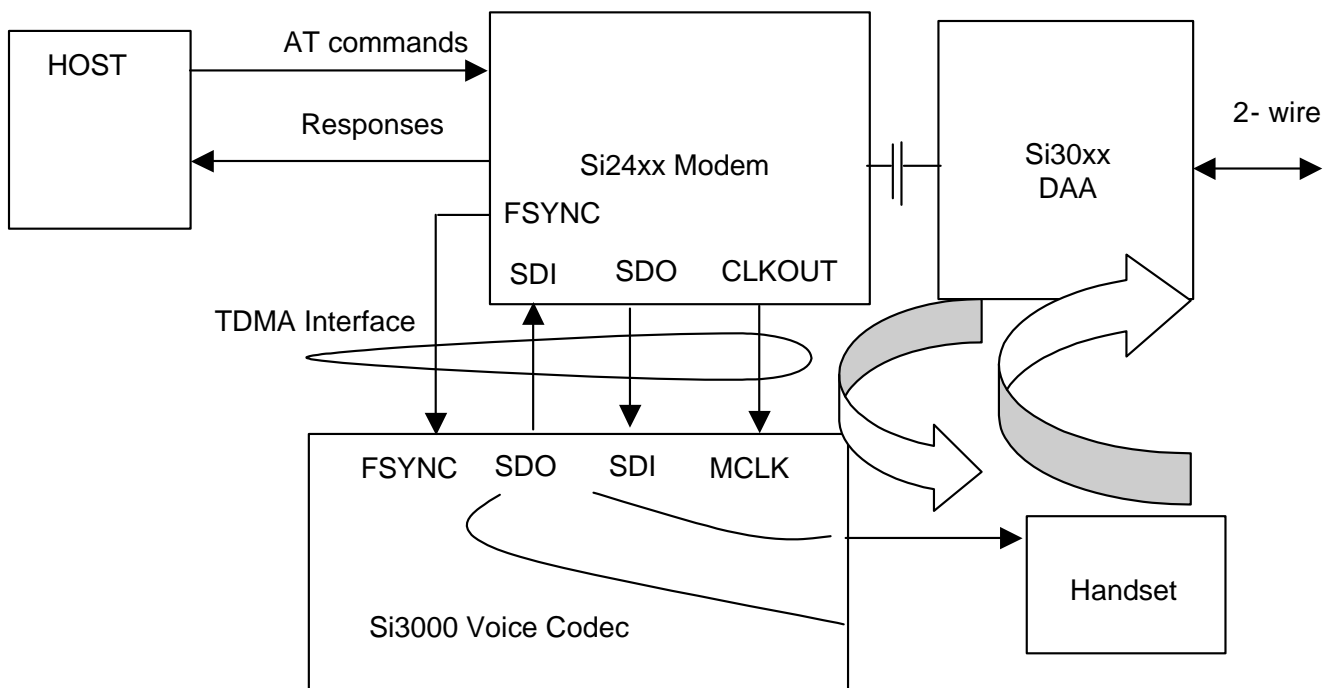
Figure 10. Voice Mode Block Diagram

2.6. EEPROM Interface (24-Pin TSSOP and 38-Pin QFN Only)

The 24-pin TSSOP and 38-pin QFN packages feature an optional three-wire interface (EESD, $\overline{\text{EECS}}$ and EECLK) that may be directly connected to SPI EEPROMs. An EEPROM may contain custom default settings, firmware upgrades, and/or user-defined AT command macros for use in custom AT commands or country codes. Firmware upgrades may also be automatically loaded into the ISOmodem using the BOOT format.

2.6.1. Supported EEPROM Types

The EEPROM must support SPI mode 3 with a 16-bit (8–64 kbit range) address. The EEPROM must be between 8192 and 65536 bits in size and support the commands given in Table 26. The EEPROM must also support 16-bit addressing regardless of size, allow a clock frequency of at least 1 MHz, assert its output on falling edges of EECLK and latch input data on rising edges of EECLK. All data are sent to and from the EEPROM with the LSB first. Required EEPROM command format and signal timing are shown in Tables 26 to 28. A typical EEPROM-access timing diagram is shown on Figure 11. Such EEPROMs are available from several different manufacturers, for example:

- Microchip: 25LC080..25LC640
- Atmel: AT25080..AT25640

Table 26. EEPROM Commands

Instruction Name	Instruction Format	Description
READ	0000 0011	Read data from memory at address
WRITE	0000 0010	Write data to memory array beginning at address
WRDI	0000 0100	Clear write enable bit (disable write operation)
RDSR	0000 0101	Read status register
WRSR	0000 0001	Write status register
WREN	0000 0110	Set write enable bit (enable write operations)

Table 27. EEPROM Status Register (Any Other Bits are Unused)

7	6	5	4	3	2	1	0
—	—	—	—	—	—	WEL	WIP

WEL = write enable latch

WIP = write in progress

Table 28. EEPROM Timing

Parameter	Symbol	Min.	Typ.	Max.	Unit
EECLK period	ECLK	1.0	—	—	µs
EESD input setup time	EISU	100	—	—	ns
EESD input hold time	EIH	100	—	—	ns
EESD output setup time*	EOSU	500	—	—	ns
EESD output hold time*	EOH	500	—	—	ns
$\overline{\text{EECS}}$ asserted to EECLK positive edge	ECSS	500	—	—	ns

Table 28. EEPROM Timing

Parameter	Symbol	Min.	Typ.	Max.	Unit
EESD tristated before last falling EECLK edge during read cycle. Last positive half of EECLK cycle is extended to provide both 500 ns minimum EOH and 100 ns EESD before EECLK falling edge.	EOZ	100	—	—	ns
$\overline{\text{EECS}}$ disable time between accesses	ECSW	500	—	—	ns
$\overline{\text{EECS}}$ asserted after final EECLK edge	ECSH	1	—	—	µs
*Note: EESD output at negative EECLK edge					
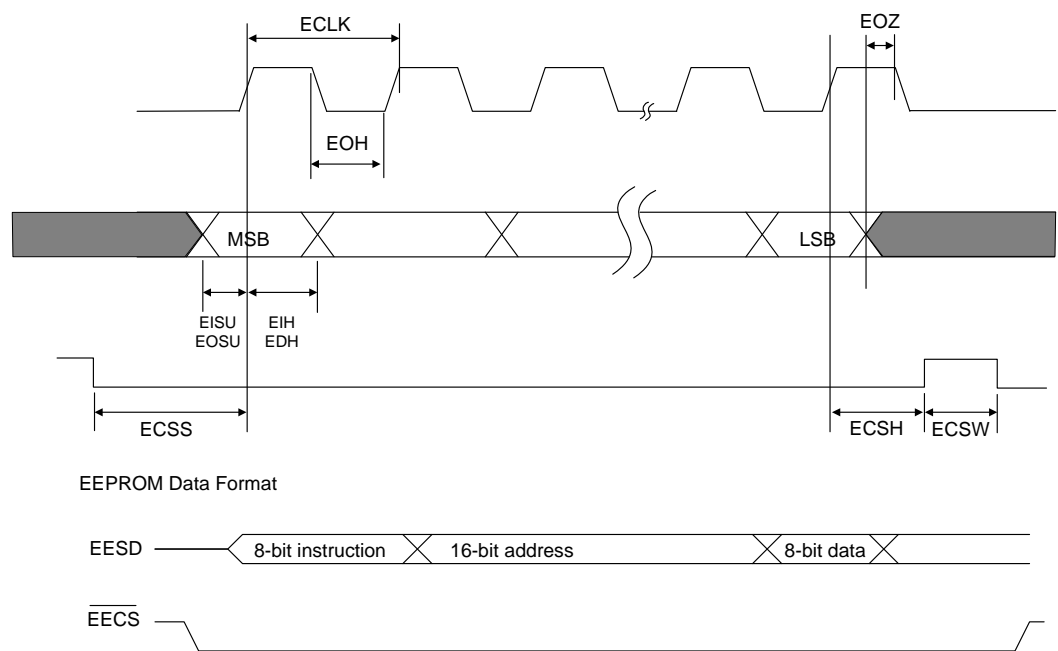
Figure 11. EEPROM Serial I/O Timing

2.6.2. Three-Wire SPI Interface to EEPROM

To enable the 3-wire SPI interface to EEPROM on the 24-pin TSSOP package, appropriate pins must be reset strapped according to Table 6 on page 14, or Table 8 on page 15, depending on the interface selected. The EEPROM option is not available on the 24-pin TSSOP package if the parallel host interface is selected.

Figure 12 shows the connection diagram for the 3-wire SPI interface to EEPROM. A four-wire EEPROM (with separate serial input and output data wires) may also be used with the input and output pins connected to EESD, if its SO output is tristated on the last falling edge of EECLK during a read cycle.
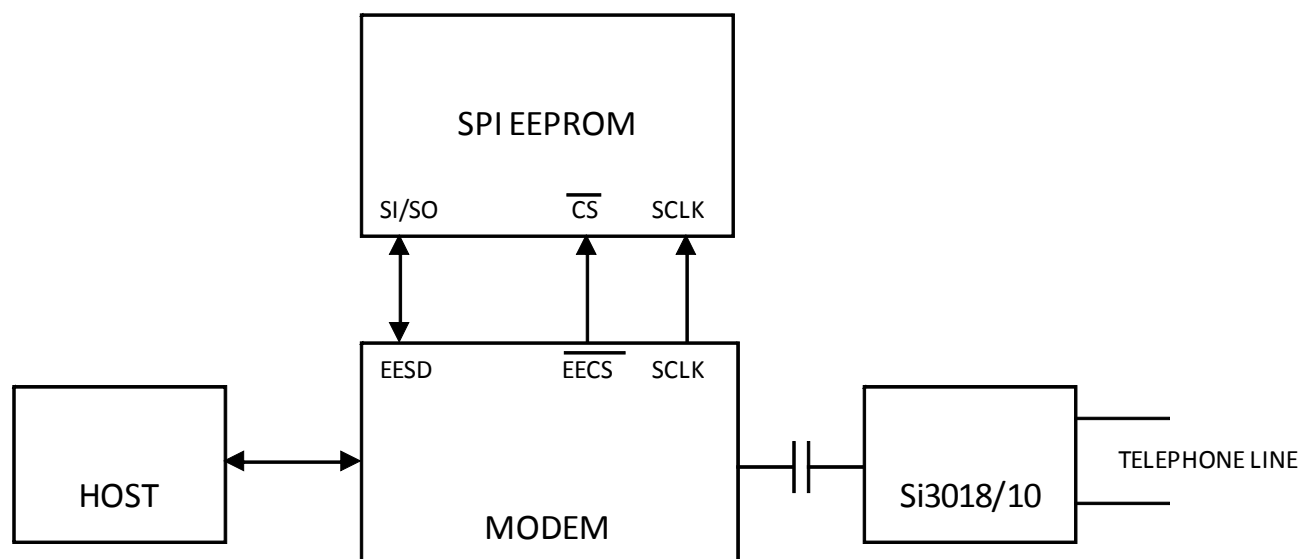
Figure 12. Three-Wire EEPROM Connection Diagram

2.6.3. Detailed EEPROM Examples

Upon powerup, if the option is selected, the ISOmodem attempts to detect an EEPROM. The modem looks for a carriage return in the first 10 memory locations. If none is found, the modem assumes the EEPROM is not programmed and stops reading it. If a programmed EEPROM is detected, customer defaults that are programmed into the EEPROM between the optional heading "BOOT" and the "<CR><CR>" delimiter are executed immediately, and AT command macros are loaded into the ISOmodem RAM. The memory that may be allocated to the <commands> portion of the EEPROM is limited to 1000 bytes. Three <CR> must be the last three entries in the EEPROM.

EEPROM Data are stored and read in hexadecimal ASCII format in eight address blocks beginning at a specified hexadecimal address. For example, the AT:M0000,y0,y1,y2,y3,y4,y5,y6,y7 command writes the hexadecimal values y0…y7 at addresses from 0 to 7, respectively. The AT:E0000 command reads the hexadecimal values y0…y7 from addresses 0 to 7, respectively.

The following sections give specific examples of EEPROM usage for command macros, firmware upgrades, boot commands, etc.

2.6.4. Boot Commands (Custom Defaults)

Commands to be executed upon boot-up are stored between the heading BOOT and the first <CR><CR> delimiter. The boot command has the following format:

```
BOOT<CR>
<commands><CR>
<commands><CR>
<CR>
```

The commands end with a <CR>, which, in combination with the final<CR>, provides the <CR><CR> delimiter. Boot commands must be the first entry in the EEPROM and are used to set the modem up with custom defaults, such as settings for specific countries, auto answer, or other special settings upon power up or after a hardware or software reset.

This saves the host processor from reloading special configuration strings at power up or after a reset, and allows the modem to be customized by programming the EEPROM or by substituting preprogrammed EEPROMs. If the BOOT command is the final entry in the EEPROM, it must end with an additional <CR> to provide the <CR><CR><CR> delimiter indicating the end of the EEPROM.

2.6.5. AT Command Macros (Customized AT Commands)

Macros allow the creation of single custom AT commands that execute combinations of default AT commands including special register configurations. AT command macros have the following format:

```
<command name><CR>
```

```
<commands><CR>
```

```
<commands><CR>
```

```
<CR>
```

Each AT Command Macro ends with a <CR><CR>. The final entry in the EEPROM ends with an additional <CR> to provide the <CR><CR><CR> delimiter indicating the end of the EEPROM. AT command macros can have a name consisting of any string of characters but must be the only command on a line.

2.6.6. Firmware Upgrades

Firmware upgrades ("patches") are typically executed upon boot-up and stored between the heading, BOOT, and the first <CR><CR> delimiter. A firmware upgrade has the format: BOOT<firmware upgrade><CR>. The firmware upgrade ends with a <CR>, which, in combination with the final<CR>, provides the <CR><CR> delimiter, which marks the end of the EEPROM contents. A firmware upgrade can also be stored as an AT command macro in a system where using the firmware upgrade is optional. The following are examples of boot commands, AT command macros, and automatically-loaded firmware upgrades.

2.6.6.1. Boot Command Example

On power-up or reset, it is desired to set the UART rate to 115.2 kbps and limit the ISOmodem to V.34 and lower operation.

The AT commands required to do this manually are:

```
AT\T12<CR>
```

```
AT&H2<CR>
```

To implement this as a boot command, the commands are:

```
BOOT<CR>
```

```
AT\T12<CR>
```

```
AT&H2<CR>
```

```
<CR>
```

This must be written to the EEPROM as ASCII hexadecimal in eight address blocks. The actual AT commands to store this boot command in the EEPROM starting at address 0 are:

```
AT:M0000,42,4F,4F,54,0D,41,54,5C
```

```
AT:M0008,54,31,32,0D,41,54,26,48
```

```
AT:M0010,32,0D,0D,00,00,00
```

The value 0x41 corresponds to the display character A, 0x54 to T, 0x42 to B, 0x4F to O etc., and the value 0x0D, for carriage return corresponds to the decimal value, 13, stored in S-register 3 (S3). Table 30 shows the relationship between the decimal values, hexadecimal values, and display characters.

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2.6.6.2. AT Command Macro Example

This example creates the AT command macro ATN<CR> to configure the ISOmodem for operation in Norway.

The AT commands required to do this manually are:

```
AT:U2C,00B0,0080<CR>
AT:U67,000C,0010,0004<CR>
AT:U4D,001<CR>
```

To implement this as an AT command macro, the EEPROM contents should be:

```
N<CR>
AT:U2C,00B0,0080<CR>
AT:U67,000C,0010,0004<CR>
AT:U4D,001<CR>
<CR><CR>
```

This must be written to the EEPROM as ASCII hexadecimal in eight address blocks. The actual AT commands to store this boot command in the EEPROM starting at address 0 are:

```
AT:M0000,4E,0D,41,54,3A,55,32,43
AT:M0008,2C,30,30,42,30,0D,0D,30
AT:M0010,38,30,0D,41,54,3A,55,36
AT:M0018,37,2C,30,30,30,43,2C,30
AT:M0020,30,31,30,2C,30,30,30,34
AT:M0028,0D,41,54,3A,55,34,44,2C
AT:M0030,30,30,31,0D,0D,0D
```

With this macro installed in the EEPROM, the command ATN<CR> configures the modem for operation in Norway.

2.6.6.3. Autoloading Firmware Upgrade Example

This example stores a firmware upgrade in EEPROM that is automatically loaded into the modem after power-up or hardware/software reset if the EEPROM option is selected.

The AT commands required to load the firmware upgrade manually are:

```
AT*Y254:W0050,0000<CR>
AT:PF800.08D5
```

To implement this as a boot command macro, the commands are:

```
BOOT<CR>
AT*Y254:W0050,0000<CR>
AT:PF800.08D5
```

This must be written to the EEPROM as ASCII hexadecimal in eight address blocks. The actual AT commands to store this boot command in the EEPROM starting at address 0 are:

```
AT:M0000,42,4F,4F,54,0D,41,54,2A
AT:M0008,59,32,35,34,3A,57,30,30
AT:M0010,35,30,2C,30,30,30,30,0D
AT:M0018,41,54,3A,50,46,34,30,30
AT:M0020,2C,30,38,44,35,0D,0D,0D
```

This firmware upgrade (patch) is only an example meant to illustrate the procedure for loading a patch into the EEPROM. Loading this code into a ISOmodem causes undesirable behavior.

2.6.6.4. Combination Example

This example shows boot commands and custom AT commands stored in the same EEPROM.

Table 29. Combination Example

Command	Function
BOOT<CR> <commands><CR> <commands><CR>	Start of EEPROM contents
<CR> <Custom AT Command Name 1><CR> <commands><CR> <commands><CR>	End of BOOT string Start of Custom AT Command 1
<CR> <Custom AT Command Name 2><CR> <commands><CR> <commands><CR>	End of Custom AT Command 1 Start of Custom AT Command 2
<CR> <Custom AT Command Name 3><CR> <commands><CR> <commands><CR>	End of Custom AT Command 2 Start of Custom AT Command 3
<CR>	End of Custom AT Command 3
<CR>	End of EEPROM Contents

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Table 30. ASCII Chart

dec	hex	Display	dec	hex	Display	dec	hex	Display	dec	hex	Display
0	00	<NUL>	32	20	<space>	64	40	@	96	60	`
1	01	<SOH>	33	21	!	65	41	A	97	61	a
2	02	<STX>	34	22	"	66	42	B	98	62	b
3	03	<ETX>	35	23	#	67	43	C	99	63	c
4	04	<EOT>	36	24	$	68	44	D	100	64	d
5	05	<ENQ>	37	25	%	69	45	E	101	65	e
6	06	<ACK>	38	26	&	70	46	F	102	66	f
7	07	<BEL>	39	27	'	71	47	G	103	67	g
8	08	<BS>	40	28	(	72	48	H	104	68	h
9	09	<HT>	41	29	)	73	49	I	105	69	i
10	0A	<LF>	42	2A	*	74	4A	J	106	6A	j
11	0B	<VT>	43	2B	+	75	4B	K	107	6B	k
12	0C	<FF>	44	2C	,	76	4C	L	108	6C	l
13	0D	<CR>	45	2D	-	77	4D	M	109	6D	m
14	0E	<SO>	46	2E	.	78	4E	N	110	6E	n
15	0F	<SI>	47	2F	/	79	4F	O	111	6F	o
16	10	<DLE>	48	30	0	80	50	P	112	70	p
17	11	<DC1>	49	31	1	81	51	Q	113	71	q
18	12	<DC2>	50	32	2	82	52	R	114	72	r
19	13	<DC3>	51	33	3	83	53	S	115	73	s
20	14	<DC4>	52	34	4	84	54	T	116	74	t
21	15	<NAK>	53	35	5	85	55	U	117	75	u
22	16	<SYN>	54	36	6	86	56	V	118	76	v
23	17	<ETB>	55	37	7	87	57	W	119	77	w
24	18	<CAN>	56	38	8	88	58	X	120	78	x
25	19	<EM>	57	39	9	89	59	Y	121	79	y
26	1A	<SUB>	58	3A	:	90	5A	Z	122	7A	z
27	1B	<ESC>	59	3B	;	91	5B	[	123	7B	{
28	1C	<FS>	60	3C	<	92	5C	\	124	7C		
29	1D	<GS>	61	3D	=	93	5D	]	125	7D	}
30	1E	<RS>	62	3E	>	94	5E	^	126	7E	~
31	1F	<US>	63	3F	?	95	5F	_	127	7F	

3. DAA (Line-Side) Device

The Si3018/10 DAA or line-side device, contains an ADC, a DAC, control circuitry, and an isolation capacitor interface. The Si3018/10 and surrounding circuitry provide all functionality for telephone line interface requirement compliance, including a full-wave rectifier bridge, hookswitch, dc termination, ac termination, ring detection, loop voltage and current monitoring, and call-progress monitoring. The Si3018/10 external circuitry is largely responsible for EMI, EMC, safety, and surge performance.

3.1. Hookswitch and DC Termination

The DAA has programmable settings for the dc impedance, current limiting, minimum operational loop current, and Tip-to-Ring voltage. The dc impedance of the DAA is normally represented by a 50 Ω slope as shown in Figure 13, but can be changed to an 800 Ω slope by setting the DCR bit. This higher dc termination presents a higher resistance to the line as the loop current increases.
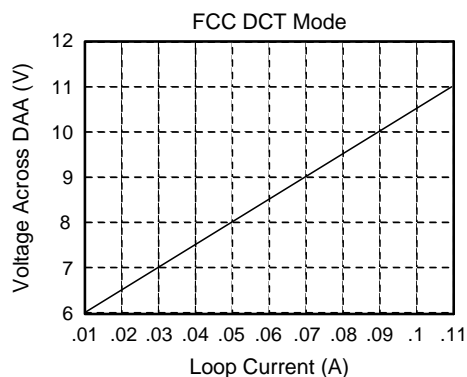
Figure 13. FCC Mode I/V Characteristics
DCV[1:0] = 11, MINI[1:0] = 00

For applications requiring current limiting per the legacy TBR21 standard, the ILIM bit may be set to select this mode. In this mode, the dc I/V curve is changed to a 2000 Ω slope above 40 mA, as shown in Figure 14. This allows the DAA to operate with a 50 V, 230 Ω feed, which results in the highest current possible in the old TBR21 standard.
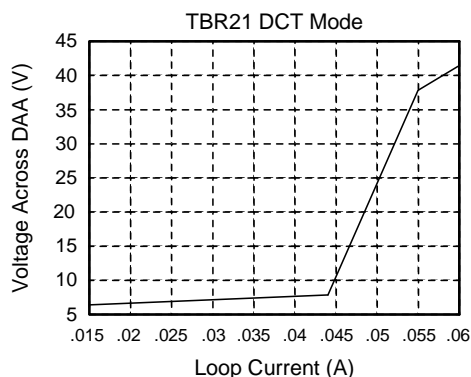
Figure 14. TBR21 (Legacy) Mode I/V Characteristics
DCV[1:0] = 11, MINI[1:0] = 00

The MINI[1:0] bits select the minimum operational loop current for the DAA, and the DCV[1:0] bits adjust the DCT pin voltage, which affects the Tip-to-Ring voltage of the DAA. These bits allow important trade-offs to be made between signal headroom and minimum operational loop current. Increasing the Tip-Ring voltage increases signal headroom, whereas decreasing the voltage allows compliance to PTT standards in low-voltage countries, such as Japan or Malaysia. Increasing the minimum operational loop current above 10 mA also increases signal headroom and prevents degradation of the signal level in low-voltage countries.

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3.2. AC Termination

The ISOmodem has four ac termination impedances when used with the Si3018 line-side device, selected by the ACT bits in Register U63. The four available settings for the Si3018 are listed in Table 31. If an ACT[3:0] setting other than the four listed in Table 31 is selected, the ac termination is forced to 600 Ω (ACT[3:0] = 0000).

Table 31. AC Termination Settings for the Si3018 Line-Side Device

ACT[3:0]	AC Termination
0000	600 Ω
0011	220 Ω + (820 Ω || 120 nF) and 220 Ω + (820 Ω || 115 nF)
0100	370 Ω + (620 Ω || 310 nF)
1111	Global complex impedance

3.3. Ringer Impedance and Threshold

The ring detector in many DAAs is ac coupled to the line with a large 1 µF, 250 V decoupling capacitor. The ring detector on the ISOmodem is resistively coupled to the line. This produces a high ringer impedance to the line of approximately 20 MΩ. This meets the majority of country PTT specifications, including FCC and ETSI ES 203 021.

Several countries, including Poland, South Africa, and Slovenia, require a maximum ringer impedance that can be met with an internally synthesized impedance by setting the RZ bit (Register 67, bit 1).

Some countries specify different ringer thresholds. The RT bit (Register U67, bit 0) selects between two different ringer thresholds: 15 V ±10% and 21.5 V ±10%. These two settings satisfy ringer threshold requirements worldwide. The thresholds are set so that a ring signal is guaranteed to be detected above the maximum and not detected below the minimum.

3.4. Pulse Dialing and Spark Quenching

Pulse dialing is accomplished by going off- and on-hook at a certain cadence to generate make and break pulses. The nominal rate is ten pulses per second. Some countries have strict specifications for pulse fidelity that include make and break times, make resistance, and rise and fall times. In a traditional, solid-state dc holding circuit, there are many problems in meeting these requirements. The ISOmodem dc holding circuit actively controls the on-hook and off-hook transients to maintain pulse dialing fidelity.

Spark-quenching requirements in countries such as Italy, the Netherlands, South Africa and Australia deal with the on-hook transition during pulse dialing. These tests provide an inductive dc feed resulting in a large voltage spike. This spike is caused by the line inductance and sudden decrease in current through the loop when going on-hook. The traditional solution to the problem is to put a parallel resistive capacitor (RC) shunt across the hookswitch relay. However, the capacitor required is bulky (~1 µF, 250 V) and relatively costly. In the ISOmodem, the loop current can be controlled to achieve three distinct on-hook speeds to pass spark-quenching tests without additional BOM components. Through settings of two bits in two registers, OHS (Register U67, bit 6) and OHS2 (Register U62, bit 8), a delay between the time the OH bit is cleared and the time the DAA actually goes on-hook, can be created, which induces a slow ramp-down of the loop current.

3.5. Line Voltage and Loop Current Sensing

There are two methods for line voltage and loop current sensing. The first method is the legacy mode using U79 (LVCS) [4:0]. The legacy mode is intended for backward compatibility in applications originally designed for the previous generation ISOmodem. This mode is used in the intrusion detection algorithm implemented on the device.

The second method of measuring line voltage and loop current takes advantage of the improved resolution available on the Si3018 and Si3010 DAA chips. U63 (LCS) [15:8] represents the value of off-hook loop current as a non-polar binary number with 1.1 mA/bit resolution. Accuracy is not guaranteed if the loop current is less than the minimum required for normal DAA operation. U6C (LVS) [15:8] represents the value of on-hook and off-hook loop voltage as a signed, two's complement number with a resolution of 1 V/bit.

Bit 15 represents the polarity of the Tip-Ring voltage, and a reversal of this bit represents a Tip-Ring polarity reversal. LVS = 0x0000 if the Tip-Ring voltage is less than 3.0 V and, in the on-hook state, can be taken as "no line connected."

The ISOmodem reports the on-hook line voltage with the LVS bits in two's complement. LVS has a full scale of 87 V with an LSB of 1 V. The first code step (going from 0 to 1) is offset so that a 0 indicates a line voltage of less than 3 V. The accuracy of the LVS bits is ±10%. The user can read these bits directly through the LVS register. A typical transfer function is shown in Figure 15.

When the ISOmodem is off-hook, the LCS bits measure loop current in 1.1 mA/bit resolution. These bits enable the user to detect another phone going off-hook by monitoring the dc loop current. Line-current sensing is detailed in Figure 16 and Table 32.
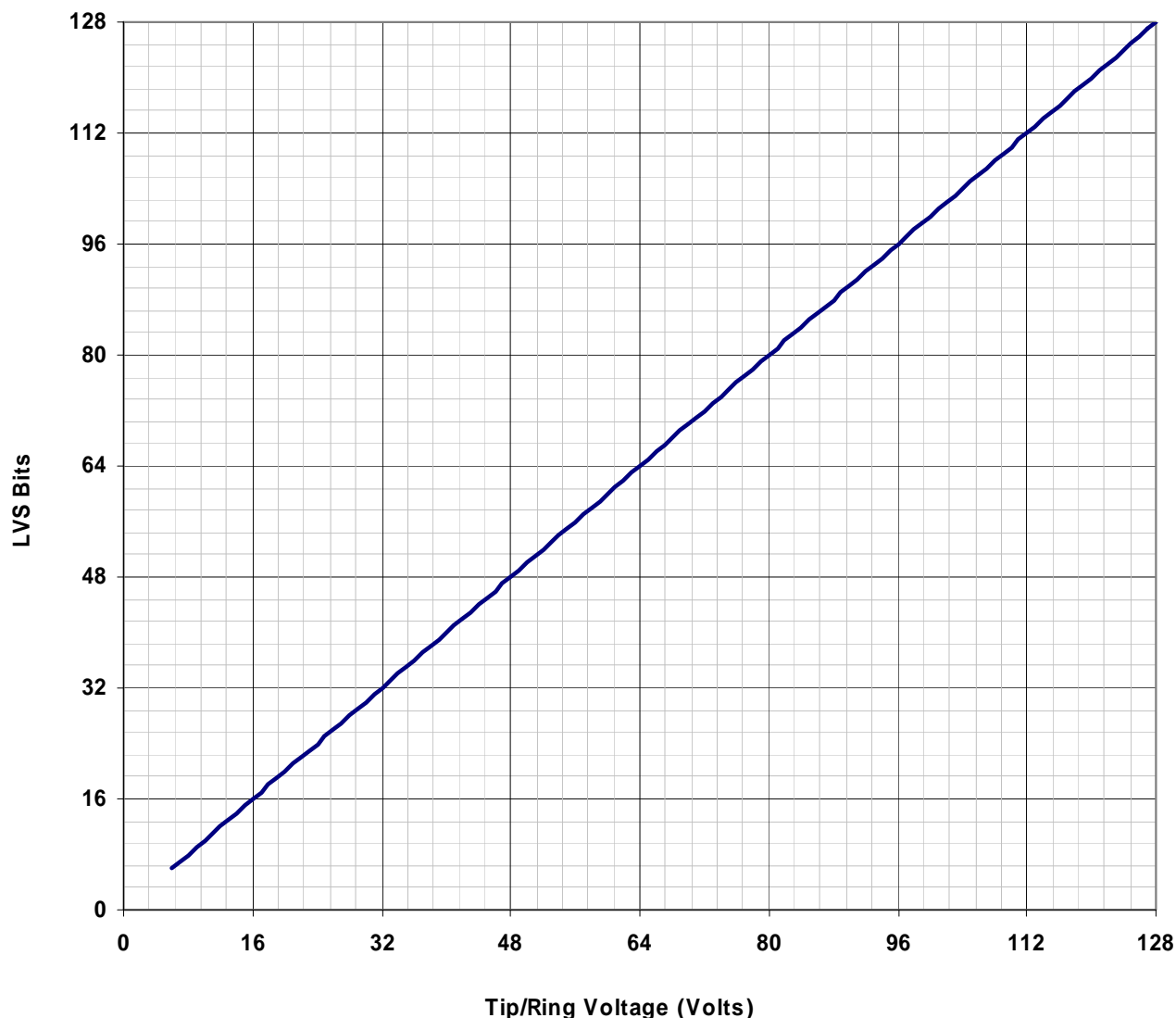
Figure 15. Typical Loop Voltage LVS Transfer Function
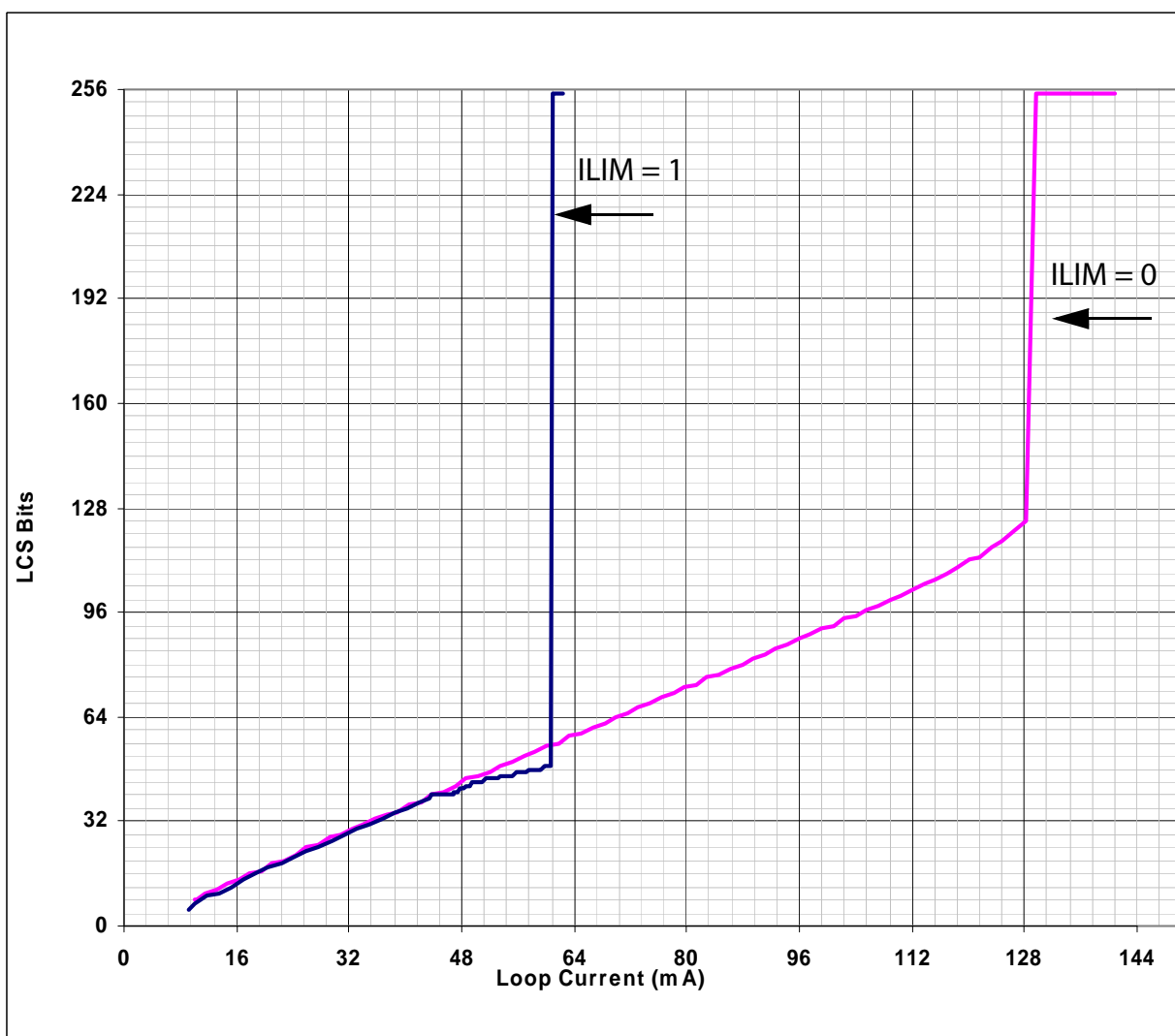
Figure 16. Typical Loop Current LCS Transfer Function

Table 32. Loop Current Transfer Function

LVCS[4:0]	Condition
00000	Insufficient line current for normal operation.
00001	Minimum line current for normal operation.
11111	Loop current overload. Overload is defined as 128 mA or more, except in TBR21, where overload is defined as 56 mA or more.

3.6. Legacy-Mode Line Voltage and Loop Current Measurement

The 5-bit LVCS register, U79 (LVCS) [4:0], reports line voltage measurements when on-hook and loop current measurements when off-hook.

Using the LVCS bits, the user can determine the following:

- When on-hook, detect if a line is connected.
- When on-hook, detect if a parallel phone is off-hook.
- When off-hook, detect if a parallel phone goes on or off-hook.
- Detect if enough loop current is available to operate.

3.7. Billing Tone Detection

Billing tones or metering pulses generated by the central office can cause connection difficulties in modems. The billing tone is typically a 12 kHz or 16 kHz signal and is sometimes used in Germany, Switzerland, and South Africa. Depending on line conditions, the billing tone may be large enough to cause major modem errors. The ISOmodem chipset can provide feedback when a billing tone occurs and when it ends.

Billing tone detection is enabled by setting the BTE bit (U68, bit 2). Billing tones less than 1.1 V_{PK} on the line are filtered out by the low-pass digital filter on the ISOmodem. The ROV bit (U68, bit 1) is set when a line signal is greater than 1.1 V_{PK}, indicating a receive overload condition. The BTD bit is set when a line signal (billing tone) is large enough to excessively reduce the line-derived power supply of the line-side device (Si3018/10). When the BTE bit is set, the dc termination is changed to an 800 Ω dc impedance. This ensures minimum line voltage levels even in the presence of billing tones.

The OVL bit should be polled following billing-tone detection. When the OVL bit returns to 0, indicating that the billing tone has passed, the BTE bit should be written to 0 to return the dc termination to its original state. It takes approximately 1 second to return to normal dc operating conditions. The BTD and ROV bits are sticky and must be written to 0 to be reset. After the BTE, ROV, and BTD bits are cleared, the BTE bit can be set to reenable billing-tone detection.

Certain line events, such as an off-hook event on a parallel phone or a polarity reversal, may trigger the ROV bit or the BTD bit, after which the billing-tone detector must be reset. Look for multiple events before qualifying whether billing tones are actually present.

Although the DAA remains off-hook during a billing-tone event, the received data from the line is corrupted (or a modem disconnect or retrain may occur) in the presence of large billing tones. To receive data in the presence of a billing tone, an external LC filter must be added. A modem manufacturer can provide this filter to users in the form of a dongle that connects on the phone line before the DAA. This keeps the manufacturer from having to include a costly LC filter internal to the modem when it may only be necessary to support a few countries or customers.

Alternatively, when a billing tone is detected, the host software may notify the user that a billing tone has occurred. This notification can be used to prompt the user to contact the telephone company to have the billing tones disabled or purchase an external LC filter.

4. Hardware Design Reference

This section describes hardware design requirements for optimum Si24xx ISOmodem chipset implementation. There are three important considerations for any hardware design. First, the reference design and components listed in the associated bill of materials should be followed exactly. These designs reflect field experience with millions of deployed units throughout the world and are optimized for cost and performance. *Any* deviation from the reference design schematic and components will likely have an adverse affect on performance. Second, circuit board layouts must follow "4.4. Layout Guidelines" rigorously. Deviations from these layout techniques will likely affect modem performance and regulatory compliance. Finally, all reference designs use a standard component numbering scheme. This simplifies documentation references and communication with the Silicon Laboratories technical support team. It is strongly recommended that these same component reference designators be used in all ISOmodem designs.

4.1. Component Functions

In spite of the significant internal complexity of the chip, the external support circuitry is very simple. The following section describes the modem's functions in detail.

4.1.1. Power Supply and Bias Circuitry

Power supply bypassing is important for the proper operation of the ISOmodem, suppression of unwanted radiation, and prevention of interfering signals and noise from being coupled into the modem via the power supply. C50 and C52 provide filtering of the 3.3 V system power and must be located as close to the ISOmodem chip as possible to minimize lead lengths. The best practice is to use surface-mount components connected between a power plane and a ground plane. This technique minimizes the inductive effects of component leads and PCB traces and provides bypassing over the widest possible frequency range, and minimizes loop areas that can radiate radio frequency energy.

Two bias voltages used inside the modem chip require external bypassing and/or clamping. VDA (pin 7) is bypassed by C51. VDB (pin 19) is bypassed by C53. R12 and R13 are optional resistors that can, in some cases, reduce radiated emissions due to signals associated with the isolation capacitors. These components must be located as close to the ISOmodem chip as possible to minimize lead lengths.

The Si3018/10 is powered by a small current passed across the ISOcap in the on-hook mode and by the loop current in the off-hook mode. Since there is no system ground reference for the line-side chip due to isolation requirements, a virtual ground, IGND, is used as a reference point for the Si3018/10. Several bias voltages and signal reference points used inside the DAA chip require external bypassing, filtering, and/or clamping. VREG2 (pin 10) is bypassed by C6. VREG (pin 7) is bypassed by C5. These components must be located as close to the Si3018/10 chip as possible to minimize lead lengths.

4.1.2. Hookswitch and DC Termination

The hookswitch and dc termination circuitry are shown in Figure 18 on page 46. Q1, Q2, Q3, Q4, R5. R6, R7, R8, R15, R16, R17, R19, and R24 perform the hookswitch function. The on-hook/off-hook condition of the modem is controlled by Si3018/10 pins 13 (QB) and 1 (QE).

4.1.3. Clocks

The crystal oscillator circuit has three operating frequencies/modes that are selected by using the correct clock source and by installing the correct pulldown resistors on the modem in order to signal the ISOmodem which mode to operate. Selecting among these modes of operation is described in "2.1. Resetting the Device" on page 11.

One mode requires a 4.9152 MHz fundamental mode parallel-resonant crystal. Typical crystals require a 20 pF load capacitance. This load is calculated as the series combination of the capacitance from each crystal terminal to ground, including parasitic capacitance due to package pins and PCB traces. The parasitic capacitance is estimated as 7 pF per terminal. This, in combination with the 33 pF capacitor, provides 40 pF per terminal, which, in series, yields the proper 20 pF load for the crystal.

Instead of using a 4.9152 MHz crystal, a signal at 4.9152 MHz can be applied to the XTALI pin. In such a case, the crystal loading caps should not be used.

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The second mode is a 32.768 kHz fundamental mode parallel-resonant crystal. Typical crystals require a 12.5 pF load capacitance. This load is calculated as the series combination of the capacitance from each crystal terminal to ground, including parasitic capacitance due to package pins and PCB traces. The parasitic capacitance is estimated as 7 pF per terminal. This, in combination with the 18 pF capacitors, provides 25 pF per terminal, which, in series, yields the proper 12.5 pF load for the crystal.

Instead of a using a 32.768 kHz crystal, a signal at 32.768 kHz can be applied to the XTALI pin. In such a case, the crystal loading caps should not be used.

The third mode is to use a 27 MHz clock signal. A crystal cannot be used for this mode, and the signal must be applied to the XTALI pin.

Frequency stability and accuracy are critically important to the performance of the modem. ITU-T specifications require less than 200 ppm difference between the carrier frequencies of two modems. This value, split between the two modems, requires the oscillator frequency of each modem to be accurate and stable over all operating conditions within ±100 ppm. This tolerance includes the initial accuracy of the crystal, the frequency drift over the temperature range that the crystal is expected to experience, and the five-year aging of the crystal. Other factors affecting the oscillator frequency include the tolerance and temperature drift of the load capacitor values. For optimal V.92 performance, it is recommended to increase the oscillator stability to ±25 ppm.

For all the above three modes of operation, the CLKIN/XTALI pin (Pin 1) can accept a 3.3 V external clock signal meeting the accuracy and stability requirements described above.

The CLKOUT/A0 pin outputs a signal derived from the 4.9152 MHz clock. If the frequency of the output is controlled via register U6E (CK1) using the Si2404 or Si2415, this signal is programmable from 2.64 MHz to 40.96 MHz. If using the Si2434 or Si2457, this signal is programmable from 3.17 MHz to 49.152 MHz. There are two special cases for the value of R1: R1 = 00000, CLKOUT is disabled, and R1 = 11111 (default), CLKOUT = 2.048 MHz.

On older parts, the CLKOUT pulse starts immediately after RESET goes high, but, on the most recent versions (those including SPI and 32 kHz operation), there is a small delay after RESET goes high. The delay is of approximately 200 µs when using 4.91592 MHz or 27 MHz and approximately 8 ms when using a 32 kHz clock.

4.1.4. Ringer Network

R7 and R8 comprise the ringer network. These components determine the modem's on-hook impedance at Tip and Ring. These components are selected to present a high impedance to the line, and care must be taken to ensure the circuit board area around these components is clean and free of contaminants, such as solder flux and solder flakes. Leakage on RNG1 (Si3018/10 pin 8) and RNG2 (Si3018/10 pin 9) can impair modem performance. R7 and R8 are also used by the modem to monitor the line voltage.

4.1.5. Optional Billing-Tone Filter

To operate without degradation during billing tones in Germany, Switzerland, and South Africa, an external LC notch filter is required. (The Si3018/10 will remain off-hook during a billing tone event, but modem data may be lost, or a modem disconnect or retrain may occur, in the presence of large billing-tone signals.) The notch filter design requires two notches: one at 12 kHz and one at 16 kHz. Because these components are expensive and few countries require billing-tone support, this filter is typically placed in an external dongle or added as a population option. Figure 17 shows an example billing tone filter. L3 must carry the entire loop current. The series resistance of the inductors is important to achieve a narrow and deep notch. This design has more than 25 dB of attenuation at 12 kHz and 16 kHz. The billing tone filter degrades the ac termination and return loss slightly, but the global complex ac termination passes worldwide return-loss specifications with and without the billing tone filter by at least 3 dB.

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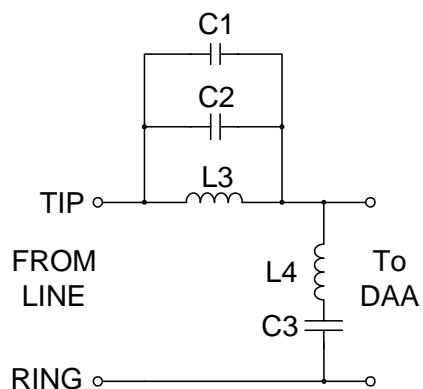
Figure 17. Billing-Tone Filter

Table 33. Optional Billing Tone Filters Component Values

Symbol	Value
C1,C2	0.027 µF, 50 V, ±10%
C3	0.01 µF, 250 V, ±10%
L3	3.3 mH, >120 mA, <10 Ω, ±10% Coilcraft RFB0810-332 or equivalent
L4	10 mH, >40 mA, <10 Ω, ±10% Coilcraft RFB0810-103 or equivalent

Figure 18. Si3018/10 Component Functions

4.2. Schematic

Figure 19. Si3018/10 Schematic
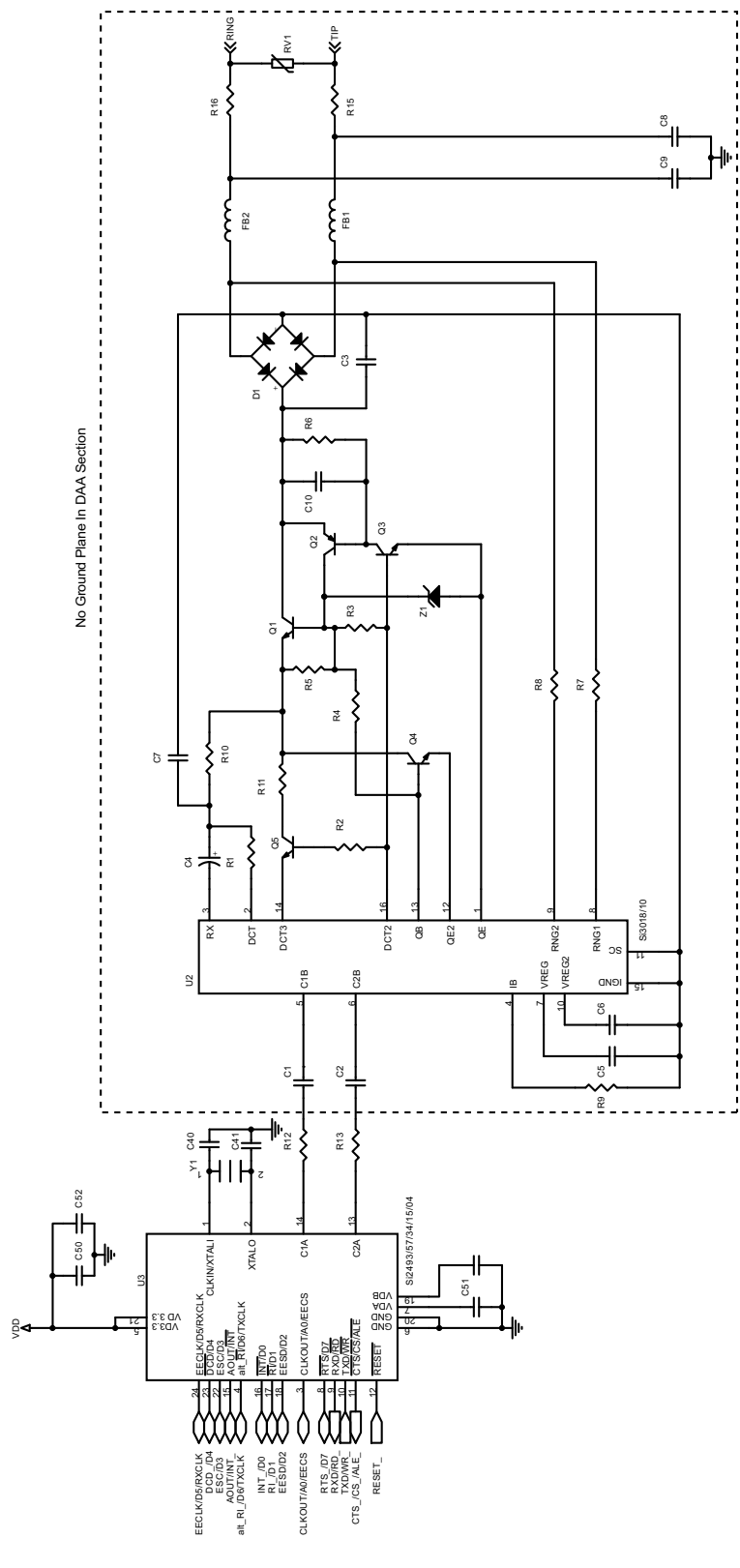
Note: See Section "10.4.2. Safety" for information regarding the use of a fuse or PTC resistor.

4.3. Bill of Materials

Component	Value	Supplier(s)
C1, C2	33 pF, Y2, X7R, ±20%	Panasonic, Murata, Vishay, Holy Stone
C3	10 nF, 250 V, X7R, ±20%	Venkel, SMEC
C4	1.0 µF, 50 V, Elec/Tant, ±20%	Panasonic
C5, C6, C50, C52[1]	0.1 µF, 16 V, X7R, ±20%	Venkel, SMEC
C7	2.7 nF, 50 V, X7R, ±20%	Venkel, SMEC
C8, C9	680 pF, Y2, X7R, ±10%	Panasonic, Murata, Vishay, Holy Stone
C10	0.01 µF, 16 V, X7R, ±20%	Venkel, SMEC
C40	32.768 kHz, 18 pF, 16 V, NPO, ±5%	Venkel, SMEC
C41	4.9152 MHz, 27 MHz, 33 pF, 16 V, NPO, ±5%	
C51, C53[1]	0.22 µF, 16 V, X7R, ±20%	Venkel, SMEC
D1, D2[2]	Dual Diode, 225 mA, 300 V, MMBT3004S	Diodes Inc.
FB1, FB2	Ferrite Bead, BLM18AG601SN1	Murata
Q1, Q3	NPN, 300 V, MMBTA42	Diodes Inc., Fairchild
Q2	PNP, 300 V, MMBTA92	Diodes Inc., Fairchild
Q4, Q5	NPN, 80 V, 330 mW, MMBTA06	Diodes Inc., Fairchild
RV1	Sidactor, 275 V, 100 A	Teccor, Protek, ST Micro
R1	1.07 kΩ, 1/2 W, 1%	Venkel, SMEC, Panasonic
R2	150 Ω, 1/16 W, 5%	Venkel, SMEC, Panasonic
R3	3.65 kΩ, 1/2 W, 1%	Venkel, SMEC, Panasonic
R4	2.49 kΩ, 1/2 W, 1%	Venkel, SMEC, Panasonic
R5, R6	100 kΩ, 1/16 W, 5%	Venkel, SMEC, Panasonic
R7, R8	20 MΩ, 1/16 W, 5%	Venkel, SMEC, Panasonic
R9	1 MΩ, 1/16 W, 1%	Venkel, SMEC, Panasonic
R10	536 Ω, 1/4 W, 1%	Venkel, SMEC, Panasonic
R11	73.2 Ω, 1/2 W, 1%	Venkel, SMEC, Panasonic
R12, R13	56 Ω, 1/16 W, 1%	Venkel, SMEC, Panasonic
R15, R16[3]	0 Ω, 1/16 W	Venkel, SMEC, Panasonic
U1	Si24xx ISOmodem	Silicon Labs
U2	Si3018	Silicon Labs
Y1[4]	32.768 kHz, 12 pF, 100 ppm, 50 kΩ max ESR	ECS Inc., Siward, Abracon
	4.9152 MHz, 20 pF, 100 ppm, 150 Ω ESR 27 MHz (from external clock)	
Z1	Zener Diode, 43 V, 1/2 W, BZT84C43	On Semi

Notes:
1. C52 and C53 should not be populated with the Si2493 16-pin package option.
2. Several diode bridge configurations are acceptable. For example, a single DF04S or four 1N4004 diodes may be used.
3. Murata BLM18AG601SN1 may be substituted for R15–R16 (0 Ω) to decrease emissions.
4. To ensure compliance with ITU specifications, frequency tolerance must be less than 100 ppm including initial accuracy, 5-year aging, 0 to 70 °C, and capacitive loading. For optimal V.92 PCM upstream performance, the recommended crystal accuracy is ±25 ppm.

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4.4. Layout Guidelines

The key to a good layout is proper placement of the components. It is best to copy the placement shown in Figure 20. Alternatively, follow the following steps, referring to the schematics and Figure 21. It is strongly recommended to complete the checklist in Table 34 on page 51 while reviewing the final layout.

1. All traces, open pad sites, and vias connected to the following components are considered to be in the DAA section and must be physically separated from non-DAA circuits by 5 mm to achieve the best possible surge performance: R1, R2, R3, R4, R5, R6, R7, R8, R9, R10, R11, R15, R16, U2, Z1, D1, FB1, FB2, RJ11, Q1, Q2, Q3, Q4, Q5, C3, C4, C5, C6, C7, C8, C9, C10, RV1, C1 pin 2 only, C2 pin 2 only, C8 pin 2 only, and C9 pin 2 only.

2. The isolation capacitors, C1, C2, C8 and C9, are the only components permitted to straddle between the DAA section and non-DAA section components and traces. This means that for each of these capacitors, one of the terminals is on the DAA side, and the other is not. Maximize the spacing between the terminals (between pin 1 and pin 2) of each of these capacitors.

3. Place and group the following components: U1, U2, R12*, R13*, C1, C2.
   *Note: Do *not* use ferrite beads in place of R12 and R13.

   a.U1 and U2 are placed so that the right side of U1 faces the left side of U2.

   b.C1 and C2 are placed directly between U1 and U2.

   c.Keep R12 and R13 close to U1.

   d.Place U1, U2, C1, and C2 so that the minimum creepage distance for the target application is met.

   e.Place C1 and C2 so that traces connected to U2 pin 5 (C1B) and U2 pin 6 (C2B) are physically separated from traces connected to:

      i.C8, R15, FB1

      ii.C9, R16, FB2

      iii.U2 pin 8, R7

      iv.U2 pin 9, R9

4. Place and group the following components around U2: C4, R9, C7, R2, C5, C6, R7, R8. These components should form the critical "inner circle" of components around U2.

   a.Place C4 close to U2 pin 3. This is best achieved by placing C4 northwest of U2.

   b.Place R9 close to U2 pin 4. This is best achieved by placing R9 horizontally, directly to the north of U2.

   c.Place C7 close to U2 pin 15. This is best achieved by placing C7 next to R9.

   d.Place R2 next to U2 pin 16. This is best achieved by placing R2 northeast of U2.

   e.Place C6 close to U2 pin 10. This is best achieved by placing C6 southeast of U2.

   f.Place R7 and R8 close to U2. This is best achieved by placing these components to the south of U2.

   g.Place C5 close to U2 pin 7. This is best achieved by placing C5 southwest of U2.

5. Place Q5 next to R2 so that the base of Q5 can be connected to R2 directly.

6. Place Q4 so that the base of Q4 can be routed to pin 13 of U2 easily and the emitter of Q4 can be routed to U2 pin 12 easily. Route these two traces next to each other so that the loop area formed by these two traces is minimized.

7. Place and group the following components around the RJ11 jack: FB1, FB2, RV1, R15, R16, C8, and C9.

   a.Use 20-mil-wide traces on this grouping to minimize impedance.

   b.Place C8 and C9 close to the RJ11 jack, recognizing that a GND trace will be routed between C8 and C9 back to the Si24xx GND pin through a 20-mil-wide trace. The GND trace from C8 and C9 must be isolated from the rest of the Si3018/10 traces.

   c.The trace from C8 to GND and the trace from C9 to GND must be short and of equal lengths.

8. After the previous step, there should be some space between the grouping around U2 and the grouping of components around the RJ11 jack. Place the rest of the components in this area, given the following guidelines:

    a. Space U2, Q4, Q5, R1, R3, R4, R10 and R11 away from each other for best thermal performance.

    b. The tightest layout can be achieved by grouping R6, C10, Q2, R3, R5, and Q1.

    c. Place C3 next to D1.

    d. Make the size of the Q1, Q3, Q4, and Q5 collector pads each sufficiently large for the transistor to safely dissipate 0.5 W under worst case conditions. See the transistor data sheet for thermal resistance and maximum operating temperature information. Implement collector pads on both the component and solder side, and use vias between them to improve heat transfer for best performance. When ambient conditions are a moderate 50 deg or less, use 0.05 square inches of copper at the collectors of Q1, Q3, Q4, Q5. Both sides of the PCB can be used to double the available area.

9. U2, IGND, is the return path for many of the discrete components and requires special mention:

    a. Traces associated with IGND should be 20 mils wide.

    b. U2's IGND should not be a large ground plane and should only occupy the space under U2. Beyond this area, use traces and avoid getting close to the components on the other side of the diode bridge.

    c. C5, C6, C7 IGND return path should be direct.

10. The traces from R7 to FB1 and from R8 to FB2 should be well matched. This can be achieved by routing these traces next to each other as much as possible. Ensure that these traces are not routed close to the traces connected to C1 or C2.

11. Minimize all traces associated with Y1, C40, and C41.

12. Decoupling capacitors (0.22 µF and 0.1 µF capacitors connected to V_{DA}, V_{DB}, V_{DD}) must be placed next to those pins. Traces of these decoupling capacitors back to the Si24xx GND pin should be direct and short.
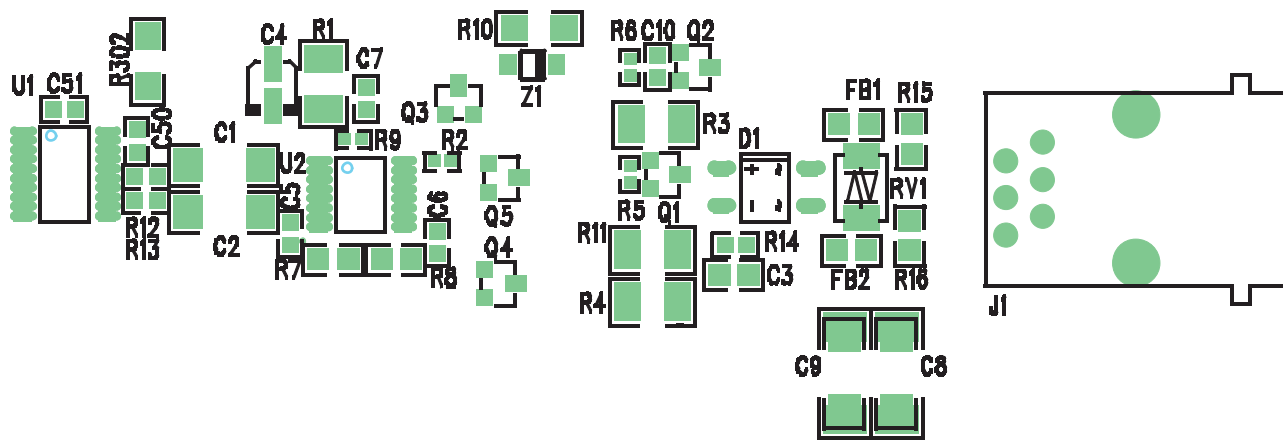
Figure 20. Reference Placement

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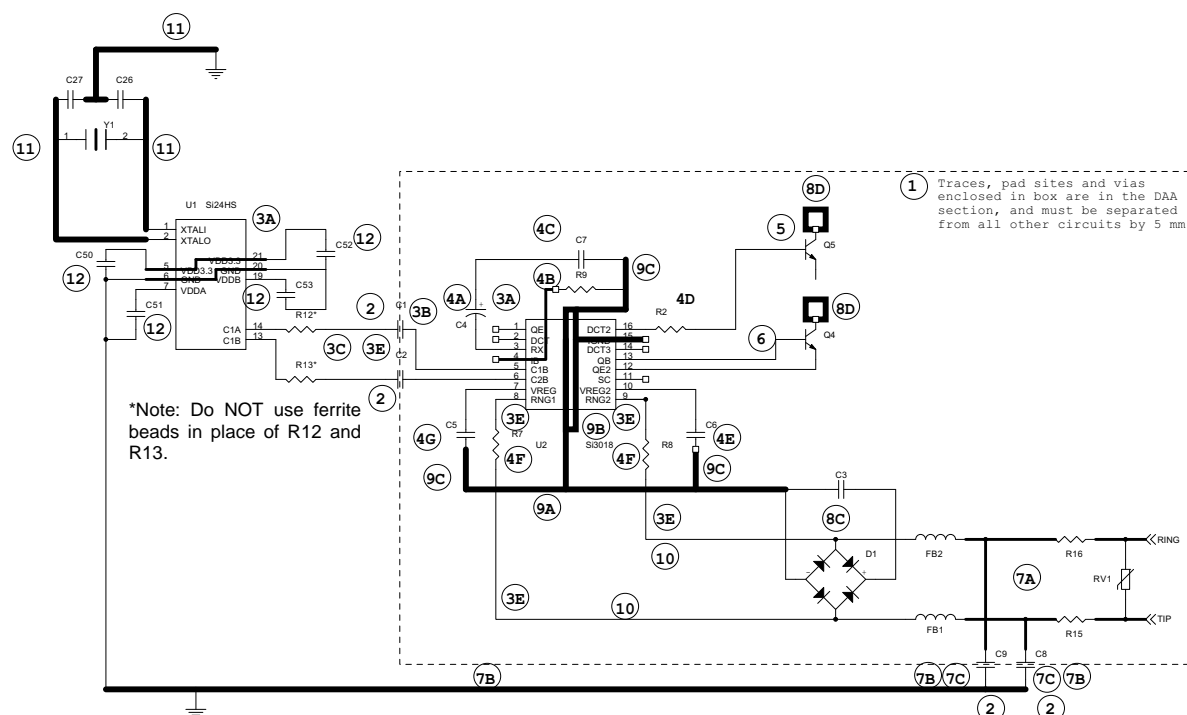
Note: Encircled references are described in the numbered paragraphs in Appendix A.

This is not a complete schematic. Only critical component placement and nets are drawn.

Figure 21. Illustrated Layout Guidelines

4.4.1. ISOmodem Layout Check List

Table 34 is a checklist that the designer can use during the layout process to ensure that all the recommendations in this application note have been implemented. Additionally, Figure 21 provides an annotated diagram of all relevant layout guidelines for the SI3054 CNR/AMR/ACR applications. See "10.4.2. Safety" on page 254 for information about design for safety compliance.

Table 34. Layout Checklist

P	#	Layout Items	Required
	1	U1 and U2 are placed so that pins 9–16 of U1 are facing pins 1–8 of U2. C1 and C2 are placed directly between U1 and U2.	
	2	Place U1, U2, C1, and C2 so that the recommended minimum creepage spacing for the target application is implemented. R12 and R13 should be close to U1.	
	3	C1 and C2 should be placed directly between U1 and U2. Short, direct traces should be used to connect C1 and C2 to U1 and U2. These traces should not be longer than two inches and should be minimized in length. Place C2 such that its accompanying trace to the C2B pin (pin 6) on the Si3018 is not close to the trace from R7 to the RNG1 pin on the Si3018 (pin 8).	
	4	Place R7 and R8 as close as possible to the RNG1 and RNG2 pins (pins 8 and 9), ensuring a minimum trace length from the RNG1 or RNG2 pin to the R7 or R8 resistor. In order to space the R7 component further from the trace from C2 to the C2B pin, it is acceptable to orient it 90 degrees relative to the RNG1 pin (pin 8).	

Table 34. Layout Checklist (Continued)

P	#	Layout Items	Required
	5	The area of the loop from C50 to U1 pin 4 and from C51 to pin 13 back to pin 12 (DGND) should be minimized. The return traces to U2 pin 12 (DGND) should be on the component side.	
	6	The loop formed by XTALI, Y1, and XTALO should be minimized and routed on one layer. The loop formed by Y1, C40, and C41 should be minimized and routed on one layer.	
	7	The digital ground plane is made as small as possible, and the ground plane has rounded corners.	
	8	Series resistors on clock signals are placed near source.	
	9	Use a minimum of 15-mil-wide traces in DAA section, use a minimum of 20-mil-wide traces for IGND.	
	10	C3 should be placed across the diode bridge, and the area of the loop formed from Si3018 pin 11 through C3 to the diode bridge and back to Si3018 pin 15 should be minimized.	
	11	FB1, FB2, and RV1 should be placed as close as possible to the RJ11.	
	12	C8 and C9 should be placed so that there is a minimal distance between the nodes where they connect to digital ground.	
	13	Use at least a 20-mil-wide trace from RJ11 to FB1, FB2, RV1, C8, and C9.	
	14	The routing from Tip and Ring of the RJ11 to the ferrite beads should be well-matched.	
	15	The traces from the RJ11 through R7 and R8 to U2 Pin 8 and Pin 9 should be well matched. These traces may be up to 10 cm long.	
	16	The distance from Tip and Ring through EMC capacitors C8 and C9 to digital ground must be short.	
	17	There should be no digital ground plane in the DAA Section.	
	18	Minimize the area of the loop from U2 pin 7 and pin 10 to C5 and C6 and from those components to U2 pin 15 (IGND).	
	19	R2 should be placed next to the base of Q5, and the trace from R2 to U2 pin16 should be less than 20 mm.	
	20	Place C4 close to U2 and connect C4 to U2 using a short, direct trace.	
	21	The area of the loop formed from U2 pin 13 to the base of Q4 and from U2 pin 12 to the emitter of Q4 should be minimized.	
	22	The trace from C7 to U2 pin 15 should be short and direct.	
	23	The trace from C3 to the D1/D2 node should be short and direct.	
	24	Provide a minimum of 5 mm creepage (or use the capacitor terminal plating spacing as a guideline for small form factor applications) from any TNV component, pad or trace, to any SELV component, pad or trace.	

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Table 34. Layout Checklist (Continued)

P	#	Layout Items	Required
	25	Minimize the area of the loop formed from U2 pin 4 to R9 to U2 pin 15.	
	26	Cathode marking for Z1.	
	27	Pin 1 marking for U1 and U2.	
	28	Space and mounting holes to accommodate for fire enclosure if necessary.	
	29	IGND does not extend under C3, D1, FB1, FB2, R15, R16, C8, C9, or RV1.	
	30	Size Q1, Q3, Q4, and Q5 collector pads to safely dissipate 0.5 W (see text).	
	31	Submit layout to Silicon Laboratories for review.	

4.4.2. Module Design and Application Considerations

Modem modules are more susceptible to radiated fields and ESD discharges than modems routed directly on the motherboard because the module ground plane is discontinuous and elevated from the motherboard's ground plane. This separation also creates the possibility of loops that couple interfering signals to the modem. Moreover, a poor motherboard layout can degrade the ESD and EMI performance of a well-designed module.

4.4.2.1. Module Design

Particular attention should be paid to power-supply bypassing and reset-line filtering when designing a modem module. Trace routing is normally very short on modules since they are generally designed to be as small as possible. Care should be taken to use ground and power planes in the low-voltage circuitry whenever possible and to minimize the number of vias in the ground and power traces. Ground and power should each be connected to the motherboard through only one pin so as not to create loops. Bypassing and filtering components should be placed as close to the modem chip as possible with the shortest possible traces to a solid ground. It is recommended that a pi filter be placed in series with the module V_{CC} pin with a filter such as the one shown in Figure 22 on the reset line. This filter also provides a proper power-on reset to the modem. Careful module design is critical since the module designer often has little control over the motherboard design and the environment in which the module will be used.

4.4.2.2. Motherboard Design

Motherboard design is critical to proper modem module performance and immunity to EMI and ESD events. First and foremost, good design and layout practices must be followed. Use ground and power planes whenever possible. Keep all traces short and direct. Use ground fill on the top and bottom layers. Use adequate power supply bypassing, and use special precautions with the power and reset lines to the modem module. Bypass V_{CC} right at the modem module connector. Be sure the modem module is connected to V_{CC} through a single pin. Likewise, be sure ground is connected to the modem module through one pin connected to the motherboard ground plane. The modem reset line is sensitive and must be kept very short and routed well away from any circuitry or components that could be subjected to an ESD event. Finally, mount the modem module as close to the motherboard as possible. Avoid high-profile sockets that increase the separation between the modem module and the motherboard.
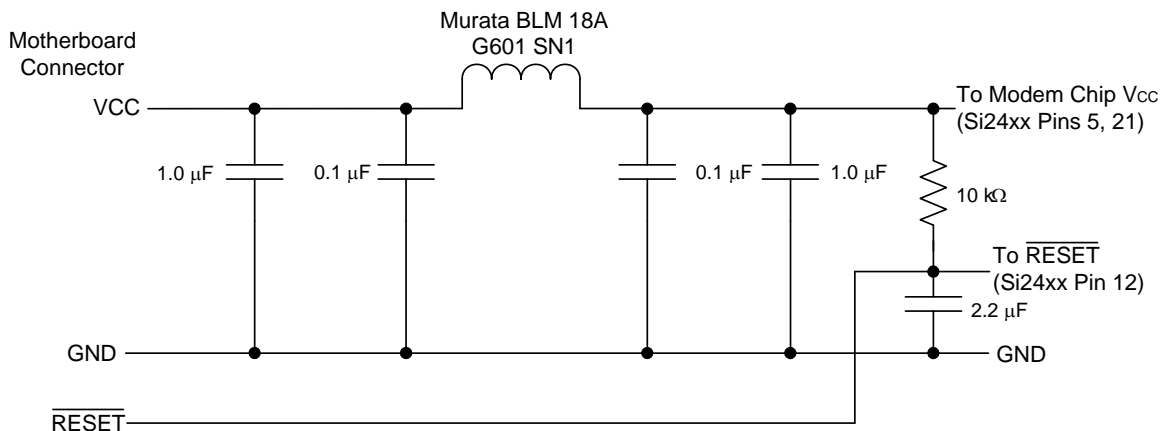
Figure 22. Modem Module V_{CC} and RESET Filter

4.5. Analog Output

The call progress tone provided by AOUT and discussed in this section comes from a PWM output pin on the ISOmodem. AOUT is a 50% duty cycle, 32 kHz square wave, pulse-width modulated (PWM) by voice band audio, such as call progress tones.

The PWM signal should be processed by a high-pass filter (R2, R3, R4, C2,C3 and C4), and, with the aid of a bridge mode amplifier, provides low-cost 100 mW to 250 mW power with a 3 to 5 V supply. See the circuit in Figure 23. A slightly more expensive amplifier (LM4862) is available and, while still pin-compatible, provides twice as much power.
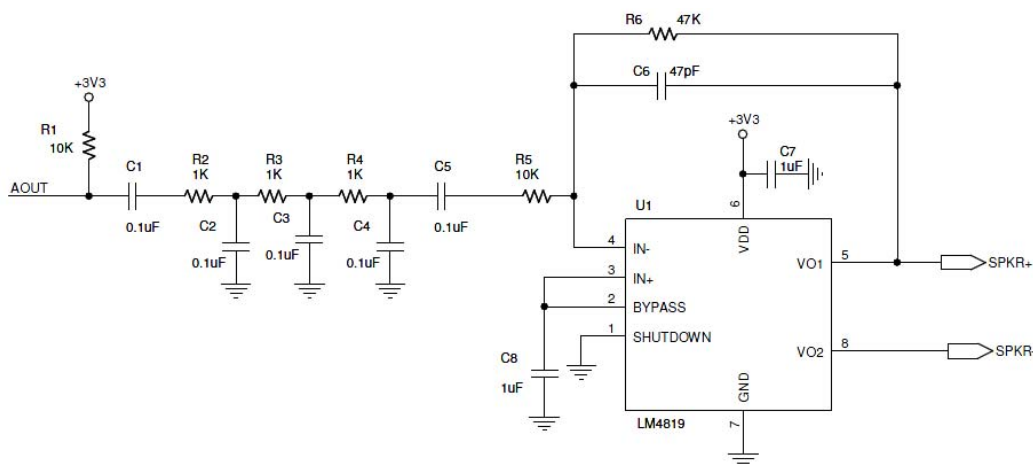
Figure 23. PWM Audio Processing and Amplifying Circuit

4.5.1. Interaction between the AOUT Circuit and the Required Modem Reset Time

When modifying the circuit shown in Figure 23, it is important to examine the reset timing and know that when external reset is applied to the modem, the AOUT pin still has time to rise to VCC due to the pullup installed on it. One has to assume that the modem has been operating prior to reset and has put AOUT into a PWM state that is 100% low.

This is important because the AOUT pin, which is shared with INT in some packages, is read by the strapping option logic in the modem at the end of the reset time to set the operational mode as shown in "2.1.3. Reset-Strap Options for 16-Pin SOIC Package" and "2.1.4. Reset-Strap Options for 24-Pin TSSOP Package" on page 13 and "2.1.5. Reset Strapping Options for QFN Parts" on page 15.

The value of the capacitors and resistors in the above circuit thus has an effect on the minimum required ISOmodem reset time.

4.5.2. Audio Quality

The mulipole filter illustrated in this diagram is designed to shape the response for a pleasant sound and remove interference, but note that, when PWM is demodulated in this way, it carries all the audio spectrum noise that is present in the power supply of the modem minus 6 dB. This requires VCC to be as clean as one wants the call progress audio to be. An alternative is for the AOUT signal to be buffered to a clean supply domain using a logic gate or transistor buffer.

The 3-pole low-pass filter, with a 3 dB point at approximately 2 kHz, filters the 32 kHz square wave from AOUT and allows only audio signals below 2 kHz to pass. See Figure 24 below. The amplifier provides differential speaker drive, eliminating the need for a large coupling capacitor. Some additional design work and optimization must be done to select the optimum gain and frequency response of this circuit, depending on speaker efficiency, final product enclosure, and performance requirements. A two- or even one-pole filter may be adequate in some applications.

Keep this audio circuitry well away from digital signals and use generous ground fill in the PCB layout.
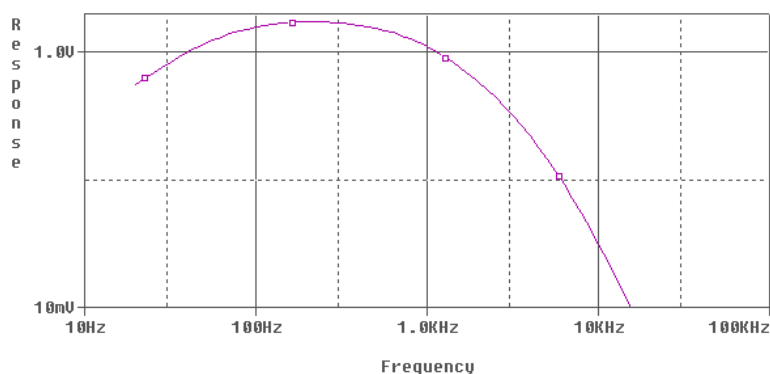
Figure 24. Audio Filter Response

5. Modem Reference Guide

This section provides information about the architecture of the modem, its functional blocks, its registers, and their interactions. The AT command set is presented, and options are explained. The accessible memory locations (S registers and U registers) are described. Instructions for writing to and reading from them are discussed along with any limitations or special considerations. A large number of configuration and programming examples are offered as illustrations of actual testable applications. These examples can be used alone or in combination to create the desired modem operation. The use of S registers and U registers to control the operation, features, and configuration of the modem is documented.

The Si24xx ISOmodem chipset family is controller-based. No modem driver is required to run on the system processor. This makes the Si24xx ISOmodem family ideal for embedded systems because a wide variety of processors and operating systems can interface with the ISOmodem through a simple UART driver.

The modems in this family operate at maximum connect rates of 48 kbps upstream/V.92 (Si2494/93), 56 kbps downstream/V.90 (Si2457), 33.6 kbps/V.34 (Si2439/34), 14.4 kbps/V.32b (Si2415), and 2400 bps/ V.22b (Si2404) with support for all standard ITU-T fallback modes. These chipsets can be programmed to comply with FCC, JATE, ETSI ES 203 021 and other country-specific PTT requirements. They also support V.42 and MNP2–4 error correction and V.42b and MNP5 compression. "Fast connect" and "transparent HDLC" modes are also supported.

The basic ISOmodem functional blocks are shown in Figure 1 on page 1. The ISOmodem includes a controller, data pump (DSP), ROM, RAM, an oscillator, phase-locked loop (PLL), timer, UART interface, a parallel interface option, an SPI interface option, and a DAA interface. An optional voice mode is supported through an SSI interface and an external Si3000 voice codec. The modem software is permanently stored in the on-chip ROM. Only modem setup information (other than defaults) and other software updates need to be stored on the host or optional external EEPROM and downloaded to the on-chip RAM during initialization. There is no nonvolatile on-chip memory other than program ROM.

The following memory notation conventions are followed in this document:

- Single-variable U registers are identified in this document as the register type (i.e., U) followed by the register's hexadecimal address and finally the register identifier in parenthesis, e.g. U4A (RGFD). Once the full register reference is made, continuing discussion refers to the register name to simplify the text. The address and value of a single variable U register are always read from or written to the ISOmodem in hexadecimal.
- Bit-mapped U registers are identified in this document at the top level as the register type (i.e., U) followed by the register's hexadecimal address and finally the register identifier in parenthesis, e.g. U67 (ITC1). Once the full register reference is made, continuing discussion of the register at the top level refers to the register name to simplify the text. The address and value of a bit-mapped U register is always read from or written to the ISOmodem in hexadecimal.
- Bits within bit-mapped registers are identified in this document as the register type (i.e., U) followed by the register's hexadecimal address, the bit or bit range within the register in brackets, and finally the bit or bit range identifier in parenthesis. Example: U67 [6] (OHS) or U67 [3:2] (] (DCT). Once the full register reference is made, continuing discussion of the bits or bit range refers to the bit or bit range name to simplify the text. The bit or bit range inside the bracket represents the actual bit or bit range within the register. The value of a bit or bit range is presented in binary for clarity. However, the address and value of a bit-mapped U register is always read from or written to the ISOmodem in hexadecimal.
- ISOmodem S registers are identified with a decimal address (e.g., S38), and the number stored in an S register is also a decimal value.

5.1. Controller

The controller provides several vital functions, including AT command parsing, DAA control, connect sequence control, DCE (data communication equipment) protocol control, intrusion detection, parallel phone off-hook detection, escape control, Caller ID control and formatting, ring detection, DTMF (dual tone multi-frequency) control, call progress monitoring, error correction, and data compression. The controller also writes to the control registers that configure the modem. Virtually all interaction between the host and the modem is done via the controller. The controller uses AT (ATtention) commands, S registers, and U registers to configure and control the modem.

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5.2. DSP

The DSP (data pump) is primarily responsible for modulation, demodulation, equalization, and echo cancellation. Because the ISOmodem is controller-based, all interaction with the DSP is via the controller through AT commands, S registers, and/or U registers.

5.3. Memory

The user-accessible memory in the ISOmodem includes the S registers, accessed via the ATSn command, and the U registers, accessed via the AT:Rhh and AT:Uhh commands. These memory locations allow the modem to be configured for a wide variety of functions and applications and for global operation.

5.4. AT Command Set

AT commands begin with the letters AT, end with a carriage return, and are case-insensitive. However, case cannot be mixed in a single command. The only exception to this format is the A/ command. This command is neither preceded by AT nor followed by a carriage return but re-executes the previous command immediately when the "/" character is typed. Generally, AT commands can be divided into two groups: control commands and configuration commands. Control commands, such as ATD, cause the modem to perform an action (in this case, dialing). The value of this type of command is changed at a particular time to perform a particular action. For example, the command ATDT1234<CR> causes the modem to go off-hook and dial the number 1234 via DTMF. No change is made to the modem settings during the execution of an action command. Configuration commands change modem characteristics until they are modified or reversed by a subsequent configuration command or the modem is reset. Modem configuration status can be determined with the use of ATY$, ATSn?, or AT:Rhh commands where Y is a group of AT command arguments, n is an S-register number (decimal), and hh is the hexadecimal address of a U register.

The AT commands for reading configuration status are listed in Table 35. Each command is followed by a carriage return.

Table 35. Configuration Status

Command	Action
ATY$ settings	Displays status of a group of settings.
AT$	Basic AT command settings.
AT&$	AT& command settings.
AT%$	AT% command settings.
AT\$	AT\ command settings.
ATSn?	Displays contents of S-register n
ATS$	Displays contents of all S registers
AT:Rhh	Displays contents of U-register hh
AT:R	Displays the current contents of all U registers.
AT+VCID?	Displays Caller ID setting.

The examples in Table 36 assume the modem is reset to its default condition. Each command is followed by a carriage return.

Table 36. Command Examples

Command	Result	Comment
AT$	E = 001	Configuration status of basic AT commands.
	M = 000	
	Q = 000	
	V = 001	
	X = 004	
	Y = 000	
AT&$	&D = 001 &G = 017	Configuration of &AT commands.
	&H = 000 (Si2457) &P = 000	
ATS2?	043	S-register 2 value—Escape code character (+).
AT:R2C	00A0	Value stored in register U2C.

The modem has a 48-character buffer, which makes it possible to enter multiple AT commands on a single line. The multiple commands can be separated with spaces or linefeed characters to improve readability. AT, space and linefeed characters are not loaded into the buffer and are not included in the 48-character count. The command line must end with carriage return for the modem to begin executing it. The modem ignores command lines longer than 48 characters and reports ERROR. Table 37 shows examples of multiple AT commands on a single line.

Table 37. Multiple AT Commands on a Single Line

Command	Result
ATS0=4M1X1<CR>	The modem auto-answers on the fourth ring. The speaker is on during dial and handshake only. Blind dialing is enabled.
AT S0=4 M1 X1 <CR>	Same as above (spaces do not matter).
ATS0=4<CR>	Same as above.
ATM1<CR>	
ATX1<CR>	

When concatenating commands on the same line, the following must also be taken in to account:

■ A semicolon is used to append to :U or :R commands. For example, AT:U42,0022;:R43;S6=4.

■ The command +IPR cannot be on the same line as a :U or :R command.

■ The commands *Y, :W, :P, +MS and +MR cannot be appended to. They must be the last command in a string.

■ The command AT+GCI=9 must be on a line of its own.

■ Consecutive U registers can be written in a single command as AT:Uhh,xxxx,yyyy,zzzz where hh is the first U-register address in the three register consecutive series. This command writes a value of xxxx to Uhh, yyyy to Uhh+1, and zzzz to Uhh+2. Additional consecutive values may be written up to the 48 character limit.

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Table 38. Consecutive U-Register Writes on a Single Line

Command	Result
AT:U00,0078,67EF,C4FA	0x0078 written to U00
	0x67EF written to U01
	0xC4FA written to U02

Caution: Some U-register addresses are reserved for internal use and hidden from the user. Consequently, there are gaps in the addresses of available U registers. Writing to reserved registers can cause unpredictable results. Care must therefore be taken not to write to reserved or undefined register locations. This is especially likely when writing to consecutive U-register addresses: all addresses covered by a conscutive write operation must be defined and allowed to the user.

The AT command execution time is as long as 300 ms. The host must wait for a response after each command (e.g., OK) before issuing additional commands. The reset recovery time (the time between a hardware reset or the carriage return of an ATZ command and the time the next AT command can be executed) must also be respected, as described in "2.1.1. Reset Sequence" on page 11.

Characters must not be sent between the ATDT command and the protocol message. During this time, the modem is in a transition between command and data modes. Any characters sent during this time will cause the connection attempt to fail.

Blind dialing (dialing without waiting for dial tone) is enabled by ATX0, ATX1, and ATX3. Whether or not blind dialing is enabled, use of the W dial modifier causes the modem to look for a dial tone before dialing the number string after the W. For example, an AT command string, ATX1 DT 9, W123456<CR>, causes the modem to dial 9 immediately without detecting a dial tone but does not dial 123456 until a dial tone is detected. AT commands and result codes are listed in Tables 39–43. The default settings are shown in bold.

Table 39. Basic AT Command Set

Command	Action
$	Display Basic AT command mode settings (see text for details). Answer incoming call. Re-execute last command (executes immediately, not preceded by AT or followed by <CR>)
A	
A/	

Table 39. Basic AT Command Set (Continued)

Command	Action
Dn	Dial The dial command, which may be followed by one or more dial command modifiers, dials a phone number: **Modifier** ! or & , or < ; @ G L P T W
En	Local DTE echo.
E0	Disable.
E1	**Enable.**
Hn	Hook-switch.
H0	Go on-hook (hang up modem).
H1	Go off-hook.
In	Identification and checksum.
I0	Display Si24xx revision code. A = Revision A. B = Revision B, etc.
I1	Display Si24xx firmware revision code (numeric).

No Patch	
AT Command	**Chip Revision**
ATI0	A
ATI1	A
ATI0	B
ATI1	B
ATI0	C
ATI1	C
ATI0	D

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
ATI1	D
Revision B Patch (rb_pX_YYYY)	
AT Command	**Chip Revision**
ATI0	B
ATI1	B
ATI0	C
ATI1	C
Revision C Patch (rc_pX_YYYY)	
AT Command	**Chip Revision**
ATI0	B (not allowed)
ATI1	B (not allowed)
ATI0	C
ATI1	C
Command	**Action**
I3	Display line-side revision code. 18 (10)C = Si3018/10 Revision C.
I6	Display the ISOmodem model number. 2404 = Si2404 2415 = Si2415 2434 = Si2434 2457 = Si2457 2493 = Si2493
I7	Diagnostic Results 1. **Format** RX <rx_rate>,TX <tx_rate> PROTOCOL: <protocol> LOCAL NAK <rre> REMOTE NAK <rte> RETRN/RR <rn> DISC REASON <dr>
I8	Diagnostic Results 2. **Format** RX LEVEL <rx_level> TX LEVEL <tx_level> EFFECTIVE S/N <esn> RESIDUAL ECHO <re>

Table 39. Basic AT Command Set (Continued)

Command	Action
Ln	Speaker Volume
L1	Low
L2	Medium
L3	High
L4	Very High
Mn	Speaker operation (via AOUT).
M0	**Speaker is always off.**
M1	Speaker is on while dialing and handshaking; off in data mode.
M2	Speaker is always on.
M3	Speaker is off while dialing; on during handshaking and retraining.
On	Return to data mode from command mode.
O0	Return to data mode.
O1	Return to data mode and perform a full retrain (at any speed except 300 bps).
O2	Return to data mode and perform rate renegotiation.
Qn	Response mode.
Q0	**Enable result codes** (See Table 43.)
Q1	Disable result codes (enable quiet mode)
R	Initiate V.23 Reversal (U53 bit 15 must be set.)
Sn	S-register operations (see Table 45)
S$	List contents of all S registers.
Sn?	Display contents of S-register n.
Sn=x	Set S-register n to value x (n and x are decimal values).
Vn	Result code type (See Table 43)
V0	Numeric result codes.

Table 39. Basic AT Command Set (Continued)

Command	Action
V1	**Verbal result codes.**
Xn	Call Progress Monitor (CPM)—This command controls which CPM signals are monitored and reported to the host from the ISOmodem (See Table 43).
X0	Basic results; disable CPM—Blind dial (does not wait for dial tone). CONNECT message does not include speed.
X1	Extended results; disable CPM—Blind dial. CONNECT message includes speed.
X2	Extended results and detect dial tone only. X1 with dial tone detection.
X3	Extended results and detect busy only. X1 with busy tone detection.
X4	**Extended results, full CPM. X1 with dial and busy tone detection.**
X5	Extended results—Full CPM enabled including ringback detection. X4 with ring back detection.
Yn	Long space disconnect—Modem hangs up after 1.5 seconds or more of continuous space while on-line.
*Y0	**Disable data memory access by disallowing :W and :Q Commands.**
*Y1	Enable continuous DTMF tone (ATxY1D9 sends continuous "9" tone).
*Y2	Enable continuous answer tone. To enable continuous answer tone and answer, use ATxY2A.
*Y254	Enables Data Memory Access, i.e. allows :W and :Q commands.
Z	Hard reset—This command is functionally-equivalent to pulsing the RESET pin low.
:E	Read from serial EEPROM. The format is AT:Ehhhh, where hhhh is the EEPROM address in hexadecimal.
:I	Interrupt read—This command causes the ISOmodem to report the lower eight bits of the interrupt register U70 (IO0). The $\overline{\text{CID}}$, OCD, PPD, and RI bits of this register are cleared, and the $\overline{\text{INT}}$ pin (HIR1 INT flag in parallel or SPI mode) is deactivated on this read.
:LPhh	Read Quick Connect data. hh is a hexadecimal value. Data are read as follows: :LP$_0$ $d_1...d_8$:LP$_8$ $d_9...d_{16}$:LP$_{10}$ $d_{17}...d_{24}$:LP$_{18}$ $d_{25}...d_{32}$
:M	Write to serial EEPROM. The format is AT:Mhhhh,xxxx, where hhhh is the EEPROM address in hexadecimal and xxxx is the EEPROM data in hexadecimal.

Table 39. Basic AT Command Set (Continued)

Command	Action
:P	Program RAM write: this command is used to upload firmware supplied by Silicon Labs to the ISOmodem. The format for this command is AT:Phhhh,xxxx,yyyy,.... where hhhh is the first address in hexadecimal, and xxxx,yyyy,.... is data in hexadecimal. Only one :P command is allowed per AT command line. No other command can be concatenated in the :P command line. This command is **only** for use with special files provided by Silicon Laboratories. Do not attempt to use this command for any other purpose. Use &T6 to display checksum for patch verification.
:Q	:Qaaaa reads hexadecimal address aaaa. Returns hexadecimal data value dddd. Only one command per line.
:R	U-register read—This command reads U-register values in hexadecimal. The format is AT:Rhh, where hh = A particular U-register address in hexadecimal. The AT:R command displays all U-register values. Only one :R command is allowed per AT command line.
:U	U-register write—This command writes to the 16-bit U registers. The format is AT:Uhh,xxxx,yyyy,zzzz,..., where hh = user-access address in hexadecimal. xxxx = data in hexadecimal to be written to location hh. yyyy = data in hexadecimal to be written to location (hh + 1). zzzz = data in hexadecimal to be written to location (hh + 2). etc. Only one :U command is allowed per AT command line.
:W	:Waaaa,dddd writes hexadecimal data value dddd to hexadecimal data address aaaa. Only one command per line.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
*Y[sequence]	Special Access Mode—This command enables special modes and data memory access. [sequence] — Description 254:Waaaa,dddd — Write hexadecimal data value dddd to hexadecimal data address aaaa. Only one 254:W command per line. 254:Qaaaa — Read hexadecimal address aaaa. Returns hexadecimal data value dddd. Only one 254:Q command per line. 2 — Enable continuous answer tone for the ATA command. Use ATZ to clear this mode. For example, the single-line, multiple command is AT*Y2A. 1 — Enable continuous DTMF tone for first digit used in the ATD command. Use ATZ to clear this mode. For example, the single-line, multiple command for a continuous DTMF "1" digit would be AT*Y1D1. 0 — Exit from 254:W or 254:Q access mode. Must reside on a separate line and must be the final sequence be sent after the final 254:W or 254:Q command.
+DR=X	Data compression reporting. X — Mode **0** — **Disabled** 1 — Enabled If enabled, the intermediate result code is transmitted at the point after error control negotiation. The format of this result code is as follows: Result code — Mode +DR:NONE — Data compression is not in use +DR:V42B — Rec. V.42bis is in use in both directions +DR:V42B RD — Rec. V.42bis is in use in receive direction only +DR:V42B TD — Rec. V.42bis is in use in transmit directions only +DR:V44 — Rec. V.44 is in use in both directions +DR:V44 RD — Rec. V.44 is in use in receive direction only +DR:V44 TD — Rec. V.44 is in use in transmit directions only

Table 39. Basic AT Command Set (Continued)

Command	Action
+DS= A,B,C,D	Controls V.42bis data compression function. A Direction 0 No compression (V.42bis P0 = 0) 1 Transmit only 2 Receive only 3 Both Directions (V.42bis P0 = 11) B Compression negotiation 0 Do not disconnect if Rec. V.42 is not negotiated. 1 Disconnect is Rec. V.42 is not negotiated. C Max_dict 512 to 65535 D Max_string 6 to 250
+DS44 = A,B,C,D,E,F,G, H,I	Controls V.44 data compression function* A Direction 0 No compression (V.42bis P0 = 0) 1 Transmit only 2 Receive only 3 Both Directions (V.42bis P0 = 11) B Compression negotiation 0 Do not disconnect if Rec. V.42 is not negotiated 1 Disconnect is Rec. V.42 is not negotiated C Capability 0 Stream method 1 Packet method 2 Multi-packet method D Max_codewords_tx 256 to 65536 E Max_codewords_rx 256 to 65536 F Max_string_tx 32 to 255 G Max_string_rx 32 to 255 H Max_history_tx $\geq$ 512 I Max_history_rx $\geq$ 512 ***Note:** Si2493 only
+ES = A, B, C	Enable synchronous access mode **A – specifies the mode of operation when initiating a modem connection** **D** = **Disable synchronous access mode** 6 = Enable synchronous access mode when connection is completed and data state is entered. **B – This parameter should not be used.** **C – Specifies the mode of operation when answer a modem connection** **D** = **Disable synchronous access mode** 8 = Enable synchronous access mode when connection is completed and data state is entered.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+ESA = A,B,C,D,E,F,G	Synchronous access mode control options **A – Specifies action taken if an underrun condition occurs during transparent sub-mode** **0 = Modem transmits 8-bit SYN sequences (see +ESA[G]) on idle.** **B – Specifies action taken if an underrun condition occurs after a flag during framed sub-mode** **0 = Modem transmits 8-bit HDLC flags on idle.** C – Specifies action taken if an underrun or overrun condition occurs after a non-flag during framed sub-mode **0 = Modem transmits abort on underrun in middle of frame.** 1 = Modem transmits flag on underrun in middle of frame and notifies host of underrun or overrun. D – Specifies V.34 half duplex operation. This parameter should not be used. E – Specifies CRC polynomial used while in framed sub-mode **0 = CRC generation checking disable** 1 = 16-bit CRC generation and checking is performed by the modem F – Specifies NRZI encoding and decoding **0 = NRZI encoding and decoding disabled** G – Defines 8-bit SYN 255 = Fixed at 255 (marks)
+FCLASS = X	Class 1 Mode Enable. X Mode **0** **Off** 1 Enables support for V.29 Fast Connect mode. 8 Enables voice mode. 256 SMS mode
+FRM = X	Class 1 Receive Carrier. X Mode 2 Detect V.21 (980 Hz) tone for longer than 100 ms, then send answer tone (2100/2225 Hz) for 200 ms. 95 V.29 short synchronous. 96 V.29 full synchronous. 200 Returns to data mode prepared to receive an SMS message.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+FTM = X	Class 1 Transmit Carrier. <u>X</u> <u>Mode</u> 2 Transmit V.21 (980 Hz) tone and detect (2100/2225 Hz). Stop transmit 980 Hz when (2100/2225 Hz is detected. 53 Same as &T4, but transmit V.29 7200 bps. Data pattern set by S40 register. AT + FCLASS = 0 must be sent to restore the ISOmodem to normal operation after test. 54 Same as &T4, but transmit V.29 9600 bps. Data pattern set by S40 register. AT + FCLASS = 0 must be sent to restore the ISOmodem to normal operation after test. 95 V.29 short synchronous. 96 V.29 full synchronous. 201 Returns to data mode prepared to transmit an SMS protocol 1 message. 202 Returns to data mode prepared to transmit an SMS protocol 2 message.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+GCI = X	Country settings: Automatically configure all registers for a particular country. **X** **Country** 9 Australia A Austria F Belgium 16 Brazil 1B Bulgaria 20 Canada 26 China 27 Columbia 2E Czech Republic 31 Denmark 35 Ecuador 3C Finland 3D France 42 Germany 46 Greece 50 Hong Kong 51 Hungary 53 India 57 Ireland 58 Israel 59 Italy 0 Japan 61 South Korea 69 Luxembourg 6C Malaysia 73 Mexico 7B Netherlands 7E New Zealand 82 Norway 87 Paraguay 89 Philippines 8A Poland 8B Portugal B8 Russia 9C Singapore 9F South Africa A0 Spain A5 Sweden A6 Switzerland FE Taiwan B4 United Kingdom **B5** **United States (default)** **Note:** U registers are configured to Silicon Laboratories' recommended values. Changes may be made by writing individual registers after sending the AT+GCI command. The +GCI command resets U registers through U86 and S6 (in Japan) to default values before setting country-specific values. Refer to the chart and setup tables beginning with "6.2.2.1. Country Initialization Table" on page 134.

Table 39. Basic AT Command Set (Continued)

Command	Action
+GCI?	List current country code setting (response is: + GCI:<setting>)
+GCI = ?	List all possible country code settings.

+IFC Options
+IFC = A
+IFC = A,B
	Specifies the flow control to be implemented.
	A Specifies the flow control method used by the host to control data from the modem
	    0 None
	    1 Local XON/OFF flow control. Does not pass XON/XOFF character to the remote
	        modem.
	    2 Hardware flow control (RTS)
	B Specifies the flow control method used by the modem to control data from the host
	    0 None
	    1 Local XON/OFF flow control.
	    2 Hardware flow control (CTS).

+IPR = <rate>	**Fixed DTE Rate.** <u><rate></u> <u>Description</u> **0** **Automatically detect the baud rate.** [BPS] The decimal value of the rate in bits per second. Note that the <rate> parameter represents the DTE rate in bps and may be set to any of the following values: 300, 600, 1200, 2400, 4800, 7200, 9600, 12000, 14400, 19200, 38400, 57600, 115200, 230400, 245760, and 307200.
+ITF Options +ITF = A +ITF = A,B +ITF = A,B,C	Transmit flow control threshold. A Threshold above which the modem will generate a flow off signal <0 to 511> bytes B Threshold below which the modem will generate a flow on signal <0 to 511> bytes C Polling interval for <EM><BNUM> indicator 0 to 300 in 10 msec units.
+MR=X	Modulation reporting control. <u>X</u> <u>Mode</u> **0** **Disabled** 1 Enabled If enabled, the intermediate result code is transmitted at the point during connect negotiation. The format of this result code is as follows: +MCR: <carrier> e.g. +MCR: V32B +MRR: <rate> e.g. +MRR: 14400

Table 39. Basic AT Command Set (Continued)

Command	Action

+MS Options
+MS = A
+MS = A,B
+MS = A,B,C
+MS = A,B,C,
D
+MS = A,B,C,
D,E
+MS = A,B,C,
D,E,F
	Modulation Selection.
	A Preferred modem carrier
	      V21 ITU-T V.21
	      V22 ITU-T V.22
	      V22B ITU-T V.22bis **(default for Si2404)**
	      V32 ITU-T V.32
	      V32B ITU-T V.32bis **(default for Si2415)**
	      V34 ITU-T V.34 **(default for Si2434)**
	      V90 ITU-T V.90 **(default for Si2457)**
	      V92 ITU-T V.92 **(default for Si2493)**
	B Automatic modulation negotiation
	      0 Disabled
	      1 **Enabled (default)**
	C Min Tx rate. Specifies minimum transmission rate.
	      0 Not configurable; always set to 0.
	D Max Tx rate. Specifies highest transmission rate. If not
	      specified, it is determined by the carrier and automode
	      settings.
	      V21 300 V32 9600 V90 33600
	      V22 1200 V32B 14400 V92 48000
	      V22B 2400 V34 33600
	E Min Rx rate. Specifies minimum receive rate.
	      0 Not configurable; always set to 0.
	F Max Rx rate. Specifies maximum receive rate. If not
	      specified (set to 0), it is determined by the carrier and
	      automode settings.
	      V21 300 V32 9600 V90 54666
	      V22 1200 V32B 14400 V92 54666
	      V22B 2400 V34 33600

+PCW = X	Controls the action to be taken upon detection of call waiting. <u>X</u> <u>Mode</u> 0 Toggle $\overline{RI}$ and collect type II Caller ID if enabled by +VCID. 1 Hang up. **2** **Ignore call waiting.**
+PIG=X	Controls the use of PCM upstream in a V.92 DCE. <u>X</u> <u>Mode</u> **0** **Enable PCM upstream.** 1 Disable PCM upstream.
+PMH=X	Controls the modem-on-hold procedures. <u>X</u> <u>Mode</u> **0** **Enables V.92 MOH.** 1 Disables V.92 MOH.
+PMHF=X	V.92 MOH hook flash. This command causes the DCE to go on-hook and then return off-hook. If this command is initiated and the modem is not On Hold, Error is returned.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+PMHR=X	Initiate MOH. Requests the DCE to initiate or to confirm a MOH procedure. Valid only if MOH is enabled. X Mode 0 V.92 MOH request denied or not available. 1 MOH with 10 s timeout granted. 2 MOH with 20 s timeout granted. 3 MOH with 30 s timeout granted. 4 MOH with 40 s timeout granted. 5 MOH with 1 min. timeout granted. 6 MOH with 2 min. timeout granted. 7 MOH with 3 min. timeout granted. 8 MOH with 4 min. timeout granted. 9 MOH with 6 min. timeout granted. 10 MOH with 8 min. timeout granted. 11 MOH with 12 min. timeout granted. 12 MOH with 16 min. timeout granted. 13 MOH with indefinite timeout granted. 14 MOH request denied. Future request will also be denied.
+PMHT=X	Controls access to MOH request and sets the timeout value. X Mode 0 Deny V.92 MOH request. 1 Grant MOH with 10 s timeout. 2 Grant MOH with 20 s timeout. 3 Grant MOH with 30 s timeout. 4 Grant MOH with 40 s timeout. 5 Grant MOH with 1 min. timeout. 6 Grant MOH with 2 min. timeout. 7 Grant MOH with 3 min. timeout. 8 Grant MOH with 4 min. timeout. 9 Grant MOH with 6 min. timeout. 10 Grant MOH with 8 min. timeout. 11 Grant MOH with 12 min. timeout. 12 Grant MOH with 16 min. timeout. 13 Grant MOH with indefinite timeout.
+PQC=X	V.92 Phase 1 and Phase 2 Control. X Mode **0** **Enable Short Phase 1 and Short Phase 2.** 1 Enable Short Phase 1. 2 Enable Short Phase 2. 3 Disable Short Phase 1 and Short Phase 2.

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+PSS=X	Selection of full or short startup procedures. X̲ Mode̲ **0** **The DCEs decide to use short startup procedures.** 1 Forces the use of short startup procedures on next and subsequent connections. 2 Forces the use of full startup procedures on next and subsequent connections.
+VCDT = n	Caller ID Type. n̲ Mode̲ **0 = After ring only** 1 = Always on 2 = UK with wetting pulse 3 = Japan 6 = DTMF
+VCID = n	Caller ID Enable. n̲ Mode̲ **0 = Off** 1 = Formatted Caller ID enabled. 2 = Raw data Caller ID enabled.
+VCIDR?	Type II Caller ID information—"+VCIDR:" will be followed by raw Caller ID information including checksum. NO DATA will be displayed if no Type II data are available.
+VDR = n	**Distinctive Ring.** n̲ Mode̲ **0,x** **Disable distinctive ring** 1,0 Enable distinctive ring. The ISOmodem will report DROF and DRON result codes only. DROF and DRON are reported in 100 ms units. 1,x Enable distinctive ring. The ISOmodem will report DROF and DRON result codes as well as well as a RING result code x/10 seconds after the falling edge of a ring pulse. DROF and DRON are reported in 100 ms units.
+VGR	**Receive Gain Selection.** The <gain> parameter has a range of 112-134 with 128 being the nominal value. This represents a range of -48 dB to 18 dB. The default is 128 (0 dB). This command is used to control the receive gain at the DTE from either the Si3000 Codec or the DAA. The purpose is to adjust the DTE receive gain for the TAM voice stream during idle state.

Table 39. Basic AT Command Set (Continued)

Command	Action
+VGT	**Transmit Gain Selection.** The <gain> parameter has a range of 112-134 with 128 being the nominal value. This represents a range of -48 to 18 dB. The default is 128 (0 dB). This command is used to control the transmit gain at the DTE to either the Si3000 Codec or the DAA. The purpose is to adjust the DTE transmit gain for the TAM voice stream during idle state.
+VIP	**Load Voice Factory Defaults.**
+VIT	**DTE/DCE Inactivity Timer.** The <timer> parameter has a range of 0–255 with units of seconds. The default is 0 (disable).
+VLS = n	**Analog Source / Destination Select.** n Description **0** **ISOmodem on-hook. AOUT disabled. Tone detectors disabled. Si3000 sample pass-through to DAA is inactive.** 1 ISOmodem off-hook. AOUT disabled. Tone detectors disabled. 4 ISOmodem on-hook. AOUT connected to ISOmodem tone generators. Tone detectors disabled. 5 ISOmodem off-hook. AOUT connected to PSTN. Tone detectors enabled. 15 ISOmodem goes off-hook, begins V.253 tone event reporting and Si3000 to DAA sample pass-through becomes active. Dial tone can be heard on handset. 20 ISOmodem on-hook. AOUT disabled. Tone detectors enabled. 21 ISOmodem on-hook. AOUT connected to ISOmodem tone generators. Tone detectors enabled.
+VNH = <hook>	**Automatic Hangup Control.** <u><hook></u> <u>Hook control description</u> **0** **The ISOmodem retains automatic hangups as is normal in the other modes (such as hanging up the phone when the ISOmodem does not detect a data carrier with a given time interval).** 1 The ISOmodem shall disable automatic hangups in the other non-voice modes. 2 The ISOmodem shall disable all hang-ups in other non-voice modes. The ISOmodem shall only perform a "logical" hangup (return the OK result code).

SILICON LABS

Table 39. Basic AT Command Set (Continued)

Command	Action
+VRA = n	**Ringing Tone Goes Away Timer.** The ISOmodem only uses this command in call origination trans-actions. This command sets the amount of time in 0.1 second units the ISOmodem shall wait between Ringing Tone before it can assume that the remote modem has gone off-hook. **Default time is five seconds.**
+VRID = n	**Repeat Caller ID.** <u>n</u> <u>Description</u> 0 Display Caller ID information of the last incoming call in formatted form. 1 Display Caller ID information of the last incoming call in unformatted form.
+VRN = n	**Ringing Tone Never Appeared Timer.** This command sets the amount of time in seconds the ISOmodem will wait looking for Ringing Tone. If the ISOmodem does not detect Ringing Tone in this time period, the ISOmodem shall assume that the remote station has gone off-hook and return an OK result code. **Default time is 0 seconds.**
+VRX	**Receive Voice Stream.** Enable DTE receive of voice stream. The DCE will return a CON-NECT response followed by the voice stream as defined by the +VSM command. The DTE can issue a <DLE><!> or <DLE><ESC> sequence to terminate the receive stream. The DCE will return a <DLE><ETX> followed by an OK response for <DLE><!> and <DLE><ESC> followed by an OK response for <DLE><ESC>. The DCE can be configured to terminate the stream using the DTE/DCE Inactivity Timer, which is configured using the +VIT command. The DTE will need to process any <DLE> shielded events present in the data stream. Any <DLE><DLE> sequences can be preserved to allow less overhead during playback of the stream with the +VTX command.
+VSD = <sds>, <sdi>	**Silence Detection.** <sds> Noise level sensitivity 127 Less aggressive [more sensitive, lower noise lev-els considered to be silence]. **128** **Nominal level of sensitivity.** 129 More aggressive [less sensitive, higher noise lev-els considered to be silence]. <sdi> sets the length of a time interval in 0.1 second units, which must contain no or little activity, before the ISOmodem will report (QUIET) (<DLE><q>). Default is five seconds.

Table 39. Basic AT Command Set (Continued)

Command	Action
+VSM = n	**Voice Compression Method.** **0 Signed PCM** 1 Unsigned PCM 4 G.711 µ-Law 5 G.711 A-Law 129 ADPCM 2-bit (2 kB/s storage) 131 ADPCM 4-bit (4 kB/s storage)
+VSP	**Voice Speakerphone State** <mode> Description **0 Speakerphone AEC, AES and LEC disabled.** **Handset FIR filter coefficients are selected.** 1 Speakerphone AEC, AES and LEC enabled. Speakerphone FIR filter coefficients are selected. The +VLS=13 command must be used in combination with this setting.
+VTD = n	**DTMF / Tone Duration Timer.** This command sets the default DTMF / tone generation duration in 10 ms units for the +VTS command. **Default time is 1 second (n = 100).**
+VTS = [<freq 1>, <freq2>, <dur>]	**DTMF and Tone Generation.** This command can be used to produce DTMF tones, single-frequency tones, and double-frequency tones. Note that the bracket characters are required for correct operation. <freq1> Frequency one, which has a range of 0, 200-3200 Hz. <freq2> Frequency two, which has a range of 0, 200-3200 Hz. <dur> Duration of the tone(s) in 10 ms units.
+VTX	**Transmit Voice Samples.** Used for sending digitized voice samples from host memory through the UART interface. The +VSM command determines the format of the samples. Multiple routing options are available.

5.5. Extended AT Commands

The extended AT commands, described in Tables 40–42, are supported by the ISOmodem.

Table 40. Extended AT& Command Set

Command	Action
&$	Display AT& current settings (see text for details).
&Dn	Escape pin function (similar to DTR)
&D0	Escape pin is not used.
&D1	**Escape pin escapes to command mode from data mode.** The escape pin must be enabled by setting bit HES (Enable Hardware Escape Pin, U70 bit 15).
&D2	Escape pin assertion during a modem connection causes the modem to go on-hook and return to command mode. The escape pin must be enabled by setting bit HES (Enable Hardware Escape Pin, U70 bit 15).
&D3	Escape pin assertion causes ATZ command (reset and return OK result code). The escape pin must be enabled by setting bit HES (Enable Hardware Escape Pin, U70 bit 15).
&Gn	Line connection rate limit—This command sets an upper limit on the line speed that the ISOmodem can connect. The &Hn commands may limit the line speed as well (&Gn not used for &H0 or &H1). Not all modulations support rates given by &G. Improper settings are ignored.
&G3	1200 bps max.
&G4	2400 bps max.
&G5	4.8 kbps max.
&G6	7.2 kbps max.
&G7	9.6 kbps max.
&G8	12 kbps max.
&G9	14.4 kbps max **(default for Si2415)**
&G10	16.8 kbps max.
&G11	19.2 kbps max.
&G12	21.6 kbps max.
&G13	24 kbps max.
&G14	26.4 kbps max.
&G15	28.8 kbps max.
&G16	31.2 kbps max.
&G17	33.6 kbps max **(default for Si2457 transmit and Si2434)**
&Hn	Switched network handshake mode—&Hn commands must be on a separate command line from ATD, ATA, or ATO commands.
&H0	V.90 with automatic fallback (56 kbps to 300 bps) **(default for Si2457)**

Notes:
  1. The initial number attempted to test for an outside line is controlled by S51 (default = 1).
  2. AT&$ reflects the last AT&P command issued but does not reflect any subsequent changes made by writing U registers with AT:U.

Table 40. Extended AT& Command Set (Continued)

&H1	V.90 only (56 kbps to 28 kbps)
&H2	V.34 with automatic fallback (33.6 kbps to 300 bps) **(default for Si2434)**
&H3	V.34 only (33.6 kbps to 2400 bps)
&H4	ITU-T V.32bis with automatic fallback (14.4 kbps to 300 bps) **(default for Si2415)**
&H5	ITU-T V.32bis only (14.4 kbps to 4800 bps)
&H6	ITU-T V.22bis only (2400 bps or 1200 bps) **(default for Si2404)**
&H7	ITU-T V.22 only (1200 bps)
&H8	Bell 212 only (1200 bps)
&H9	Bell 103 only (300 bps)
&H10	ITU-T V.21 only (300 bps)
&H11	V.23 (1200/75 bps)
&H12	V.92 with automatic fallback **(default for Si2493)**
&Pn	Japan pulse dialing*
&P0	Configure ISOmodem for 10 pulse-per-second pulse dialing
&P1	Configure ISOmodem for 20 pulse-per-second pulse dialing (Japan)
&Tn	Test mode.
&T2	Initiate ITU-T V.54 (ANALOOP) test. Modem mode set by &H. Test loop is through the DSP and DAA interface section of the ISOmodem only. ISOmodem echoes data from TX pin (Hardware Interface Register 0 in parallel or SPI mode) back to RX pin (Hardware Interface Register 0 in parallel or SPI mode). *This test mode is typically used during board-level debug.*
&T3	Initiate ITU-T V.54 (ANALOOP) test. Modem mode set by &H. Test loop is through the DSP (ISOmodem), DAA interface section (ISOmodem), ISOcap interface (Si3018/10), and analog hybrid circuit (Si3018/10). ISOmodem echoes data from TX pin (Hardware Interface Register 0 in parallel or SPI mode) back to RX pin (Register 0 in parallel or SPI mode). Phone line termination required as in Figure 25. In order to test only the ISOcap link operation, the hybrid and AFE codec can be removed from the test loop by setting U62 [1] (DL) = 1.
&T4	Initiate transmit as originating modem with automatic data generation. Modulation, data rate, and symbol rate are set by &H, &G, and S41. Data pattern is set by the S40 register. Continues until the ATH command is sent after an escape into command mode. Data are also demodulated as in ANALOOP. The test can be ended by escaping and issuing the ATH command.
&T5	Initiate transmit as answering modem with automatic data generation. Modulation, data rate, and symbol rate are set by &H, &G, and S41. Data pattern is set by the S40 register. Continues until the ATH command is sent after an escape into command mode. Data are also demodulated as in ANALOOP. The test can be ended by escaping and issuing the ATH command.
&T6	Compute checksum for firmware-upgradeable section of program memory. If no firmware upgrade is installed, &T6 returns C:4474.
&Xn	Automatic determination of telephone line type.
&X0	Abort &x1 or &x2 command.

Notes:
1. The initial number attempted to test for an outside line is controlled by S51 (default = 1).
2. AT&$ reflects the last AT&P command issued but does not reflect any subsequent changes made by writing U registers with AT:U.

SILICON LABS

Table 40. Extended AT& Command Set (Continued)

&X1	Automatic determination of telephone line type.
	Result code: WXYZn
	W: 0 = line supports DTMF dialing.
	           1 = line is pulse dial only.
	X: 0 = line supports 20 pps dialing.
	           1 = line supports 10 pps dialing only.
	Y: 0 = extension network present (PBX).
	           1 = outside line (PSTN) connected directly.
	Z: 0 = continuous dial tone.
	           1 = make-break dial tone.
	n: 0–9 (number required for outside line if Y = 0).[1]

&X2	Same as &X1, but Y result (PBX) is not tested.
Y2A[2]	Produce a constant answer tone (ITU-T) and return to command mode. The answer tone continues until the ATH command is received or the S7 timer expires.
&Z	Enter low-power wake-on-ring mode.

Notes:
1. The initial number attempted to test for an outside line is controlled by S51 (default = 1).
2. AT&$ reflects the last AT&P command issued but does not reflect any subsequent changes made by writing U registers with AT:U.

Figure 25. Phone Line Termination Circuit

SILICON LABS

Table 41. Extended AT% Command Set

Command	Action
%$	Display AT% command settings (see text for details).
%B	Report blacklist. See also S42 register.
%Cn	Data compression.
%C0	Disable V.42bis and MNP5 data compression.
%C1	**Enable V.42bis in transmit and receive paths.** If MNP is selected (\N2), %C1 enables MNP5 in transmit and receive paths.
%C2	Enable V.42bis in transmit path only.
%C3	Enable V.42bis in receive path only.
%On	Answer mode.
%O1	**ISOmodem answers a call in answer mode.**
%O2	ISOmodem answers a call in originate mode.
%Vn	Automatic Line Status Detection. After the %V1 and %V2 commands are issued, the ISOmodem automatically checks the telephone connection for whether a line is present. If a line is present, the ISOmodem automatically checks if the line is already in use. Finally, the ISOmodem checks line status both before going off-hook and again before dialing. %V1 uses the fixed method, and %V2 uses the adaptive method. %V0 (default) disables this feature.
%V0	**Disable automatic line-in-use detection.**
%V1	Automatic Line Status Detection - Fixed Method. Description: Before going off-hook with the ATD, ATO, or ATA commands, the ISOmodem compares the line voltage (via LVCS) to registers NOLN (U83) and LIUS (U84): Loop Voltage Action $0 \leq \text{LVCS} \leq \text{NOLN}$ Report NO LINE and remain on-hook. $\text{NOLN} \leq \text{LVCS} \leq \text{LIUS}$ Report LINE IN USE and remain on-hook. $\text{LIUS} \leq \text{LCVS}$ Go off-hook and establish a modem connection. Once the call has begun, the off-hook intrusion algorithm (described in "6.6.2. Off-Hook Condition" on page 162) operates normally. In addition, the ISOmodem reports NO LINE if the line is completely disconnected. If the HOI bit (U77, bit 11) is set, LINE IN USE is reported upon intrusion.

SILICON LABS

Table 41. Extended AT% Command Set (Continued)

%V2	Automatic Line Status Detection - Adaptive Method. Description: Before going off-hook with the ATD, ATO, or ATA commands, the ISOmodem compares the line voltage (via LVCS) to the NLIU (U85) register: Loop Voltage Action $0 \le LVCS \le (0.0625 \times NLIU)$ Report NO LINE and remain on-hook. $(0.0625 \times NLIU) < LVCS \le (0.85 \times NLIU)$ Report LINE IN USE and remain on-hook. $(0.85 \times NLIU) < LCVS$ Go off-hook and establish a modem connection. The NLIU register is updated every 1 ms with the minimum non-zero value of LVCS in the last 30 ms. This allows the ISOmodem to eliminate errors due to 50/60 Hz interference and also adapt to relatively slow changes in the on-hook dc reference value on the telephone line. This algorithm does not allow any non-zero values for NLIU below 0x0007. The host may also initialize NLIU prior to issuing the %V2 command. Once the call has begun, the off-hook intrusion algorithm (described in "6.6.2. Off-Hook Condition" on page 162) operates normally. In addition, the ISOmodem reports NO LINE if the telephone line is completely disconnected. If the HOI (U77, bit 11) bit is set, LINE IN USE is reported upon intrusion.

Table 42. Extended AT\ Command Set

Command	Action
\$	Display AT\ command settings (see text for details).
\Bn	Character length is automatically set in autobaud mode.
\B0	Reserved
\B1	7N1—Seven data bits, no parity, one stop bit, one start bit, nine bits total (\N0 only)
\B2	7P1—Seven data bits, parity optioned by \P, one stop bit, one start bit, ten bits total
\B3	**8N1—Eight data bits, no parity, one stop bit, one start bit, 10 bits total (default)**
\B5	8P1—Eight data bits, parity optioned by \P, one stop bit, one start bit, 11 bits total (\N0 only) **This mode is not allowed with a parallel or SPI interface.**
\B6	8X1—Eight data bits, one escape bit, one stop bit, one start bit, 11 bits total (enables ninth-bit escape mode) **This mode is not allowed with a parallel or SPI interface.**
\Nn	Asynchronous protocol.
\N0	Wire mode (no error correction, no compression).

Notes:
1. When in autobaud mode, \B0, \B1, and \P1 is not detected automatically. The combination of \B2 and \P3 is detected. This is compatible with seven data bits, no parity, two stop bits. Seven data bits, no parity, one stop bit may be forced by sending AT\T17\B1.
2. After changing the baud rate, the result code OK is sent at the *old* DTE rate. Subsequent commands must be sent at the new rate. If the ISOmodem is configured in autobaud mode, AT commands \T0 through \T15 lock the new baud rate and disable autobaud. To eliminate any possibility of a race condition between the receipt of the result code and the changing of the UART speed, CTS is de-asserted while the result code is being sent until after the rate has been successfully changed. The host should send the \T command and wait for the OK response. After OK has been received, the host may send data at the new rate as soon as CTS is asserted. The \T command should be the last command sent in a multi-command line and may not be used on the same command line as :U or :R commands. If it is not, the OK from the \T command is sent at the old DTE rate, and other result codes are sent at the new DTE rate.
3. The autobaud feature does not detect this rate.
4. Default is \T16 if autobaud is selected by reset-strap option; otherwise default is \T9 (19.2 kbps).

Table 42. Extended AT\ Command Set (Continued)

Command	Action
\N2	MNP reliable mode. The ISOmodem attempts to connect with the MNP protocol. If unsuccessful, the call is dropped. Compression is controlled by %Cn.
\N3	**V.42 auto-reliable—The ISOmodem attempts to connect with the V.42 protocol. If unsuccessful, the MNP protocol is attempted. If unsuccessful, wire mode is attempted. Compression is controlled by %Cn.**
\N4	V.42 (LAPM) reliable mode (or drop call)—Same as \N3 except that the ISOmodem drops the call instead of connecting in MNP or wire mode. Compression is controlled by %Cn.
\N5	V.42 and MNP reliable mode - The ISOmodem attempts to connect with V.42. If unsuccessful, MNP is attempted. If MNP is unsuccessful, the call is dropped. Wiremode is not attempted. Compression is controlled by %Cn.
\Pn	Parity type is automatically set in autobaud mode.
\P0	**Even**
\P1	Space[1]
\P2	Odd
\P3	Mark.
\Qn	Modem-to-DTE flow control.
\Q0	Disable all flow control—This may only be used if the DTE speed and the line (DCE) speed are guaranteed to match throughout the call.
\Q2	**Use CTS only.**
\Q3	Use RTS/CTS.
\Q4	Enable XON/XOFF flow control for modem-to-DTE interface. Does not enable modem-to-modem flow control.
\Tn	DTE rate[2]
\T0	300 bps
\T1	600 bps
\T2	1200 bps

Notes:
1. When in autobaud mode, \B0, \B1, and \P1 is not detected automatically. The combination of \B2 and \P3 is detected. This is compatible with seven data bits, no parity, two stop bits. Seven data bits, no parity, one stop bit may be forced by sending AT\T17\B1.
2. After changing the baud rate, the result code OK is sent at the *old* DTE rate. Subsequent commands must be sent at the new rate. If the ISOmodem is configured in autobaud mode, AT commands \T0 through \T15 lock the new baud rate and disable autobaud. To eliminate any possibility of a race condition between the receipt of the result code and the changing of the UART speed, CTS is de-asserted while the result code is being sent until after the rate has been successfully changed. The host should send the \T command and wait for the OK response. After OK has been received, the host may send data at the new rate as soon as CTS is asserted. The \T command should be the last command sent in a multi-command line and may not be used on the same command line as :U or :R commands. If it is not, the OK from the \T command is sent at the old DTE rate, and other result codes are sent at the new DTE rate.
3. The autobaud feature does not detect this rate.
4. Default is \T16 if autobaud is selected by reset-strap option; otherwise default is \T9 (19.2 kbps).

SILICON LABS

Table 42. Extended AT\ Command Set (Continued)

Command	Action
\T3	2400 bps
\T4	4800 bps
\T5	7200 bps
\T6	9600 bps
\T7	12.0 kbps[3]
\T8	14.4 kbps.
\T9	**19.2 kbps[4]**
\T10	38.4 kbps
\T11	57.6 kbps
\T12	115.2 kbps
\T13	230.4 kbps
\T14	245.760 kbps[3]
\T15	307.200 kbps
\T16	**Autobaud On[4]**
\T17	Autobaud Off. Lock at current baud rate.
\U	In UART mode: 1. Causes a low pulse (25 ms) on $\overline{RI}$ and $\overline{DCD}$ 2. Makes $\overline{INT}$ the inverse of ESC 3. Makes $\overline{RTS}$ the inverse of $\overline{CTS}$ In parallel or SPI mode, causes a low pulse (25 ms) on $\overline{INT}$. This command terminates with $\overline{RESET}$ and does not generate an OK message.
\Vn	Connect message type.
\V0	**Report connect and protocol message.**
\V2	Report connect message only (exclude protocol message).
\V4	Report connect and protocol message with both upstream and downstream connect rates.

Notes:
   1. When in autobaud mode, \B0, \B1, and \P1 is not detected automatically. The combination of \B2 and \P3 is detected. This is compatible with seven data bits, no parity, two stop bits. Seven data bits, no parity, one stop bit may be forced by sending AT\T17\B1.
   2. After changing the baud rate, the result code OK is sent at the *old* DTE rate. Subsequent commands must be sent at the new rate. If the ISOmodem is configured in autobaud mode, AT commands \T0 through \T15 lock the new baud rate and disable autobaud. To eliminate any possibility of a race condition between the receipt of the result code and the changing of the UART speed, CTS is de-asserted while the result code is being sent until after the rate has been successfully changed. The host should send the \T command and wait for the OK response. After OK has been received, the host may send data at the new rate as soon as CTS is asserted. The \T command should be the last command sent in a multi-command line and may not be used on the same command line as :U or :R commands. If it is not, the OK from the \T command is sent at the old DTE rate, and other result codes are sent at the new DTE rate.
   3. The autobaud feature does not detect this rate.
   4. Default is \T16 if autobaud is selected by reset-strap option; otherwise default is \T9 (19.2 kbps).

The connect messages shown in Table 43 are sent when link negotiation is complete.

Table 43. Result Codes

Numeric[1]	Meaning	Verbal Response	X0	X1	X2	X3	X4	X5
0	Command was successful	OK	X	X	X	X	**X**	X
1	Link established at 300 bps or higher	CONNECT	X	X	X	X	**X**	X
2	Incoming ring detected	RING	X	X	X	X	**X**	X
3	Link dropped	NO CARRIER	X	X	X	X	**X**	X
4	Command failed	ERROR	X	X	X	X	**X**	X
5	Link established at 1200	CONNECT 1200		X	X	X	**X**	X
6	Dial tone not present	NO DIALTONE			X		**X**	X
7	Line busy	BUSY				X	**X**	X
8	Remote not answering	NO ANSWER[2]	X	X	X	X	**X**	X
9	Ringback detected	RINGING						X
10	Link established at 2400	CONNECT 2400		X	X	X	**X**	X
11	Link established at 4800	CONNECT 4800[3]		X	X	X	**X**	X
12	Link established at 9600	CONNECT 9600[3]		X	X	X	**X**	X
14	Link established at 19200	CONNECT 19200[4]		X	X	X	**X**	X
15	Link established at 7200	CONNECT 7200[3]		X	X	X	**X**	X
16	Link established at 12000	CONNECT 12000[3]		X	X	X	**X**	X
17	Link established at 14400	CONNECT 14400[3]		X	X	X	**X**	X
18	Link established at 16800	CONNECT 16800[4]		X	X	X	**X**	X
19	Link established at 21600	CONNECT 21600[4]		X	X	X	**X**	X
20	Link established at 24000	CONNECT 24000[4]		X	X	X	**X**	X
21	Link established at 26400	CONNECT 26400[4]		X	X	X	**X**	X
22	Link established at 28800	CONNECT 28800[4]		X	X	X	**X**	X
23	Link established at 31200	CONNECT 31200[4]		X	X	X	**X**	X
24	Link established at 33600	CONNECT 33600[4]		X	X	X	**X**	X
30	Caller ID mark detected	CIDM	X	X	X	X	**X**	X
31	Hookswitch flash detected	FLASH	X	X	X	X	**X**	X

Notes:
   1. Numeric mode: Result code <CR>.
   2. Response for ATDn@mmm is silence is not found.
   3. This message is supported only on the Si2493, Si2457, Si2434, and Si2415.
   4. This message is supported only on the Si2493, Si2457, and Si2434.
   5. X is not preceded by <CR><LF>.
   6. This message is supported only on the Si2493 and Si2457.
   7. V.44 with data compression disabled (+DS = 0) emits this result code.
   8. If data compression is disabled (+DS = Q), the modem returns the message PROTOCOL:V42.

SILICON LABS

Table 43. Result Codes (Continued)

Numeric[1]	Meaning	Verbal Response	X0	X1	X2	X3	X4	X5
32	UK CID State Tone Alert Signal detected	STAS	X	X	X	X	**X**	X
33	Overcurrent condition	X[5]	X	X	X	X	**X**	X
40	Blacklist is full	BLACKLIST FULL (enabled via S42 register)	X	X	X	X	**X**	X
41	Attempted number is black-listed.	BLACKLISTED (enabled via S42 register)	X	X	X	X	**X**	X
42	No phone line present	NO LINE (enabled via %Vn commands)	X	X	X	X	**X**	X
43	Telephone line is in use	LINE IN USE (enabled via %Vn commands)	X	X	X	X	**X**	X
44	Polarity reversal detected	POLARITY REVERSAL (enabled via G modifier)	X	X	X	X	**X**	X
45	Polarity reversal NOT detected	NO POLARITY REVERSAL (enabled via G modifier)	X	X	X	X	**X**	X
52	Link established at 56000	CONNECT 56000[6]		X	X	X	**X**	X
60	Link established at 32000	CONNECT 32000[6]		X	X	X	**X**	X
61	Link established at 48000	CONNECT 48000[6]		X	X	X	**X**	X
63	Link established at 28000	CONNECT 28000[6]		X	X	X	**X**	X
64	Link established at 29333	CONNECT 29333[6]		X	X	X	**X**	X
65	Link established at 30666	CONNECT 30666[6]		X	X	X	**X**	X
66	Link established at 33333	CONNECT 33333[6]		X	X	X	**X**	X
67	Link established at 34666	CONNECT 34666[6]		X	X	X	**X**	X
68	Link established at 36000	CONNECT 36000[6]		X	X	X	**X**	X
69	Link established at 37333	CONNECT 37333[6]		X	X	X	**X**	X
70	No protocol	PROTOCOL: NONE	Set with \V0 command.					
75	Link established at 75	CONNECT 75		X	X	X	**X**	X
77	V.42 protocol	PROTOCOL: V42[7]	Set with \V0 command.					
79	V.42bis protocol	PROTOCOL: V42bis[3]	Set with \V0 command.					

Notes:
1. Numeric mode: Result code <CR>.
2. Response for ATDn@mmm is silence is not found.
3. This message is supported only on the Si2493, Si2457, Si2434, and Si2415.
4. This message is supported only on the Si2493, Si2457, and Si2434.
5. X is not preceded by <CR><LF>.
6. This message is supported only on the Si2493 and Si2457.
7. V.44 with data compression disabled (+DS = 0) emits this result code.
8. If data compression is disabled (+DS = Q), the modem returns the message PROTOCOL:V42.

SILICON LABS

Table 43. Result Codes (Continued)

Numeric[1]	Meaning	Verbal Response	X0	X1	X2	X3	X4	X5
80	MNP2 protocol	PROTOCOL: ALTERNATE, +CLASS 2	Set with \V command.					
81	MNP3 protocol	PROTOCOL: ALTERNATE, +CLASS 3	Set with \V command.					
82	MNP4 protocol	PROTOCOL: ALTERNATE, +CLASS 4	Set with \V command.					
83	MNP5 protocol	PROTOCOL: ALTERNATE, +CLASS 5[3]	Set with \V command.					
84	V.44 protocol	PROTOCOL: V.44[8]	Set with +DR command					
90	Link established at 38666	CONNECT 38666[6]		X	X	X	**X**	X
91	Link established at 40000	CONNECT 40000[6]		X	X	X	**X**	X
92	Link established at 41333	CONNECT 41333[6]		X	X	X	**X**	X
93	Link established at 42666	CONNECT 42666[6]		X	X	X	**X**	X
94	Link established at 44000	CONNECT 44000[6]		X	X	X	**X**	X
95	Link established at 45333	CONNECT 45333[6]		X	X	X	**X**	X
96	Link established at 46666	CONNECT 46666[6]		X	X	X	**X**	X
97	Link established at 49333	CONNECT 49333[6]		X	X	X	**X**	X
98	Link established at 50666	CONNECT 50666[6]		X	X	X	**X**	X
99	Link established at 52000	CONNECT 52000[6]		X	X	X	**X**	X
100	Link established at 53333	CONNECT 53333[6]		X	X	X	**X**	X
101	Link established at 54666	CONNECT 54666[6]		X	X	X	**X**	X
102	DTMF dial attempted on a pulse dial only line	UN-OBTAINABLE NUMBER	X	X	X	X	**X**	X

Notes:
1. Numeric mode: Result code <CR>.
2. Response for ATDn@mmm is silence is not found.
3. This message is supported only on the Si2493, Si2457, Si2434, and Si2415.
4. This message is supported only on the Si2493, Si2457, and Si2434.
5. X is not preceded by <CR><LF>.
6. This message is supported only on the Si2493 and Si2457.
7. V.44 with data compression disabled (+DS = 0) emits this result code.
8. If data compression is disabled (+DS = Q), the modem returns the message PROTOCOL:V42.

SILICON LABS

Table 44. Disconnect Codes

Disconnect Code	Reason
8002	Handshake stalled.
8	No dial tone detected.
8008	No line available.
9	No loop current detected.
8009	Parallel phone pickup disconnect.
A	No ringback.
B	Busy signal detected.
D	V.42 requested disconnect.
E	MNP requested disconnect.
10	Drop-dead timer disconnect.
8014	Loop-current loss.
8017	Remote modem requested disconnect.
8018, 8019	Soft-reset command received.
1a	V.42 Protocol error.
1b	MNP Protocol error.
801c	Loss-of-carrier disconnect.
801e	Long-space disconnect.
801f	Character-abort disconnect.
802a	Rate request failed.
802b	Answer modem energy not detected.
802c	V.8 negotiation failed.
2d	TX data timeout.

5.6. S Registers

S registers are typically used to set modem configuration parameters during initialization and are not usually changed during normal modem operation. S-register values other than defaults must be written via the ATSn=x command after every reset event. S registers are specified as a decimal value (S1 for example), and the contents of the register are also decimal numbers. Table 45 lists the S registers available on the ISOmodem, their functions, default values, ranges of values, and units.

Many S registers are industry standards, such as S0 (number of rings for auto answer), S1 (ring count), and S2 (escape character) among others. However, there are usually variations in the function (and availability) of S registers from one chipset to another or from one chipset manufacturer to another. These variations are due to a combination of feature availability and choices made during the chip design. It is prudent to verify the compatibility of S-register functions, defaults, ranges, and values when adapting the ISOmodem to an existing design that uses another chipset. This simple step can save time and help speed product development. If a particular S register is not available on the ISOmodem, the register may not be necessary, or the function of the S register may be available with the use of U registers (discussed later) or through an AT command.

Table 45. S-Register Descriptions

Definition				
S Register (Decimal)	**Function**	**Default (Decimal)**	**Range**	**Units**
0	Automatic answer—This value represents the number of rings the ISOmodem must detect before answering a call. 0 disables auto answer.	0	0–255	rings
1	Ring counter—Counts rings received on current call.	0	0–255	rings
2	ESC code character	43 (+)	0–255	(ASCII)
3	Carriage return character	13 (CR)	0–255	(ASCII)
4	Linefeed character	10 (LF)	0–255	(ASCII)
5	Backspace character	08 (BS)	0–255	(ASCII)
6	Dial tone wait timer—This timer sets the number of seconds the ISOmodem waits before blind dialing and is only active if blind dialing is enabled (X0, X1, X3).	02	0–255	seconds
7	Carrier wait timer—This timer starts when dialing is completed. It sets the number of seconds the modem waits without carrier before hanging up and the number of seconds the modem waits for ringback when originating a call before hanging up. The register also sets the number of seconds the answer tone continues while using the AT*Y2A command.	80	0–255	seconds
8	Dial pause timer for "," and "<" dial command modifiers	02	0–255	seconds
9	Carrier presence timer—Time the remote modem carrier must be detected before activating or reactivating DCD (carrier loss debounce time).	06	1–255	0.1 second

SILICON LABS

Table 45. S-Register Descriptions (Continued)

S Register (Decimal)	Function	Default (Decimal)	Range	Units
	Definition			
10	Carrier loss timer—The time a remote modem carrier must be lost before the ISOmodem disconnects. Setting this timer to 255 disables the timer, and the modem does not time out and disconnect. If S10 is less than S9, even a momentary loss of carrier causes a disconnect. Use for V.22bis and lower data rates.	14	1–255	0.1 second
12	Escape code guard timer—Minimum guard time before and after +++ to recognize a valid escape sequence.	50	10–255	0.02 second
14	Wait for dial tone delay timer. This timer starts when the W command is executed in the dial string.	12	0–255	seconds
24	Sleep inactivity time—This is the time the modem operates in normal power mode with no activity on the UART, parallel port, SPI port, or telephone line before entering the low-power sleep mode and waking on ring. The modem remains in the normal power mode, regardless of activity, if the timer is set to 0.	0	0–255	seconds
30	Disconnect activity timer—Sets the length of time that the modem stays online before disconnecting with no activity on the UART, parallel port, SPI port, or telephone line (ring, hookswitch flash, or Caller ID). This feature is disabled if set to 0.	0	0–255	minutes
38	Hang up delay time—Maximum delay between receipt of the ATH0 command and hang up. If time out occurs before all data can be sent, the NO CARRIER (3) result code is sent. An OK response is sent if all data are transmitted prior to time out. This register applies to V.42 mode only. S38=255 disables time out, and the modem only disconnects if data are successfully sent or carrier lost.	20	0–255	seconds
40	Data Pattern - Data pattern generated during &T4 and &T5 transmit tests. **0 – All spaces (0s)** 1 – All marks (1s) 2 – Random data	0	0–2	–

Table 45. S-Register Descriptions (Continued)

S Register (Decimal)	Function	Default (Decimal)	Range	Units
	Definition			
41	V.34 symbol rate - Symbol rate for V.34 when using the &T4 and &T5 commands. **0 – 2400 symbols/second** 1 – 2743 symbols/second 2 – 2800 symbols/second 3 – 3000 symbols/second 4 – 3200 symbols/second 5 – 3429 symbols/second A valid combination of symbol rate (S41) and data rate (&G) must be selected. **Symbol Rate Allowable Data Rates** 2400 2400 – 21600 2743 4800 – 26400 2800 4800 – 26400 3000 4800 – 28800 3200 4800 – 31200 3429 4800 – 33600	0	0–5	–
42	Blacklisting—The ISOmodem does not dial the same number more than two times in S44 seconds. An attempt to dial a third time within S44 seconds results in a BLACKLISTED result code. If the blacklist memory is full, any dial to a new number will result in a BLACKLIST FULL result code. Numbers are added to the blacklist only if the modem connection fails. The %B command lists the numbers on the blacklists. **0 – disabled** 1 – enabled	0 (disabled)	0–1	–
43	Dial attempts to blacklist. When blacklisting is enabled with S42, this value controls the number of dial attempts that result in a number being blacklisted.	4	0–4	–
44	Blacklist Timer Period during which blacklisting is active	180	0–255	seconds
50	Minimum on-hook time—Modem remains on-hook for S50 seconds. Any attempt to go off-hook is delayed until this timer expires.	3	0–255	seconds
51	Number to start checking for an outside PBX line.	1	0–9	–

SILICON LABS

5.7. U Registers

U registers (user-access registers) are 16-bit registers written by the AT:Uhh command and read by the AT:R (read all U registers) command or AT:Rhh (read U-register hh) command. See the AT command list in Table 39 on page 59. All values associated with the U registers, the address, and the value written to or read from the register are hexadecimal.

Some U registers are reserved and not available to the user. Therefore, there are gaps in the available U-register address sequence. Additionally, some bits within available U registers are reserved. Any attempt to write to a non-listed U register or to write a reserved bit can cause unpredictable modem operation.

There are two types of U registers. The first represents a single 16-bit term, such as a filter coefficient, threshold, delay, or other quantity. These registers can be read from or written to as a single 16-bit value. The second type of U register is bit mapped. Bit-mapped registers are also written and/or read in hexadecimal, but each bit or combination of bits in the register represents an independent value. These individual bits are used to enable or disable features and indicate states. Bits in these registers can be read/write, read only, reserved, or they may be required to always be set to a certain value. Pay particular attention when writing to bit-mapped registers to ensure no reserved bits are overwritten. When changing bits in a U register with reserved bits, use a read-modify-write procedure: read the register value with AT:R; modify only the desired bits, then write the new value with AT:U. This will ensure the reserved bits are not altered. All U registers revert to their default settings after a reset.

The U registers can be broken into three groups: call progress (U0–U33, U49–U4C), dialing (U37–U48), line interface, and extended functions (U4D–UA9). Table 46 lists the available U registers, a brief description, and their default values. Table 47 summarizes the signals and values available in the bit-mapped registers. Country-specific register values are presented in "6.2. Country-Dependent Setup" on page 133. All default settings are chosen to meet FCC requirements.

Table 46. U-Register Descriptions

Register	Address (Hex)	Name	Description	Default Value
U00	0x0000	DT1A0	Dial-tone detection filters stage 1 biquad coefficients.	0x0800
U01	0x0001	DT1B1		0x0000
U02	0x0002	DT1B2		0x0000
U03	0x0003	DT1A2		0x0000
U04	0x0004	DT1A1		0x0000
U05	0x0005	DT2A0	Dial-tone detection filters stage 2 biquad coefficients.	0x00A0
U06	0x0006	DT2B1		0x6EF1
U07	0x0007	DT2B2		0xC4F4
U08	0x0008	DT2A2		0xC000
U09	0x0009	DT2A1		0x0000
U0A	0x000A	DT3A0	Dial-tone detection filters stage 3 biquad coefficients.	0x00A0
U0B	0x000B	DT3B1		0x78B0
U0C	0x000C	DT3B2		0xC305
U0D	0x000D	DT3A2		0x4000
U0E	0x000E	DT3A1		0xB50A

Table 46. U-Register Descriptions (Continued)

Register	Address (Hex)	Name	Description	Default Value
U0F	0x000F	DT4A0	Dial-tone detection filter stage 4 biquad coefficients.	0x0400
U10	0x0010	DT4B1		0x70D2
U11	0x0011	DT4B2		0xC830
U12	0x0012	DT4A2		0x4000
U13	0x0013	DT4A1		0x80E2
U14	0x0014	DTK	Dial-tone detection filter output scaler.	0x0009
U15	0x0015	DTON	Dial-tone detection ON threshold.	0x00A0
U16	0x0016	DTOF	Dial-tone detection OFF threshold.	0x0070
U17	0x0017	BT1A0	Busy-tone detection filters stage 1 biquad coefficients.	0x0800
U18	0x0018	BT1B1		0x0000
U19	0x0019	BT1B2		0x0000
U1A	0x001A	BT1A2		0x0000
U1B	0x001B	BT1A1		0x0000
U1C	0x001C	BT2A0	Busy-tone detection filter stage 2 biquad coefficients.	0x00A0
U1D	0x001D	BT2B1		0x6EF1
U1E	0x001E	BT2B2		0xC4F4
U1F	0x001F	BT2A2		0xC000
U20	0x0020	BT2A1		0x0000
U21	0x0021	BT3A0	Busy-tone detection filter stage 3 biquad coefficients.	0x00A0
U22	0x0022	BT3B1		0x78B0
U23	0x0023	BT3B2		0xC305
U24	0x0024	BT3A2		0x4000
U25	0x0025	BT3A1		0xB50A
U26	0x0026	BT4A0	Busy-tone detection filter stage 4 biquad coefficients.	0x0400
U27	0x0027	BT4B1		0x70D2
U28	0x0028	BT4B2		0xC830
U29	0x0029	BT4A2		0x4000
U2A	0x002A	BT4A1		0x80E2
U2B	0x002B	BTK	Busy-tone detection filter output scaler.	0x0009
U2C	0x002C	BTON	Busy-tone detection ON threshold.	0x00A0
U2D	0x002D	BTOF	Busy-tone detection OFF threshold.	0x0070

Table 46. U-Register Descriptions (Continued)

Register	Address (Hex)	Name	Description	Default Value
U2E	0x002E	BMTT	Busy cadence minimum total time in seconds multiplied by 7200.	0x0870
U2F	0x002F	BDLT	Busy cadence delta in seconds multiplied by 7200.	0x25F8
U30	0x0030	BMOT	Busy cadence minimum on time in seconds multiplied by 7200.	0x0438
U31	0x0031	RMTT	Ringback cadence minimum total time in seconds multiplied by 7200.	0x4650
U32	0x0032	RDLT	Ringback cadence delta in seconds multiplied by 7200.	0xEF10
U33	0x0033	RMOT	Ringback cadence minimum on time in seconds multiplied by 7200.	0x1200
U34	0x0034	DTWD	Window to look for dial tone in seconds multiplied by 1000.	0x1B58
U35	0x0035	DMOT	Minimum dial tone on time in seconds multiplied by 7200.	0x2D00
U37	0x0037	PD0	Number of pulses to dial 0.	0x000A
U38	0x0038	PD1	Number of pulses to dial 1.	0x0001
U39	0x0039	PD2	Number of pulses to dial 2.	0x0002
U3A	0x003A	PD3	Number of pulses to dial 3.	0x0003
U3B	0x003B	PD4	Number of pulses to dial 4.	0x0004
U3C	0x003C	PD5	Number of pulses to dial 5.	0x0005
U3D	0x003D	PD6	Number of pulses to dial 6.	0x0006
U3E	0x003E	PD7	Number of pulses to dial 7.	0x0007
U3F	0x003F	PD8	Number of pulses to dial 8.	0x0008
U40	0x0040	PD9	Number of pulses to dial 9.	0x0009
U42	0x0042	PDBT	Pulse dial break time (ms units).	0x003D
U43	0x0043	PDMT	Pulse dial make time (ms units).	0x0027
U45	0x0045	PDIT	Pulse dial interdigit time (ms units).	0x0320
U46	0x0046	DTPL	DTMF power level.	0x09B0
U47	0x0047	DTNT	DTMF on time (ms units).	0x0064
U48	0x0048	DTFT	DTMF off time (ms units).	0x0064
U49	0x0049	RGFH	Ring frequency high (2400/maximum valid ring frequency in Hz).	0x0022
U4A	0x004A	RGFD	Ring frequency delta = (2400/minimum valid ring frequency in Hz) – (2400/maximum valid ring frequency in Hz)	0x007A
U4B	0x004B	RGMN	Ring cadence minimum ON time in seconds multiplied by 2400.	0x0258
U4C	0x004C	RGNX	Ring cadence maximum total time in seconds multiplied by 2400.	0x6720
U4D	0x004D	MOD1	This is a bit-mapped register.	0x0000

Table 46. U-Register Descriptions (Continued)

Register	Address (Hex)	Name	Description	Default Value
U4E	0x004E	PRDD	Pre-dial delay-time—(ms units).	0x0000
U4F	0x004F	FHT	Flash hook time—(ms units).	0x01F4
U50	0x0050	LCDN	Loop current debounce on time (ms units).	0x015E
U51	0x0051	LCDF	Loop current debounce off time (ms units).	0x00C8
U52	0x0052	XMTL	Transmit level adjust (1 dB units)	0x0000
U53	0x0053	MOD2	This is a bit-mapped register.	0x0000
U62	0x0062	DAAC1	This is a bit-mapped register.	0x0804
U63	0x0063	DAAC3	This is a bit-mapped register.	0x0003
U65	0x0065	DAAC4	This is a bit-mapped register.	0x00E0
U66	0x0066	DAAC5	This is a bit-mapped register.	0xXX40
U67	0x0067	ITC1	This is a bit-mapped register.	0x0008
U68	0x0068	ITC2	This is a bit-mapped register.	0x0000
U6A	0x006A	ITC4	This is a bit-mapped register (read only).	N/A
U6C	0x006C	LVS	This is a bit-mapped register.	0xXX00
U6E	0x006E	CK1	This is a bit-mapped register.	0x1FA0
U6F	0x006F	PTME	This is a bit-mapped register.	0x0001
U70	0x0070	IO0	This is a bit-mapped register.	0x2700
U71	0x0071	IO1	This is a bit-mapped register.	0x0000
U76	0x0076	GEN1	This is a bit-mapped register.	0x3240
U77	0x0077	GEN2	This is a bit-mapped register.	0x401E
U78	0x0078	GEN3	This is a bit-mapped register.	0x0000
U79	0x0079	GEN4	This is a bit-mapped register.	0x00XX
U7A	0x007A	GENA	This is a bit-mapped register.	0x0000
U7C	0x007C	GENC	This is a bit-mapped register.	0x0000
U7D	0x007D	GEND	This is a bit-mapped register.	0x4001
U80	0x0080		This is a bit-mapped register.	0x0168
U83	0x0083	NOLN	No-Line threshold. If %V1 is set, NOLN sets the threshold for determination of line present vs. line not present. 3 V/bit	0x0001
U84	0x0084	LIUS	Line-in-use threshold. If %V1 is set, LIUS sets the threshold for determination of line in use vs. line not in use. 3 V/bit	0x0007
U85	0x0085	NLIU	Line-in-use/No-line threshold. If %V2 is set, NLIU sets the threshold reference for the adaptive algorithm (see %V2). 3 V/bit	0x0000

Table 46. U-Register Descriptions (Continued)

Register	Address (Hex)	Name	Description	Default Value
U86	0x0086	V9AGG	V.90 rate reduction in 1333 bps units. The V.90 connect rate is reduced by this amount during negotiation.	0x0000
U87	0x0087	SAMCO	This is a bit-mapped register	0x0000
U9F[1]	0x009F	SASF	SAS frequency detection.	0x0000
UA0[2]	0x00A0	SC0	SAS cadence 0. Sets the duration of the first SAS tone (ms).	0x001E
UA1[2]	0x00A1	SC1	SAS cadence 1. Sets the duration of the first SAS silence (ms).	0x0000
UA2[2]	0x00A2	SC2	SAS cadence 2. Sets the duration of the second SAS tone (ms).	0x0000
UA3[2]	0x00A3	SC3	SAS cadence 3. Sets the duration of the second SAS silence (ms).	0x0000
UA4[2]	0x00A4	SC4	SAS cadence 4. Sets the duration of the third SAS tone (ms).	0x0000
UA5[2]	0x00A5	SC5	SAS cadence 5. Sets the duration of the third SAS silence (ms).	0x0000
UA6[2]	0x00A6	SC6	SAS cadence 6. Sets the duration of the fourth SAS tone (ms).	0x0000
UA7[2]	0x00A7	SC7	SAS cadence 7. Sets the duration of the fourth SAS silence (ms).	0x0000
UA8[2]	0x00A8	SC8	SAS cadence 8. Sets the duration of the fifth SAS tone (ms).	0x0000
UA9[2]	0x00A9	SC9	SAS cadence 9. Sets the duration of the fifth SAS silence (ms).	0x0000
UAA[2]	0x00AA	V29MODE	This is a bit-mapped register.	0x0000
UIDA	0x01DA		Delay (ms) to the response to an answer tone	0x0000

Notes:
   1. See Table 100 for details.
   2. See Table 101 for details.

SILICON LABS

5.7.1. U-Register Summary

Table 47. Bit-Mapped U-Register Summary

Register	Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
U4D	MOD1		TOCT		NHFP	NHFD	CLPD		FTP	SPDM		GT18	GT55	CTE			
U53	MOD2	REV															
U54	CALT					OHCT											
U62	DAAC1								OHS2						FOH	DL	
U63	DAAC3				LCS						ACT						
U65	DAAC4		PWMG	PDN									PDL				
U66	DAAC5										FDT						
U67	ITC1				MINI		ILIM		DCR	OHS			DCV			RZ	RT
U68	ITC2														BTE	ROV	BTD
U6A	ITC4		SQ1		SQ0										OVL		
U6C	LVS				LVS												
U6E	CK1					R1							HRS				
U6F	PTME									PTMR							
U70	IO0	HES		TES	CIDM	OCDM	PPDM	RIM	DCDM				CID	OCD	PPD	RI	DCD
U71	IO1												COMP				PRT
U76	GEN1				OHSR				FACL		DCL			ACL			
U77	GEN2		IST			HOI		AOC				OHT					
U78	GEN3		IB									IS					
U79	GEN4													LVCS			
U7A	GENA					ARMLO				DOP	ADD					HDLC	FAST
U7C	GENC											RIGPO					RIG-POEN
U7D	GEND		NLM		TCAL	CALD										ATZD	FDP
U80	XMITDEL	V22FCDF				V22FCDEL											
U87	SAM						MINT	SERM	FSMS			XMTT					
UAA	V29MODE														RUDE	V29ENA	

5.7.2. U00–U16 (Dial Tone Detect Filter Registers)

U00–U13 set the biquad filter coefficients for stages 1–4 of the dial-tone detection filter. U14, U15, and U16 set the dial-tone detection output scaler, on threshold and off threshold, respectively.

The thresholds are empirically found scalars and have no units. These coefficients are programmed as 16-bit, two's complement values. All A0 values are in 3.12 format where 1.0 = 0x1000. All other coefficients are in 1.14 format where 1.0 = 0xC000. Default settings meet FCC requirements. Additionally, register U34 sets the time window in which a dial tone can be detected. Register U35 sets the minimum time within the U34 window that the dial tone must be present for a valid detection. See "5.7.5. U34–U35 (Dial Tone Timing Register)" for more information.

Table 48. U0–U16 (Dial Tone Registers)

Register	Name	Description	Default
U00	DT1A0		0x0800
U01	DT1B1		0x0000
U02	DT1B2	Dial-tone detection filters stage 1 biquad coefficients.	0x0000
U03	DT1A2		0x0000
U04	DT1A1		0x0000
U05	DT2A0		0x00A0
U06	DT2B1		0x6EF1
U07	DT2B2	Dial-tone detection filters stage 2 biquad coefficients.	0xC4F4
U08	DT2A2		0xC000
U09	DT2A1		0x0000
U0A	DT3A0		0x00A0
U0B	DT3B1		0x78B0
U0C	DT3B2	Dial-tone detection filters stage 3 biquad coefficients.	0xC305
U0D	DT3A2		0x4000
U0E	DT3A1		0xB50A
U0F	DT4A0		0x0400
U10	DT4B1		0x70D2
U11	DT4B2	Dial-tone detection filters stage 4 biquad coefficients.	0xC830
U12	DT4A2		0x4000
U13	DT4A1		0x80E2
U14	DTK	Dial-tone detection filter output scaler.	0x0009
U15	DTON	Dial-tone detection ON threshold.	0x00A0
U16	DTOF	Dial-tone detection OFF threshold.	0x0070

5.7.3. U17–U30 (Busy Tone Detect Filter Registers)

U17–U2A set the biquad filter coefficients for stages 1–4 of the busy-tone detection filter, and U2B, U2C, and U2D set the busy-tone detection output scalar on threshold and off threshold, respectively (see Table 49). The thresholds are empirically found scalars and have no units. These coefficients are programmed as 16-bit, two's complement values. All A0 values are in 3.12 format where 1.0 = 0x1000. All other coefficients are in 1.14 format where 1.0 = 0xC000. Default values meet FCC requirements.

U2E, U2F, and U30 set the busy cadence minimum total time (BMTT), busy cadence delta time (BDLT), and busy cadence minimum on time (BMOT), respectively. Settings for busy cadences are specified as a range for ON time (minimum ON and maximum ON) and a range for OFF time (minimum OFF and maximum OFF). The three values represented by BMTT, BDLT, and BMOT fully specify these ranges. BMTT (minimum total time) is equal to the minimum ON time plus the minimum OFF time. BDLT (allowable delta) is equal to the maximum total time (maximum ON time plus the maximum OFF time) minus the minimum total time (BMTT). BMOT is the minimum ON time. The values stored in the registers are the hexadecimal representation of the times in seconds multiplied by 7200. Default values meet FCC requirements (see Figure 26, "Cadence Timing," on page 100).

Table 49. U17–U30 (Busy Tone Detect Registers)

Register	Name	Description	Default
U17	BT1A0	Busy-tone detection filter stage 1 biquad coefficients.	0x0800
U18	BT1B1		0x0000
U19	BT1B2		0x0000
U1A	BT1A2		0x0000
U1B	BT1A1		0x0000
U1C	BT2A0	Busy-tone detection filter stage 2 biquad coefficients.	0x00A0
U1D	BT2B1		0x6EF1
U1E	BT2B2		0xC4F4
U1F	BT2A2		0xC000
U20	BT2A1		0x0000
U21	BT3A0	Busy-tone detection filter stage 3 biquad coefficients.	0x00A0
U22	BT3B1		0x78B0
U23	BT3B2		0xC305
U24	BT3A2		0x4000
U25	BT3A1		0xB50A
U26	BT4A0	Busy-tone detection filter stage 4 biquad coefficients.	0x0400
U27	BT4B1		0x70D2
U28	BT4B2		0xC830
U29	BT4A2		0x4000
U2A	BT4A1		0x80E2
U2B	BTK	Busy-tone detection filter output scaler.	0x0009
U2C	BTON	Busy-tone detection ON threshold.	0x00A0
U2D	BTOF	Busy-tone detection OFF threshold.	0x0070
U2E	BMTT	Busy cadence minimum total time in seconds multiplied by 7200.	0x0870
U2F	BDLT	Busy cadence delta time in seconds multiplied by 7200.	0x25F8
U30	BMOT	Busy cadence minimum on time in seconds multiplied by 7200.	0x0438

SILICON LABS

Table 50. BPF Biquad Values

BPF Biquad Values	Stage 1	Stage 2	Stage 3	Stage 4	Output Scalar
310/510 (Default Busy and Dial Tone)					
A0	0x0800	0x00A0	0x00A0	0x0400	—
B1	0x0000	0x6EF1	0x78B0	0x70D2	—
B2	0x0000	0xC4F4	0xC305	0xC830	—
A2	0x0000	0xC000	0x4000	0x4000	—
A1	0x0000	0x0000	0xB50A	0x80E2	—
K	—	—	—	—	0x0009
300/480					
A0	0x0800	0x01A0	0x01A0	0x03A0	—
B1	0x0000	0x6E79	0x7905	0x7061	—
B2	0x0000	0xC548	0xC311	0xC8EF	—
A2	0x0000	0xC000	0x4000	0x4000	—
A1	0x0000	0x0000	0xA7BE	0x8128	—
K	—	—	—	—	0x0009
320/630					
A0	0x0078	0x0210	0x0330	0x0330	—
B1	0x67EF	0x79E0	0x68C0	0x7235	—
B2	0xC4FA	0xC252	0xCB6C	0xC821	—
A2	0x4000	0x4000	0x4000	0x4000	—
A1	0x0214	0x8052	0xB1DC	0x815C	—
K	—	—	—	—	0x0008
325/550					
A0	0x0100	0x0600	0x0600	0x0600	—
B1	0x71CC	0x78EF	0x69B9	0x68F7	—
B2	0xC777	0xC245	0xC9E4	0xC451	—
A2	0x4000	0x4000	0x4000	0x4000	—
A1	0x81C2	0x806E	0xAFE9	0xFCA6	—
K	—	—	—	—	0x0009
100/550					
A0	0x0800	0x01C0	0x01C0	0x01C0	—
B1	0x7DAF	0x5629	0x7E3F	0x6151	—
B2	0xC1D5	0xCF51	0xC18A	0xDC9B	—
A2	0x4000	0xC000	0x4000	0x4000	—
A1	0x8000	0x0000	0xB96A	0x8019	—

Table 50. BPF Biquad Values (Continued)

BPF Biquad Values	Stage 1	Stage 2	Stage 3	Stage 4	Output Scalar
K	—	—	—	—	0x0005
400/440					
A0	0x0020	0x0200	0x0400	0x0040	—
B1	0x7448	0x7802	0x73D5	0x75A7	—
B2	0xC0F6	0xC0CB	0xC2A4	0xC26B	—
A2	0x4000	0x4000	0x4000	0x4000	—
A1	0x96AB	0x8359	0x8D93	0x85C1	—
K	—	—	—	—	0x0008

Example: The United States specifies a busy tone "on" time from 450 to 550 ms and "off" time from 450 to 550 ms. Thus the minimum "on" and "off" times are 0.45 s each , and the maximum "on" and "off" times are 0.55 s each.

■ The busy cadence minimum on time is 0.45 s, thus BMOT = 0.45 x 7200 = 0x0CA8.

■ The busy cadence minimum total time is 0.45 s + 0.45 s = 0.9 s, thus BMTT = 0.9 x 7200 = 6480 = 0x1950.

■ The maximum total time is 0.55 s + 0.55 s = 1.1 s, thus BDLT = (1.1 – 0.9) x 7200 = 1440 = 0x05A0.

The hexadecimal values are stored in the appropriate registers using the AT:Uhh command. Detection parameters can be wider than the minimum specifications. This is often done in the modem defaults and other suggested settings so that one set of parameters can cover a broad number of different country requirements.

Maximum Cadence
TOTAL Time

Minimum ON Time
(BMOT)
(RMOT)

Minimum Cadence
TOTAL Time
(BMTT)
(RMTT)

Cadence Delta
Time (BDLT)
(RDLT)

Figure 26. Cadence Timing

SILICON LABS
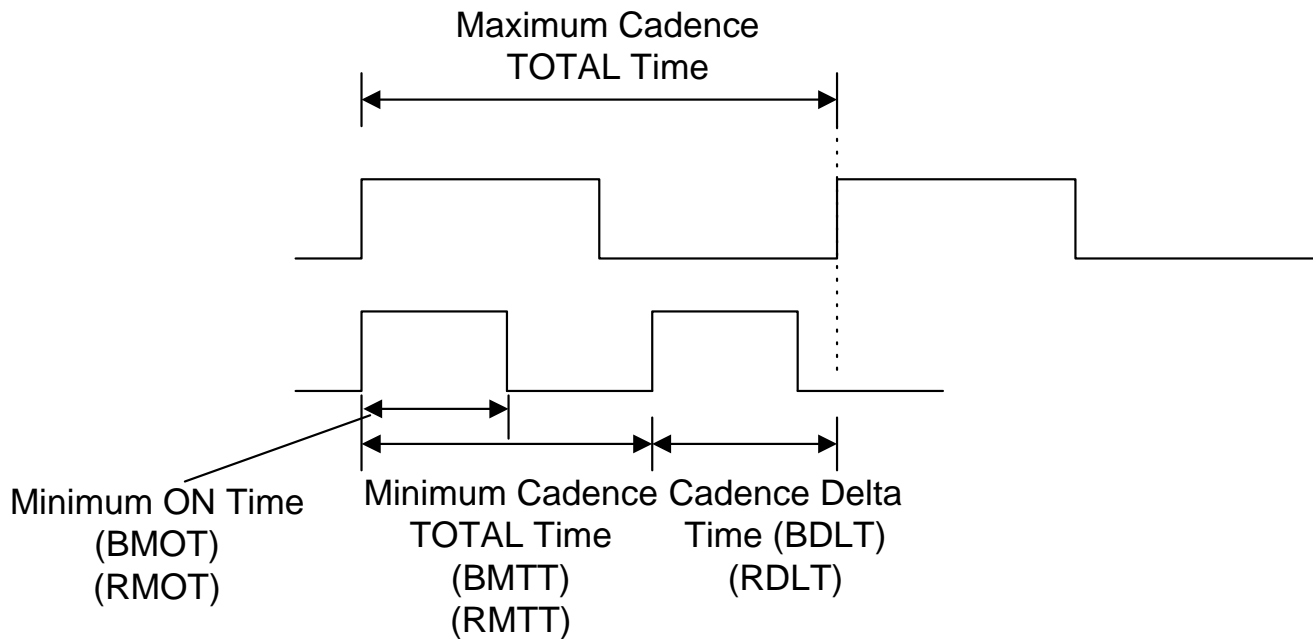
5.7.4. U31–U33 (Ringback Cadence Registers)

U31, U32, and U33 set the ringback cadence minimum total time (RMTT), ringback cadence delta time (RDLT), and ringback cadence minimum on time (RMOT) (see Table 51). Country-specific settings for ringback cadences are specified as a range for "on" time (minimum "on" and maximum "on") and a range for "off" time (minimum "off" and maximum "off"). The three values represented by RMTT, RDLT, and RMOT fully specify these ranges. RMTT, minimum total time, is equal to the minimum "on" time plus the minimum "off" time. RDLT (allowable delta) is equal to the maximum total time (maximum "on" time plus the maximum "off" time) minus the minimum total time (RMTT). RMOT is the minimum "on" time. The values stored in the registers are the hexadecimal representation of the times in seconds multiplied by 7200. Default values meet FCC requirements.

Table 51. Ringback Cadence Registers

Register	Name	Description	Default
U31	RMTT	Ringback cadence minimum total time in seconds multiplied by 7200.	0x4650
U32	RDLT	Ringback cadence delta in seconds multiplied by 7200.	0xEF10
U33	RMOT	Ringback cadence minimum on time in seconds multiplied by 7200.	0x1200

5.7.5. U34–U35 (Dial Tone Timing Register)

U34 determines the period of time the modem attempts to detect a dial tone. U35 sets the time within this window that the dial tone must be present in order to return a valid dial tone detection. The value stored in U35 is the hexadecimal representation of the time in seconds multiplied by 7200.

The value in U34 is the hexadecimal representation of the time in seconds multiplied by 1000. The time window represented in U34 must be larger than the dial tone present time represented in register U35 (see Table 52).

Table 52. Dial Tone Timing Register

Register	Name	Description	Default
U34	DTWD	Window to look for dial tone in seconds multiplied by 1000	0x1B58
U35	DMOT	Minimum dial tone on time in seconds multiplied by 7200	0x2D00

5.7.6. U37–U45 (Pulse Dial Registers)

Registers U37–U40 set the number of pulses to dial digits 0 through 9, respectively (see Table 53). The values are entered in hexadecimal format with digit 0 having a default setting of 0x000A (10 decimal) pulses, digit 1 having a default setting of one pulse, digit 2 having a default setting of two pulses, etc. This pulse arrangement is used throughout most of the world. There are, however, two exceptions—New Zealand and Sweden. New Zealand requires 10 pulses for 0, nine pulses for 1, eight pulses for 2, etc. Sweden, on the other hand, requires one pulse for 0, two pulses for 1, etc. Complete information is provided in "6.2. Country-Dependent Setup" on page 133.

U42, U43, and U45 set the pulse dial break time (PDBT), make time (PDMT), and interdigit delay time (PDIT), respectively. The values are entered in hexadecimal format and represent milliseconds. The default values meet FCC requirements. The default dialing speed is 10 pps. See "6.2. Country-Dependent Setup" on page 133 for Japanese 20 pps dialing configuration.

Table 53. Pulse Dial Registers

Register	Name	Description	Default
U37	PD0	Number of pulses to dial 0.	0x000A
U38	PD1	Number of pulses to dial 1.	0x0001
U39	PD2	Number of pulses to dial 2.	0x0002
U3A	PD3	Number of pulses to dial 3.	0x0003
U3B	PD4	Number of pulses to dial 4.	0x0004
U3C	PD5	Number of pulses to dial 5.	0x0005
U3D	PD6	Number of pulses to dial 6.	0x0006
U3E	PD7	Number of pulses to dial 7.	0x0007
U3F	PD8	Number of pulses to dial 8.	0x0008
U40	PD9	Number of pulses to dial 9.	0x0009
U42	PDBT	Pulse dial break time (ms units).	0x003D
U43	PDMT	Pulse dial make time (ms units).	0x0027
U45	PDIT	Pulse dial interdigit time (ms units).	0x0320

5.7.7. U46–U48 (DTMF Dial Registers)

U46–U48 set the DTMF power level, DTMF "on" time, and DTMF "off" time, respectively (see Table 54). The DTMF power levels are set in register U46 as a 16-bit value with the format 0x0HL0, where H is a hexadecimal number (0–F) for the dBm level of the high-frequency DTMF tone, and L is a hexadecimal number (0–F) for the dBm level of the low-frequency DTMF tone. The power level is specified in –1 dB units. The DTMF output level is 0 dBm for each tone if U46 = 0x0000 and –15 dBm if U46 = 0x0FF0. The default power level is –9 dBm for the high tone and –11 dBm for the low tone.

U47 and U48 set the DTMF "on" time (DTNT) and "off" time (DTFT) respectively as hexadecimal values in milliseconds. The default value for both U47 and U48 is 100 ms, and the range of values is 0–1000 ms.

Table 54. DTMF Dial Registers

Register	Name	Description	Default
U46	DTPL	DTMF power level	0x09B0
U47	DTNT	DTMF "on" time (ms units).	0x0064
U48	DTFT	DTMF "off" time (ms units).	0x0064

5.7.8. U49–U4C (Ring Detect Registers)

U49, U4A, U4B, and U4C set a representation of the maximum ring frequency, the difference between the highest and lowest valid ring frequency, minimum ring "on" time, and maximum ring cadence time (time on plus time off), respectively. U49 is set as the hexadecimal equivalent of 2400 divided by the highest valid ring frequency in Hz.

U4A is set as the hexadecimal equivalent of 2400 divided by the minimum valid ring frequency in Hz minus 2400 divided by the maximum valid ring frequency in Hz.

U4B and U4C are set as the hexadecimal equivalents of the times in seconds multiplied by 2400. The default high ring frequency, RGFH (U49), is 70.6 Hz. The default ring cadence minimum on time, RGMN, is 250 ms. The default ring cadence maximum total time is 11 seconds.

Table 55. Ring Detect Registers

Register	Name	Description	Default
U49	RGFH	Ring frequency high (2400/maximum valid ring frequency in Hz).	0x0022
U4A	RGFD	Ring frequency delta (2400/minimum valid ring frequency in Hz) – (2400/maximum valid ring frequency in Hz).	0x007A
U4B	RGMN	Ring cadence minimum "on" time in seconds multiplied by 2400.	0x0258
U4C	RGNX	Ring cadence maximum total time in seconds multiplied by 2400.	0x6720

5.7.9. U4D (Modem Control Register 1—MOD1)

U4D is a bit-mapped register that controls various telephony functions, including the enabling of calling and guard tones and loop current verification prior to dialing. All bits in this register are read/write, except for bits, 15, 13, 9, 6, 2, and 0, which are reserved. These bits must not be written with a logic 1, and reading them returns a value of 0 (see Table 56).

Bit 14 (TOCT) = 0 (default) turns off the calling tone after answer tone detection and allows the calling-tone cadence to complete before proceeding with the connect sequence (per V.25). TOCT = 1 turns off the calling tone 200 ms after answer-tone detection begins.

Bit 12 (NHFP) = 0 (default) disables hook-flash during pulse dialing (ignores & and ! dial modifiers). NHFP = 1 enables hook-flash during pulse dialing.

Bit 11 (NHFD) = 0 (default) disables hook-flash during dial string (tone or pulse). NHFD = 1 enables hook-flash during (tone or pulse) dial string.

Bit 10 (CLPD) = 0 (default) Modem ignores loop current prior to dialing. If CLPD = 1, modem measures loop current prior to dialing. This bit is used in conjunction with the loop-current debouncing registers, U50 and U51 (LCDN and LCDF), and U4D bit 1 (LLC). U50 provides a delay between the modem going off-hook and the loop current measurement. The delay allows the loop current to stabilize prior to the measurement. Some countries require the presence of loop current prior to dialing.

Bit 8 (FTP) = 0 (default) allows mixing tone and pulse dialing in a single AT command. FTP = 1 forces the first dialing mode encountered (tone or pulse) for the entire AT command.

Bit 7 (SPDM) = 0 (default) causes the modem to pulse dial if an ATDP command is given. If this bit is set to 1 the pulse dial modifier, P, is ignored, and the dial command is carried out as a tone dial (ATDT).

Bit 5 (GT18) = 0 (default) disables the 1800 Hz guard tone. GT18 = 1 enables the 1800 Hz guard tone.

Bit 4 (GT55) = 0 (default) disables the 550 Hz guard tone. GT55 = 1 enables the 550 Hz guard tone.

Bit 3 (CTE) = 0 (default) disables and CTE = 1 enables the calling tone referred to in bit 14 (TOCT). The calling tone is a 1300 Hz tone in originate mode with a 0.5–0.7 sec on/1.5–2.0 sec off cadence as described in V.25.

Table 56. Register U4D Bit Map

Bit	Name	Function
15	Reserved	Read returns zero.
14	TOCT	**Turn Off Calling Tone.** **0 = Disable.** 1 = Enable.
13	Reserved	Read returns zero.
12	NHFP	**No Hook-Flash Pulse.** **0 = Disable.** 1 = Enable.
11	NHFD	**No Hook-Flash Dial.** **0 = Disable.** 1 = Enable.
10	CLPD	**Check Loop Current Before Dialing.** **0 = Ignore.** 1 = Check.
9	Reserved	Read returns zero.
8	FTP	**Force Tone or Pulse.** **0 = Disable.** 1 = Enable.
7	SPDM	**Skip Pulse Dial Modifier.** **0 = No.** 1 = Yes.
6	Reserved	Read returns zero.
5	GT18	**1800 Hz Guard Tone Enable (UK Guard Tone)** **0 = Disable.** 1 = Enable.
4	GT55	**550 Hz Guard Tone Enable.** **0 = Disable.** 1 = Enable.
3	CTE	**Calling Tone Enable.** **0 = Disable.** 1 = Enable.
2	Reserved	Read returns zero.
1	Reserved	Read returns zero.
0	Reserved	Read returns zero.

SILICON LABS

5.7.10. U4E (Pre-Dial Delay Time Register)

U4E sets the delay time between the ATD command carriage return and when the modem goes off-hook and starts dialing (either tone or pulse—see Table 57). This delay establishes the minimum time the modem must be on-hook prior to going off-hook and dialing. France, Sweden, Switzerland, and Japan have minimum on-hook time requirements. The value stored in U4E is the desired delay in milliseconds minus 100 ms. The 100 ms offset is due to a delay inherent in the dialing algorithm. "6.2. Country-Dependent Setup" on page 133 contains information about country-specific values for this register.

5.7.11. U4F (Flash Hook Time Register)

U4F sets the time the modem goes on-hook as a result of a "!" or "&" dial modifier (flash hook). The value is stored in the register in milliseconds (see Table 58).

5.7.12. U50–U51 (Loop Current Debouncing Registers)

U50 (LCDN) sets the loop-current debouncing "on" time, and U51 (LCDF) sets the loop current debouncing "off" time (see Table 59). Loop-current debounce is used in cases where the presence or absence of loop current must be determined prior to taking some action. For example, it may be necessary to verify the presence of loop current prior to dialing. The loop current debounce on-time, LCDN, is used to program a delay in measuring loop current after the modem goes off-hook to ensure the loop current is stable prior to the measurement. LCDN is used in conjunction with U4D [10] (CLPD) and U4D [0] (LCN). Loop current debounce off-time, LCDF, is used in conjunction with LCN to delay the modem going on-hook if loop current is interrupted during a connection. The values are stored in the registers in milliseconds. The default value for LCDN is 350 ms. The default value for LCDF is 200 ms. The range of values for both registers is 0–65535 ms.

5.7.13. U52 (Transmit Level Register)

U52 (XMTL) adjusts the modem transmit level referred to a 600 Ω line (see Table 60). The default value of 0x0000 results in a –9.85 dBm transmit level. U52 can be used to decrease this level in –1 dBm steps approximately to the minimum modem receive threshold of –48 dBm with a register value of 0x0026.

Table 57. Pre-Dial Delay Timer Register

Register	Name	Description	Default
U4E	PRDD	Pre-dial delay-time after ATD command that modem waits to dial (ms units). The ISOmodem stays on-hook during this time.	0x0000

Table 58. Flash Hook Time Register

Register	Name	Description	Default
U4F	FHT	Flash hook time (ms units).	0x01F4

Table 59. Loop Current Debounce Registers

Register	Name	Description	Default
U50	LCDN	Loop-current debouncing "on" time (ms units).	0x015E
U51	LCDF	Loop-current debouncing "off" time (ms units).	0x00C8

Table 60. Transmit Level Register

Register	Name	Description	Default
U52	XMTL	Transmit level adjust (–1 dB units).	0x0000

5.7.14. U53 (Modem Control Register 2)

U53 (MOD2) is a bit-mapped register with all bits, except bit 15, reserved (see Table 61). The AT&H11 command sets the V.23 1200/75 bps mode. Bit 15 (REV) is used to enable V.23 reversing. This bit is set to 0 (disable reversing) by default. Setting this bit to 1 enables reversing transmit and receive speeds. Reversing is initiated by the modem in the "origination mode" (low speed TX and high speed RX). U53 resets to 0x0000 with a power-on or manual reset.

5.7.15. U54 (Calibration Timing Register)

U54 (CALT) sets the time between off-hook and DAA calibration if timed calibration is enabled with the TCAL bit (U7D, bit 12). The OHCT bits (15:8) control this timing in 32 ms units.

5.7.16. U62–U66 (DAA Control Registers)

U62 (DAAC1) is a bit-mapped register with only bits 1, 2, and 8 available. All other bits in this register are reserved and must be set according to Table 63. U62 resets to 0x0804 with a power-on or manual reset.

Bit 1 (DL) = 1 or 0 causes digital loopback to occur beyond the isolation capacitor interface out to and including the analog hybrid circuit. Setting bit 1 high enables digital loopback across the isolation barrier only. This setting is used in conjunction with the AT&H and AT&T3 commands. DL must be set low for normal operation.

Bit 2 (FOH) controls when automatic Si3018/10 calibration takes place.

Table 61. U53 Bit Map

Bit	Name	Function
15	REV	**V.23 Reversing.** **0** = **Disable.** 1 = Enable.
14:0	Reserved	Read returns zero.

Table 62. U54 Bit Map

Bit	Name	Function
15:8	OHCT	Off-hook to calibration timing in 32 ms units. If enabled with TCAL (U7D bit 12), this value controls the time between off-hook and DAA calibration.
7:0	Reserved	Must be set to zero.

Table 63. U62 Bit Map

Bit	Name	Function
15:12	Reserved	Must be set to zero.
11	Reserved	Must be set to one.
10:9	Reserved	Must be set to zero.
8	OHS2	**On-Hook Speed 2** This bit, in combination with the OHS bit and the SQ[1:0] bits on-hook speeds specified are measured from the time the OH bit is cleared until loop current equals zero. **OHS OHS2 SQ[1:0] Mean On-Hook Speed** 0 0 00 Less than 0.5 ms 0 1 00 3 ms ±10% (meets ETSI standard) 1 X 11 26 ms ±10% (meets Australia spark quenching spec) **Note:** The +GCI command *does not* modify OHS2, SQ[1:0].
7	Full 1	**0 = Disable** 1 = Enable. +3.2 dBm maximum into 600 Ω (Si3018 only)
6:5	Reserved	Must be set to zero.

SILICON LABS

Table 63. U62 Bit Map (Continued)

4	Reserved	Must be set to zero.
3	Reserved	Must be set to zero.
2	FOH	0 = Automatic calibration timer set to 426 ms. **1 = Automatic calibration timer set to 106 ms.**
1	DL	**0 = Digital loopback beyond ISOcap interface.** 1 = Digital loopback across ISOcap interface only.
0	Reserved	Must be set to zero.

U63 (DAAC2) is a bit-mapped register with bits 3:0 reserved and should be modified through a read-modify-write operation.

Bits 15:8 (LCS) function as an 8-bit unsigned measure of off-hook loop current with a resolution of 1.1 mA/bit.

Bits 7:4 (ACT) set the ac termination the Si3010/Si3018 presents to Tip and Ring. The ac impedance setting is dictated by the certification requirements for the country in which the modem is used.

Table 64. U63 Bit Map

Bit	Name	Function
15:8	LCS	Off-hook loop current (1.1 mA/bit).

7:4	ACT	**AC Termination Select**
		  ACT AC Termination
		    0000 **Real 600 Ω**
		    0011 220 Ω + (820 Ω ‖ 120 nF) and 220 Ω + (820 Ω ‖ 115 nF)
		    0100 370 Ω + (620 Ω ‖ 310 nF)
		    1111 Global complex impedance

3:0	Reserved	Read returns 0011.

U65 (DAAC4) is a bit-mapped register with bits 3:0, 12:5, and 15 reserved. Bits 1:0 and 6:5 must not be changed.

Bit 14 (PWMG) = 0 (default) provides 0 dB gain to AOUT. PWMG = 1 provides a 6 dB gain to AOUT.

Bit 13 (PDN) = 0 enables the device for normal operation. PDN = 1 completely powers down both the Si3018/10 and the Si24xx chips. The bit takes effect at the carriage return of the AT command setting this bit high. Once this bit is set, the modem must be reset via the RESET pin to become active. When reset, the modem reverts to the default settings.

Bit 4 (PDL) = 0 (default) enables the device for normal operation. PDL = 1 powers the Si3018/10 down. This is a test mode typically used for board-level debugging, not normal modem operation.

U65 resets to 0x00E0 with a power-on or manual reset.

Table 65. U65 Bit Map

Bit	Name	Function
15	Reserved	Read returns zero.
14	PWMG	**PWM gain.** **0 = No gain.** 1 = 6 dB gain applied to AOUT.
13	PDN	**Power Down.** **0 = Normal.** 1 = Power Down.

Table 65. U65 Bit Map (Continued)

12:7	Reserved	Read returns zero.
6:5	Reserved	Do not change (use read-modify-write).
4	PDL	**Line-Side Chip Power Down.** **0** = **Normal operation.** 1 = Places the Si3018/10 in Power-Down mode.
3:2	Reserved	Read returns zero.
1:0	Reserved	Do not change (use read-modify-write).

U66 (DAAC5) is a bit-mapped register with all bits except bit 6 reserved (see Table 66).

Bit 6 (FDT) is a read-only bit that reports whether or not an isolation capacitor frame lock is established. FDT is typically used for board-level debugging and is not used during normal modem operation.

U66 resets to 0xXX40 with a power-on or manual reset assuming framelock is established. The upper byte is variable.

5.7.17. U67–U6A (International Configuration Registers)

International Configuration Registers include U67 through U6A. These are bit-mapped registers that control international configuration settings, such as dc and ac termination, ringer impedance and detection, current limit, and billing tone protection.

U67 is a bit-mapped register with bits 5:4, 8, 11:10, and 15:14 reserved (see Table 67). U67 resets to 0x0008 with a power-on or manual reset.

Bit 7 (DCR) is used to set the dc line termination of the modem. DCR = 0 is the normal mode of operation with dc impedance selected by U67 [3:2] (DCV).

When DCR = 1, the device presents a dc line impedance of 800 Ω, which can be used to enhance operation with a parallel phone, for improved low line voltage performance, and for overload. **This bit must be set to 0 when the modem is on-hook.** See "6.2.1. DC Termination" on page 133 for details.

Bit 6 (OHS) is used to control the speed with which the modem drops the line. The default setting, OHS = 0, causes the modem to go from the off-hook state (drawing loop current) to the on-hook state (not drawing loop current) quickly. This operation is acceptable in many countries. However, some countries, such as Italy, South Africa, and Australia, have spark quenching requirements. Spark quenching can be accomplished by placing a resistor and a capacitor across the hookswitch or by controlling the off-hook to on-hook transition speed to prevent excessive voltage buildup. Slowly reducing the loop current to zero fulfills the spark quenching requirement without the extra components. Setting OHS = 1 causes the hookswitch to turn off the loop current with a ramp instead of a step.

Bits 3:2 (DCV) select the dc termination for the modem. DCV = 00 is the lowest voltage mode supported on the ISOmodem. DCV = 01 is the next lowest voltage mode. See "6.2.1. DC Termination" on page 133 for details.

Bit 1 (RZ) = 0 (default) allows ringer impedance to be determined by external components. This impedance is typically 800–900 kΩ. RZ = 1 enables on-chip synthesis of a lower ringer impedance for countries, such as Poland, South Africa, and South Korea.

Bit 0 (RT), Ring Threshold, is used to satisfy various country ring detect requirements. RT = 0 (default) sets the ring threshold for 11–22 V_{RMS}. RT = 1 sets the ring threshold for 17–33 V_{RMS}. Signals below the lower level of the range are not detected. Signals above the upper level of the range are always detected.

Table 66. U66 Bit Map

Bit	Name	Function
15:7	Reserved	Read returns zero.
6	FDT	**Frame Detect.** 0 = ISOcap frame lock not established 1 = ISOcap frame lock established
5:0	Reserved	Read returns zero.

Table 67. U67 Bit Map*

Bit	Name	Function
15:14	Reserved	Read returns zero.
13:12	MINI[1:0]	**Minimum Operational Loop Current.** Adjusts the minimum loop current at which the DAA can operate. Increasing the minimum operational loop current can improve signal headroom at lower Tip-Ring voltages. **MINI[1:0]　　Min Loop Current** **00　　　　　　10 mA** 01　　　　　　12 mA 10　　　　　　14 mA 11　　　　　　16 mA
11:10	Reserved	Read returns zero
9	ILIM	**Current Limiting Enable.** **0 = Current limiting mode disabled.** 1 = Current limiting mode enabled. This mode limits loop current to a maximum of 60 mA per the legacy TBR21 standard.
8	Reserved	Read returns zero.
7	DCR	**DC Impedance Selection.** **0 = 50 Ω dc termination slope is selected. This mode should be used for all standard applications.** 1 = 800 Ω dc termination is selected.
6	OHS	**On-Hook Speed.** See OHS2.
5:4	Reserved	Read returns zero.
3:2	DCV[1:0]	**Tip-Ring Voltage Adjust.** These bits adjust the voltage on the DCT pin of the line-side device, which affects the Tip-Ring voltage on the line. Low-voltage countries should use a lower Tip-Ring voltage. Raising the Tip-Ring voltage can improve signal headroom. **DCV[1:0]　　DCT Pin Voltage** 00　　　　　　3.1 V 01　　　　　　3.2 V **10　　　　　　3.35 V** 11　　　　　　3.5 V
1	RZ	**Ringer Impedance.** **0 = Maximum (high) ringer impedance.** 1 = Synthesize ringer impedance. C15, R14, Z2, and Z3 must not be installed when setting this bit.

Table 67. U67 Bit Map* (Continued)

Bit	Name	Function
0	RT	**Ringer Threshold Select.** Used to satisfy country requirements on ring detection. Signals below the lower level do not generate a ring detection; signals above the upper level are guaranteed to generate a ring detection. **0 = 11 to 22 V$_{rms}$.** 1 = 17 to 33 V$_{rms}$.

U68 is a bit-mapped register with bits 15:3 reserved. Reading these bits returns zero. Bits 4 and 2:0 are all read/write (see Table 68).

Bit 2 (BTE) = 0 (default) is disabled by default. When BTE = 1, the DAA automatically responds to a collapse of the line-derived power supply during a billing tone event. When off-hook, if BTE = 1 and BTD goes high, the dc termination is increased to 800 Ω to reduce loop current. If BTE and U70 [9] (RIM) are set to 1, an interrupt from U70 [1] (RI) also occurs when BTD goes to 1 (high).

Bit 1 (ROV) is normally 0 and is set to 1 to report an excessive receive input level. ROV is cleared by writing it to 0.

Bit 0 (BTD) = 0 normally but is set to 1 if a billing tone is detected. BTD is cleared by writing a 0 to BTD.

U68 resets to 0x0000 with a power-on or manual reset.

U6A is a bit-mapped register with bits 15:3 and 1:0 reserved. Reading these bits returns zero. Bit 2 is read-only (See Table 69).

Bit 2 (OVL) is a read-only bit that detects a receive overload. This bit is similar to U68 [1] (ROV) except OVL clears itself after the overload condition is removed.

Table 68. U68 Bit Map*

Bit	Name	Function
15:8	Reserved	Read returns zero.
7:3	Reserved	Do not modify.
2	BTE	**Billing Tone Protect Enable.** **0** = **Disabled.** 1 = Enabled.
1	ROV	**Receive Overload.** **0** = **Normal receive input level.** 1 = Excessive receive input level.
0	BTD	**Billing Tone Detected.** **0** = **No billing tone.** 1 = Billing tone detected (cleared by writing 0).

SILICON LABS

Table 69. U6A Bit Map*

Bit	Name	Function
15	Reserved	Read returns zero.
14	SQ1	Spark quenching. See OHS2.
13	Reserved	Read returns zero.
12	SQ0	Spark quenching. See OHS2.
11:3	Reserved	Read returns zero.
2	OVL	Overload Detected. This bit has the same function as ROV, but clears itself after the overload has been removed. This bit is only masked by the off-hook counter and is not affected by the BTE bit.
1	Reserved	Read only; value indeterminate.
0	Reserved	Read returns zero.

5.7.18. U6C (Line-Voltage Status Register)

U6C contains the line voltage status register, LVS, and resets to 0xXX00. Bits 7:0 are reserved, and a read returns zero.

5.7.19. U6E–U7D (Modem Control and Interface Registers)

Modem Control and Interface registers include registers U6E, U70–U71, and U76–U79. These are bit-mapped registers that control functions including TX/RX gain, clocking, I/O, SSI codecs, intrusion detection, and LVCS (line voltage current sense).

U6E controls the clockout divider. Bits 15:13 and 7:0 are reserved. U6E resets to 0x1FA0 with a power-on or manual reset (see Table 71).

Bits[12:8] (R1) control the R1 clockout divider. A 196.608 MHz clock signal passes through a divide-by (R_1+1) circuit to derive the CLKOUT signal. If R1 = 00000, CLKOUT is disabled. R1 is set at a default value of 11111, which results in CLKOUT = 2.048 MHz. The CLKOUT adjustment range ($15 \leq$ R1 ≤ 30) is 12.288 MHz to 6.342194 MHz.

U6F contains the parallel/SPI port receive FIFO interrupt timer and resets to 0x00FF.

Bits [15:8] are reserved and should not be written to any value other than 0.

Bits[7:0] set the period of an internal timer that is reset whenever the parallel or SPI port receive FIFO (Hardware Interface Register 0) is read. If the internal timer expires with data in the receive FIFO, an interrupt is generated regardless of the state of RXF (Hardware Interface Register 1 bit 7). This ensures that the host always removes all receive data from the parallel or SPI port receive FIFO even if RXF is not set.

Table 70. U6C Bit Map

Bit	Name	Function
15:8	LVS[7:0]	**Line Voltage Status.** Eight-bit signed, two's complement number representing the on-hook or off-hook tip-ring voltage. Each bit represents 1 V. Polarity of the voltage is represented by the MSB (sign bit). A value of zero indicates a measured voltage of less than 3 V.
7:3	Reserved	Read returns zero.
2:0	RXG[2:0]	Global Receive Gain in dB (Default = 000b).

Table 71. U6E Bit Map

Bit	Name	Function
15:13	Reserved	Do not modify.
12:8	R1	CLKOUT Divider (Default = 11111b)
7:5	Reserved	Read returns 101b. Do not modify.
4	HRS	Hardware Reset 0 = Normal operation. 1 = Device will perform hardware reset. All registers will return to default settings.
3:0	Reserved	Read returns 0. Do not modify.

Table 72. U6F Bit Map

Bit	Name	Function
15:8	Reserved	Do not modify
7:0	PTMR	Parallel/SPI Port Receive FIFO Interrupt Timer (in milliseconds)

U70 controls escape and several indicator and detector masks and provides several read-only status bits (see Table 73). Bits 5, 6, 7, and 14 are reserved.

Bits 4:0 are read only, and bits 15 and 13:8 are read/write. U70 resets to 0x2700 with a power-on or manual reset.

Bit 15 (HES) = 0 (default) disables the hardware escape pin.

Setting HES = 1 enables ESC. When ESC is enabled, escape from the data mode to the command mode occurs at the rising edge of the ESC pin. Multiple escape options can be enabled simultaneously.

For example, U70 [13] (TES) = 1 by default, which enables the +++ escape. If HES is also set (HES = 1), either escape method works. Additionally, the 9th bit escape can also be enabled with the AT\B6 command or through autobaud.

Bit 13 (TES) = 1 (default) enables the standard +++ escape sequence. To successfully escape from data mode to command mode using +++, there must be no UART, parallel or SPI activity (depending on the interface mode) for a guard period determined by register S12, both before and after the +++. S12 can be set for a period ranging from 200 ms to 5.1 seconds.

Bit 12 (CIDM) = 0 (default) prevents a change in U70 [4] (CID), Caller ID, from triggering an interrupt. If CIDM = 1, an interrupt is triggered with a low-to-high transition on CID.

Bit 11 (OCDM) = 0 (default), an interrupt is not triggered with a change in OCD. If OCDM = 1, a low-to-high transition on U70 [3] (OCD), overcurrent detect, triggers an interrupt. This bit must be set for Australia and Brazil.

Bit 10 (PPDM) = 1 (default) causes a low-to-high transition in U70 [2] (PPD), parallel phone detect, to trigger an interrupt. If PPDM = 0, an interrupt is not triggered with a change in PPD.

Bit 9 (RIM) = 1 (default) causes a low-to-high transition in U70 [1] (RI), ring indicator, to trigger an interrupt. If RIM = 0, an interrupt is not triggered with a change in RI.

Bit 8 (DCDM) = 1 (default) causes a high-to-low transition in U70 [0] (DCD), data carrier detect, to trigger an interrupt. If DCDM = 0, an interrupt is not triggered with a change in DCD.

Bits 4:0 are the event indicators described below. All are "sticky" (i.e., remain high after the event) and are cleared upon an interrupt read command (AT:I).

SILICON LABS

Table 73. U70 Bit Map

Bit	Name	Function
15	HES	**Enable Hardware Escape Pin.** **0 = Disable.** 1 = Enable.
14	Reserved	Read returns zero.
13	TES	**Enable Escape (+++).** 0 = Disable. **1 = Enable.**
12	CIDM	**Caller ID Mask.** **0 = Change in CID does not affect INT.** 1 = CID low-to-high transition triggers INT.
11	OCDM	**Overcurrent Detect Mask.** **0 = Change in OCD does not affect INT.** **("X" result code is not generated in command mode.)** 1 = OCD low-to-high transition triggers INT. ("X" result code is generated in command mode.)
10	PPDM	**Parallel Phone Detect Mask.** 0 = Change in PPD does not affect INT. **1 = PPD low-to-high transition triggers INT.**
9	RIM	**Ring Indicator Mask.** 0 = Change in RI does not affect INT. **1 = RI low-to-high transition triggers INT.**
8	DCDM	**Data Carrier Detect Mask.** 0 = Change in DCD (U70, bit 0) does not affect INT. **1 = DCD high-to-low transition triggers INT.**
7:5	Reserved	Read returns zero.
4	CID	**Caller ID (sticky).** 1 = Caller ID preamble detected; data to follow. Clears on :I read.
3	OCD	**Overcurrent Detect (sticky).** 1 = Overcurrent condition has occurred. Clears on :I read.
2	PPD	**Parallel Phone Detect (sticky).** 1 = Parallel phone detected since last off-hook event. Clears on :I read.
1	RI	**Ring Indicator (sticky).** 1 = Ring event has occurred (ISOmodem on-hook). Clears on :I read.
0	DCD	**Data Carrier Detect (status).** 1 = carrier detected (inverse of DCD pin).

U71 IO1

Bit	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Name												COMP				PRT
Type												R/W				R/W

Reset settings = 0x0000

Bit	Name	Function
15:5	Reserved	Read returns zero.
4	COMP	**0 – Disables compression (PCM mode).** 1 – Enables linear compression.
3:1	Reserved	
0	PRT	**0 – Disables PCM mode.** 1 – Enables PCM mode.

U76 provides control for parallel phone detect (PPD) intrusion parameters including the off-hook sample rate (OHSR), absolute current level with modem off-hook (ACL), ACL update from LVCS (FACL), and the difference in current between ACL and LVCS that triggers an off-hook intrusion detection (DCL). All bits in U76 are read/write (see Table 74).

OHSR[15:9] sets the off-hook loop current sampling interval for intrusion algorithms in 40 ms units. The default value is 25 (1 s). The minimum recommended value is 5 (200 ms). The interval can be adjusted to much lower values; however, the likelihood of false intrusion detections increases sharply with intervals of less than 520 ms.

Bit 8 (FACL). If FACL = 0 (default), the ACL register is automatically updated to the LVCS value at the sampling interval determined by OHSR. This feature is used to ensure the ACL value is continuously updated. Updating ACL allows host software to determine the loop current (value returned in ACL) provided the modem is off-hook longer than the time defined by U77 (IST). Loop current on a particular line can vary over time due to a variety of factors including temperature and weather conditions. Updating ACL reduces the probability of false intrusion detection by ensuring the ACL reference reflects the most recent off-hook conditions. If FACL = 1, a value can be written into ACL by the host. This value is not updated and remains in the ACL register until overwritten by the host or until FACL is returned to 0 and updates from LVCS overwrite the stored value. Writing an initial value to ACL eliminates the possibility of the modem going off-hook for the first time simultaneously with an intrusion and storing the intrusion loop current in ACL.

Bits 7:5 (DCL) set the differential level between ACL and LVCS that triggers an off-hook PPD interrupt. DCL is adjustable in 3 mA units. The default value is 2 (6 mA).

Bits 4:0 (ACL): ACL provides a means of detecting a parallel phone intrusion during the time between the modem going off-hook and the U77 [15:12] (IST) time value. If ACL = 0, the ISOmodem has no reference and must use the loop current sample from the first off-hook event as a reference for parallel phone intrusion detection. Typically, the host sets ACL to an approximate value and FACL = 0 before the first off-hook event after powerup or reset. This allows the updated ACL value to be used for subsequent calls and eliminates a potential detection problem if an intrusion occurs simultaneously when the modem goes off-hook for the first time after a powerup or reset. If ACL = 0, it is ignored by the off-hook intrusion algorithm. A PPD interrupt is generated if U79 [4:0] (LVCS) is DCL less than ACL for two consecutive samples. The ISOmodem writes ACL with the contents of LVCS after an intrusion with the last LVCS value before the intrusion. The default value for ACL is 0.

U76 resets to 0x3240 with a power-on or manual reset (see Table 74).

SILICON LABS

Table 74. U76 Bit Map

Bit	Name	Function
15:9	OHSR	**Off-Hook Sample Rate for Intrusion Detection (40 ms units).** **(1 second default)**
8	FACL	**Force ACL.** **0 = While off-hook, ACL is automatically updated with LVCS value.** 1 = While off-hook, ACL saves previously written value.
7:5	DCL	**Differential Current Level (3 mA units, 6 mA default)**
4:0	ACL	**Absolute Current Level (3 mA units, 0 mA default)**

U77 is a bit-mapped register that controls parameters relating to intrusion detection and overcurrent detection. U77 resets to 0x401E with a power-on or manual reset (see Table 75).

Bits 15:12 (IST) set the delay between the time the modem goes off-hook and the intrusion detection algorithm begins. This register has 250 ms increments, and the default value is 4 (1 sec).

Bit 11 (HOI) determines whether the host or modem responds to an intrusion. HOI = 0 (default) prevents the modem from hanging-up in response to an intrusion without host intervention. In this case, the host monitors U70 [2] (PPD) and takes the appropriate action when PPD is asserted indicating an intrusion. If HOI = 1, the modem hangs up immediately and will not go off-hook and dial when an intrusion is detected without host intervention. If %V_N commands are set, HOI also causes the LINE IN USE result code upon PPD interrupt.

Bit 9 (AOC) = 0 (default) disables AutoOvercurrent. If enabled and an overcurrent condition is detected, the dc termination switches to 800 Ω, thus, reducing the current. If AOC = 0, the overcurrent condition is only reported by U70 [3] (OCD).

Bits 8:0 (OHT) set the delay between the time the modem goes off-hook and LVCS is read for an overcurrent condition. The default value for this register is 30 ms (see Table 75).

U78 is a bit-mapped register that controls intrusion detection blocking and intrusion suspend. U78 resets to 0x0000 with a power-on or manual reset (see Table 76).

Bits 15:14 (IB) controls intrusion blocking after dialing has begun. Table 76 defines the bit values and intrusion blocking.

Bits 7:0 (IS) set the delay between the start of dialing and the start of the intrusion algorithm when IB = 10 (see Table 76).

Table 75. U77 Bit Map

Bit	Name	Function
15:12	IST	**Intrusion Settling Time (250 ms units) 1 second default.**
11	HOI	**Hang-Up On Intrusion.** **0 = ISOmodem does not automatically hang up after an off-hook PPD interrupt.** 1 = ISOmodem automatically hangs up after an off-hook PPD interrupt.
10	Reserved	Read returns zero.
9	AOC	**AutoOvercurrent.** **0 = Disable.** 1 = Enable.
8:0	OHT[8:0]	**Off-Hook Time (1 ms units) 30 ms default.**

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Table 76. U78 Bit Map

Bit	Name	Function
15:14	IB	**Intrusion Blocking.** **00 = No intrusion blocking.** 01 = Intrusion disabled from start of dial to end of dial. 10 = Intrusion disabled from start of dial to IS register time-out. 11 = Intrusion disabled from start of dial to CONNECT XXX, NO DIALTONE, or NO CARRIER
13:8	Reserved	Read returns zero.
7:0	IS	**Intrusion Suspend (500 ms units) default = 0 ms.**

U79 is a bit-mapped register. Bits 15:6 are reserved.

Bits 5:0 represent the line voltage, loop current, or on-hook line monitor (see Table 77). While the modem is on-hook, the value in the LVCS register measures loop voltage (see Table 78). This value can be used to determine if a line is connected or if a parallel phone or other device goes off-hook or on-hook. The accuracy of the LVCS bits is ±20%. When the modem goes off-hook, the value in the LVCS register measures loop current. LVCS can indicate when a parallel phone or other device goes on-hook or off-hook and detect whether enough loop current is available for the modem to operate or if an overload condition exists.

The line voltage monitor full scale may be modified by changing R5 as follows:

$V_{MAX} = V_{MIN} + 4.2 \times (10\ M\Omega + R5 + 1.78\ k\Omega) / (R5 + 1.78\ k\Omega) / 5$

See Table 78. LVCS is backward-compatible with older ISOmodem revisions. The value is absolute and does not reflect loop polarity. See U6C (LVS) [15:8] for 1 V/bit resolution and signed, two's complement format and U63 (LCS) [15:8] for 1.1 mA/bit loop current measurement. The values for loop voltage and loop current in U79 are calculated by the modem from the values in U6C and U63 respectively.

Table 77. Monitor Mode Values

On-Hook Voltage Monitor Mode	Off-Hook Current Monitor Mode
00000 = No line connected. 00001 = Minimum line voltage (VMIN = 2.5 V ±0.5 V). 11111 = Maximum line voltage (87 V ±20%)	00000 = No loop current. 00001 = Minimum loop current. 11110 = Maximum loop current. 11111 = Overload (more than 60 mA in legacy TBR21 mode or more than 155 mA in other modes)

Table 78. U79 Bit Map

Bit	Name	Function
15:6	Reserved	Read returns zero.
5:0	LVCS	**Line Voltage Current Sense.** On-Hook = Voltage Monitor (2.75 V/bit). Off-Hook = Loop Current Monitor (3 mA/bit).

U7A is a bit-mapped register. U7A resets to 0x0000. Bits 12, 10:8, and 5:3 are reserved.

Bit 7 (DOP) is used in a method to determine whether a phone line supports DTMF or only pulse dialing. See "6.10. Pulse/Tone Dial Decision" on page 169 for details.

SILICON LABS

Bit 6 (ADD) attempts DTMF dial, then falls back to pulse dialing if unsuccessful. The first digit is dialed as DTMF. If a dial tone is still present after two seconds, this suggests that the DTMF digit was not taken into account by the central office. In that case, the ISOmodem redials the first digit and remaining digits as pulses. If a dial tone is not present after two seconds, the ISOmodem assumes that the first DTMF digit was recognized and dials the remaining digits as DTMF. However, in a typical PBX environment, where dialing a DTMF digit (typically 8 or 9) is required to obtain an outside line, this method does not give any indication that the outside line can accept TDMF dialing.

Bit 1 (HDLC) controls whether the normal asynchronous mode (default) is used or the transparent HDLC mode is enabled. See "5.14. Legacy Synchronous DCE Mode/V.80 Synchronous Access Mode" on page 125 for more details on these modes.

Bit 0 controls whether the normal ITU/Bellcore modem handshake (default) or a special fast-connect handshake is used. Fast connect is typically used in specialized applications, such as point-of-sale terminals, where it is important to connect and transfer a small amount of data rapidly (see Table 79).

Table 79. U7A Bit Map

Bit	Name	Function
15	V29FC	Enable V29 Fast Connect; used in conjunction with AT +FCLASS=1. 1 = Enable 0 = Disable
14	CNSMS	Chinese EPOS SMS enable 1 = Enable 0 = Disable
13	V29EM	Use EM shielding to change direction of half duplex V.29FC. 0 = EM shielding 1) <EM><rrn>=<0x19><0xBC> to receive a V29FC packet. 2) <EM><rtn>=<0x19><0xBD> to send a V29FC packet. 1 = RTS pin toggle.
12	Reserved	Read returns zero.
11	ARMLO	**0 = Normal operation.** 1 = Accomodate remote modem with large clock offset, such as 340 ppm. May degrade training for normal modems; enable only when necessary.
10:8	Reserved	Read returns zero.
7	DOP	**0 = Normal ATDTW operation.** 1 = Use ATDTW for pulse/tone dial detection (see "6.10. Pulse/Tone Dial Decision" on page 169 for details).
6	ADD	**Adaptive Dialing.** 1 = Enable **0 = Disable**
5	Reserved	Read returns zero.
4	NEWFC	New V.22 handshake enable. This bit is mutually exclusive with bit 0. This bit makes hard-coded U80 timing unnecessary. Without this bit, the appropriate value in U80 is required.
3:2	Reserved	Read returns zero.
*Note: When HDLC or FAST is set, the \N0 (Wire mode) setting must be used.			

SILICON LABS

Table 79. U7A Bit Map (Continued)

Bit	Name	Function
1	HDLC	**Synchronous Mode.** **0** = **Normal asynchronous mode.** 1 = Transparent HDLC mode.*
0	FAST	**Fast Connect. This bit is mutually exclusive with bit 4; only one bit can be enabled at a given time.** **0** = **Normal modem handshake timing per ITU/Bellcore standards.** 1 = Fast-connect modem handshake timing.*
*Note: When HDLC or FAST is set, the \N0 (Wire mode) setting must be used.		

U7C is a bit-mapped register with bits 15:5 and bits 3:1 reserved. U7C resets to 0x0000 with a power-on or manual reset.

Bit 4 (RIGPO) is output on RI pin when U7C [0] (RIGPOEN) = 1. This allows the $\overline{\text{RI}}$ pin to be configured as a general-purpose output pin under host processor control. **The $\overline{\text{RI}}$ pin must not pulled down. Doing so forces the modem to enter an undocumented emulation mode.**

Bit 0 (RIGPOEN)=0 (default) allows the $\overline{\text{RI}}$ pin to indicate a valid ring signal. When Bit 0 = 1, $\overline{\text{RI}}$ outputs the value of RIGPO (See Table 80).

U7D is a bit-mapped register with bits 15,13:9, and bits 8:2 reserved. U7D resets to 0x4001 with a power-on or manual reset.

Bit 14 (NLM) = 0 (default) causes the modem to automatically detect loop current absence or loss. When bit 14 = 1, this feature is disabled.

Bit 12 (TCAL) = 0 (default) when set to 1 forces the DAA to calibrate at a programmable time after going off-hook. The time between going off-hook and the start of calibration is programmed with U54 [15:8] in 32 ms units.

Bit 11 (OHCT) = 0 (default) when set to 1 forces the DAA to calibrate at the start of dialing. The first dial character should be a delay (",") to prevent interference with the first digit.

Bit 1 (ATZD) = 0 (default) allows the ATZ command to be active. When Bit 1 = 1, the ATZ command is disabled.

Bit 0 (FDP) = 0 (default). FSK data processing stops when the carrier is lost. Unprocessed data are lost. Setting Bit 0 = 1 causes FSK data processing to continue for up to two bytes of data in the pipeline after carrier is lost.

Table 80. U7C Bit Map

Bit	Name	Function
15:5	Reserved	Read returns zero.
4	RIGPO	**$\overline{\text{RI}}$ pin** Follow this bit when U7C [0] (RIGPIOEN) = 1.
3:1	Reserved	Read returns zero.
0	RIGPOEN	**0** = **$\overline{\text{RI}}$ pin indicates valid ring signal.** 1 = $\overline{\text{RI}}$ pin follows U7C [4] (RIGPO).

SILICON LABS

Table 81. U7D Bit Map

Bit	Name	Function
15	Reserved	Read returns zero.
14	NLM	Host software recommended to always set this to bit. 0 = Enables "No Loop Current" Detect. **1 = Disables "No Loop Current" Detect.**
13	Reserved	**Read returns zero.**
12	TCAL	**0 = Timed calibration disabled.** 1 = Timed calibration. The time between off-hook and calibration is set in U54 (OHCT).
11	CALD	**0 = No calibration during dial.** 1 = Calibrate during dial. It is recommended that the dial string start with "," to prevent first digit loss.
10:2	Reserved	Read returns zero.
1	ATZD	**0 = ATZ enabled.** 1 = ATZ disabled.
0	FDP	0 = FSK data processing stops when carrier is lost. **1 = FSK data processing continues for two bytes after carrier is lost.**

5.7.20. U80 (Transmit Delay for V.22 Fast Connect)

U80 controls delay parameters when the modem is in V.22 Fast Connect mode (+MS=V22, AT:U7A,3) and the server does not respond with a short answer tone prior to scrambled data or HDLC flags. U80 configures the modem to operate without these tones. Bit 15 turns this function on. After the end of dialing, the modem waits for a time set by U80 [14:0], then begins transmitting scrambled data (or HDLC Flags). The delay units are 1/600 s. For example, to command the modem to begin transmitting three seconds after the end of dialing:

3 x 600 = 1800 = 0x0708. Issue command AT:U80,8708.

This register is only used when U7A[4] = 0.

U80 XMITDEL Transmit Delay for V.22 Fast Connect

Bit	Name	Function
15	V22FCDF	**0 = Normal operation (default)** 1 = Transmit scrambled data (or HDLC flags) after delay set in bits 14 - 0
14:0	V22FCDEL	When V22FCDF = 1, V22FCDEL is the delay between end of dialing and sending scrambled data (or HDLC flags) in 1/600 s units. Default is 0x0168 (600 ms). When V22FCDEL = 0, V22FCDEL is the delay between ANS tone detected to start of training.

5.7.21. U87 (Synchronous Access Mode Configuration Register)

U87 SAM Synchronous Access Mode Configuration Options

Bit	Name	Function
15:11	Reserved	Read returns zero.
10	MINT	**Minimal Transparency** Host software must always set this bit. **0 = Generate two-byte <EM> transparency sequences.** This option will use codes <EM><T5> through <RM><T20> (if possible) for received data containing two back-to-back bytes requiring transparency (Rev C and later). 1 = Generate one-byte <EM>transparency sequences. This option will only use codes <EM><T1> through <EM><T4> for received data (Rev B and later).
9	SERM	**Special Error Reporting Mode** **0 = Ignore unrecognized in-band commands.** 1 = Generate <EM><0x45> ("E" for error) in response to any unrecognized in-band commands.
8	FSMS	**Framed Sub-Mode Startup** **0 = Upon successful connection, enter Transparent Sub-Mode.** An <EM><FLAG> is required to enter Framed Sub-Mode. 1 = Upon successful connection, immediately enter Framed Sub-Mode. The first received <EM><err> (from a successful hunt) is transformed into an <EM><flag>.
7:0	XMTT	**Transmitter Threshold** This value represents the number of bytes before a transmission is started. The following values are special: 0 The same as ten. Upon receipt of ten bytes, data are transferred. The DTE must supply a closing flag within the required time or an underrun will occur. 255 The same as infinity, e.g. never start a packet until the closing flag is received.

SILICON LABS

5.7.22. UAA (V.29 Mode Register)

UAA V.29 MODE

Bit	Name	Function
15:3	Reserved	Read returns zero.
2	RUDE	**0 = Disables rude disconnect.** 1 = Enables rude disconnect.
1	V29ENA	**0 = Disables V.29.** 1 = Enables V.29.
0	Reserved	Read returns zero.

5.7.23. UIDA Response and Answer Tone Delay Register

This register, which is reset to 0, allows the user to add a delay in increments of milliseconds to the time the modem waits before responding to an answer tone. This is useful in dealing with non-standard answering modems.

5.8. Firmware Upgrades

The Si24xx ISOmodem family contains an on-chip program ROM that includes the firmware required for the features listed in the data sheet. Additionally, the ISOmodem contains on-chip program RAM to accommodate minor changes to ROM firmware. This allows Silicon Labs to provide future firmware updates to optimize the characteristics of new modem designs and those already deployed in the field.

Firmware upgrades (patches) provided by Silicon Labs are files loaded into the ISOmodem program RAM after a reset using the AT:P command (see Table 39 on page 59). Once loaded, the upgrade status can be read using the ATI1 command to verify the firmware revision number. The entire firmware upgrade in RAM is always cleared on reset. To reload the file after reset or power down, the host processor rewrites the file using the AT:P command during post-reset initialization.

Patch files may be more than 6000 characters in some cases. They come in a .txt file containing multiple lines that are sent serially to the ISOmodem. Several patch-loading techniques can be used in different environments. See the description and Table 82. Whichever technique is used, it is suggested to do AT&T6 to verify the CRC of the loaded patch.

5.8.1. Method 1 (Fastest)

Send the entire file in quiet mode using a program that waits for a set amount of time after every line. This can result in load times as short as 0.7 seconds for a 6235-byte patch at 115 kbaud (UART interface mode). The file transfer should be preceded by ATZ or reset and followed by ATE0 and ATQ1. After the transfer, perform ATE1 and ATQ0 as needed. The delay between lines must be increased when using the parallel or SPI interface.

1. Low pulse on RESET signal for at least 5.0 ms.

2. Wait the reset-recovery time.

3. Send ATE0.

4. Wait for OK.

5. Send ATQ1 to the modem.

6. Wait 20 ms.

7. Send AT:PIC (first line of the patch).

8. Wait 20 ms.

...

(n-5) Send AT:PIC0 (last Line of Patch).

(n-4) Wait 20 ms.

(n-3) Send ATQ0 to the modem.

(n-2) Wait for OK.

(n-1) Send AT&T6 to the modem.

(n) Wait for OK.

5.8.2. Method 2

Send the entire file using a program that waits for OK after every line. This will require 3.98 seconds for a 6235 byte patch at 115 kbaud or longer if the OS has latency.

5.8.3. Method 3

For development purposes, send the entire patch file using a program that allows a timed preprogrammed pause between lines, e.g. HyperTerminal or ProComm. This will give times of around 16 seconds for a 6235 byte patch (at 115 kbaud). Due to the granularity of a typical desktop operating system, be sure to set the time delay between lines to 100 ms.

Table 82. Load Technique and Speed Table*

Start Condition	Delay Between Lines	Load time, 6235-Byte Patch, 115 kbaud UART	Approach Used With
Reset, then ATE0 and ATQ1	0.5 ms	0.694	Embedded systems
	1 ms	0.771	Embedded systems
	2 ms	0.925	Embedded systems
	5 ms	1.385	Embedded systems
	10 ms	2.152	Embedded systems
Reset	Wait for OK	3.998	Windows or embedded system where time precision is worse than 10 ms
Reset	100 ms	15.962	Windows without writing a patch loader
*Note: The delay times do not include the time to empty the UART's possibly long TX buffer. The time quoted is between the end of transmission of the last character of a line and the start of transmission of the first character of the next line.			

A CRC can be run on the upgrade file loaded into on-chip Program RAM with the AT&T6 command to verify that the upgrade was correctly written to the on-chip memory. The CRC value obtained from executing the AT&T6 command should match the CRC value provided with the upgrade code.

5.9. Escape Methods

There are four ways to escape from data mode and return to command mode once a connection is established. Three of these, +++, "9th Bit", and the "Escape Pin", allow the connection to be maintained while one or both modems are in the command mode. The fourth method is to terminate the connection. The three escape methods that maintain the connection are combined by a logical OR. For example, if +++ and the "Escape Pin" are both enabled, either returns the modem to the command mode from the data mode. In parallel or SPI mode, the escape pin is not available. Instead the system can set the ESC flag in Hardware Interface Register 1 (HIR1).

While in data mode, an escape to command mode occurs if an escape command is sampled as negated for at least 60 ms, then sampled asserted for at least 60 ms. The modem is then prepared to accept AT commands, regardless of whether OK has been sent to the host. If the modem is already in command mode, the modem does not send OK. The host should always wait for OK before entering the next command after an escape.

When making a new connection, the host must not try to escape between the connect message and the protocol message. An escape attempt in this interval may fail because the modem is not in data mode until after the protocol message. In practice, it is difficult to determine the exact boundary between command mode and data mode. The recommendation is to time the escape command 100 ms low and 100 ms high, and expect that the modem has transitioned to command mode.

SILICON LABS

The system should then flush the receive buffer 100 ms after the escape command has been removed, send AT, and wait for OK. This ensures that the modem is in command mode because OK is caused by the AT command and not by the escape command.

5.9.1. +++ Escape

The +++ escape is enabled by default and is controlled by U70 [13] (TES). There are equal guard time periods before (leading) and after (trailing) the +++ set by the register S12, during which there must be no interface (UART, SPI or parallel) activity. If this inactivity criterion is met, the ISOmodem escapes to the command mode at the end of the S12 time period following the +++. Any activity in the host interface during either the leading or trailing time period causes the ISOmodem to ignore the escape request and remain in data mode. Timing for this escape sequence is illustrated in Figure 27.

Guard Time = S12 (20 msec units)
Default Guard Time S12 = 50 (1.0 sec)
Guard Time Range = 10–255 (0.2–5.1 sec)
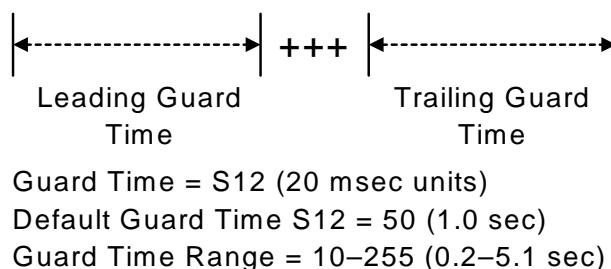
Figure 27. +++ Escape Timing

5.9.2. "9th Bit" Escape

The "9th Bit" escape mode feature is enabled by sending the AT\B6 command through autobaud, which detects a 9th bit space as "9th bit" escape mode. If this escape method is selected, a 1 detected on the ninth bit in a data word returns the modem to the command mode. The 9th bit is ignored when the modem is in the command mode. Timing for this escape sequence is illustrated in Figure 28.

UART Timing for Modem Transmit Path (9N1 Mode with 9th Bit Escape)
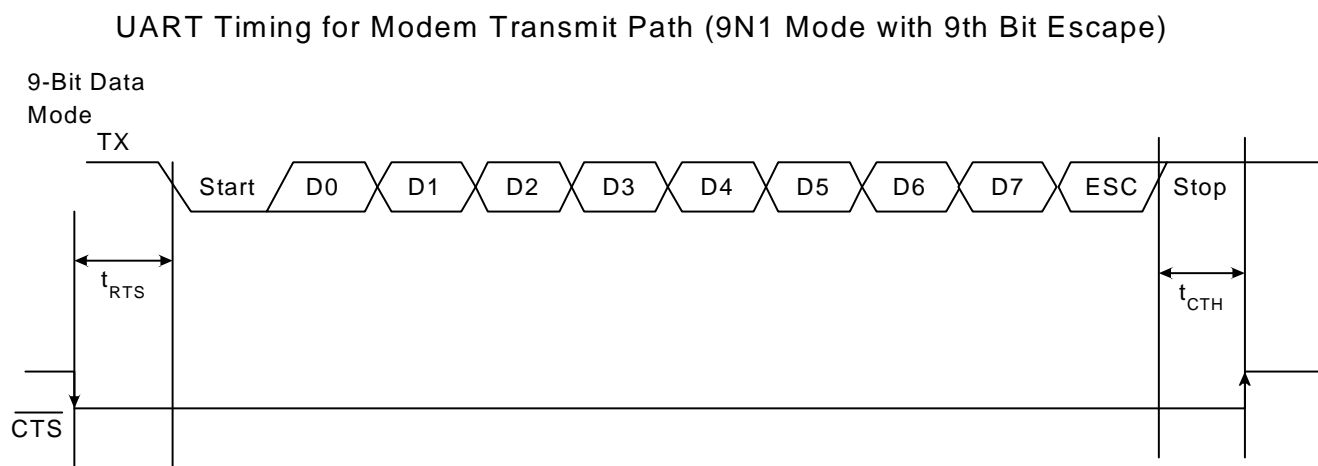
Figure 28. "9th Bit" Escape Timing

5.9.3. "Escape Pin" Escape

The "escape pin is controlled by U70 [15] (HES). This bit is 0 by default, which disables the escape pin, ESC. If HES is set to a 1, a high level on the ESC pin causes the modem to transition to the on-line command mode. The ESC pin status is polled by the processor, and there is a latency before OK is received and the modem is in command mode. The escape pin must be kept active until OK is received. In parallel or SPI interface mode, the function of the escape pin is replaced by bit 2 in Hardware Interface Register 1, described in "2.2.4.2. Hardware Interface Register 1" on page 25. Setting that bit high causes the modem to escape to the command mode.

5.10. Data Compression

The modem can achieve DTE (host-to-ISOmodem) speeds greater than the maximum DCE (modem-to-modem) speed through the use of a data-compression protocol. The compression protocols available are the ITU-T V.44, V.42bis, and MNP5 protocols. Data compression attempts to increase throughput by compressing the information to be sent before actually sending it. The modem is thus able to transmit more data in a given period of time. Table 83 details the ISOmodem error correction and data compression modes of operation.

Table 83. Enabling Error Correction/Data Compression

To Enable	Use AT Commands
V.44* V.42bis V.42 (LAPM) MNP5 MNP2–4 Wire	+DS44 (argument) \N3 and %C1 (default)
V.42 and V.42bis only	\N4 and %C1
V.42 only	\N4 and %C0
MNP2-4 only	\N2 and %C0
MNP2-5 only	\N2 and %C1
No data compression and no error correction	\N0 and %C0
*Note: V.44 is available only on Si2493.	

5.11. Error Correction

The ISOmodem can employ error correction (reliable) protocols to ensure error-free delivery of data sent between two modems. The error control methods are based on grouping data into frames with checksums determined by the contents of each frame. The receiving modem checks the frames and sends acknowledgments to the transmitting modem. When it detects a faulty frame, the receiving modem requests a retransmission. Frame length varies according to the amount of data transmitted and the number of retransmissions requested from the opposite end.

The ISOmodem supports V.42 and MNP2–4 error correction protocols. V.42 (LAPM) is most commonly used and is enabled in the \N3 and \N4 modes. In the default mode (\N3), the ISOmodem attempts to connect with V.42 error correction and V.42bis data compression (Si2457/34/15), and falls back to either V.42 only, MNP 2–5, or no error correction (wire mode) if necessary. In \N4 mode, the ISOmodem hangs up if a V.42 connection cannot be established. If the ISOmodem hangs up in V.42 mode after all data are successfully sent, the result code is OK. If the modem hangs up before all data are successfully sent, the result code is NO CARRIER. If the modem connects without a protocol, NO CARRIER is always sent.

The V.42 specification allows an alternate error correction protocol, MNP2-4. MNP2-4 is enabled in \N2 mode. In \N2 mode, the ISOmodem hangs up if an MNP2, 3, or 4 connection cannot be established.

5.12. Wire Mode

Wire mode (\N0) is used to communicate with standard, non-error-correcting modems. When optioned with \N3, the ISOmodem falls back to Wire mode if it fails in an attempt to negotiate a V.42 or MNP2-4 link with the remote modem. Error correction and data compression are not active in wire mode.

SILICON LABS

5.13. EPOS (Electronic Point of Sale) Applications

EPOS applications are discussed in "Appendix A—EPOS Applications" on page 257.

5.13.1. EPOS Fast Connect

The ISOmodem supports several fast connect modes of operation to reduce the time of a connect sequence in originate mode.

5.13.2. EPOS V.29 Fast Connect

In addition to the low modulation speed fast-connect modes, the modem (only Si2493/57/34/15) also supports a fast-connect mode based on the 9600 bps V.29 fax modulation standard. V.29 Fast Connect is available as a patch. Please contact Silicon Laboratories for additional details.

5.14. Legacy Synchronous DCE Mode/V.80 Synchronous Access Mode

The ISOmodem supports two different DTE interfaces to implement an Asynchronous DTE to Synchronous DCE conversion. Table 84 provides high-level options to choose between the Legacy Synchronous DCE Mode and the newer V.80 synchronous access mode.

Table 84. Synchronous Mode Overview

Mode	U Register	AT+ES Settings
Neither	U7A [2] = 0	+ES = D,,D
Legacy Synchronous DCE Mode	U7A [2] = 1	+ES = D,,D
Synchronous Access Mode		+ES = 6,,8

The synchronous access mode has more features than the Legacy Synchronous DCE Mode. For new designs, use of the newer synchronous access mode interface is recommended. Otherwise, existing software written with the Legacy Synchronous DCE Mode interface can still be used as long as the AT+ES command settings are not changed from the default value.

5.15. V.80 Mode

As shown in Table 85, the synchronous access mode is chosen by using the AT+ES=6,,8 command setting.

When using the synchronous access mode, it is expected that the AT\N0 command will be used to disable all other error correction protocols that may interfere with V.80 synchronous access mode operation.

The V.80 Mode has two distinct submodes. Switching between these two submodes can be accomplished within the confines of the same connection through the use of In-Band commands. The submodes are:

- Transparent Submode
- Framed Submode

The Transparent Submode creates a direct bit-by-bit translation from the DTE to and from the DCE. Any application that requires a method of reconstructing a serial bit-stream at the DCE can use the Transparent Submode.

The Framed Sub-mode represents data at the DCE in HDLC/SDLC frames. This submode is typically used in point-of-sale terminals. A common feature used in conjunction with the Framed Submode is the use of the 16-bit CRC. When used with the CRC option, the Framed Submode can be used in the same applications currently using the Legacy Synchronous DCE Mode.

Prior to sending the ATDT to establish a synchronous access mode connection, the following commands and registers require initialization: +MS, +ES, +ESA, +ITF, +IFC, U87, and U7A.

As an example, the closest equivalent to the Legacy Synchronous DCE Mode is the following initialization setting.

With either Synchronous Access Submode, once a connection has been established, payload data are multiplexed with command/indicator information by use of <EM> shielding. With <EM> shielding, either of the two bytes <0x19> or <0x99> (used to represent <EM>) precedes a special command or special indicator.

Synchronous access mode <EM> shielding is designed to support XON/XOFF handshaking. As such, the bytes 0x13 and 0x11 (XON/XOFF) are considered to be special characters in the same way the 0x19 and 0x99 bytes, used for <EM>, are special.

Since the payload data are multiplexed with <EM> shielded command/indicator and possibly XON/XOFF characters, Transparency <EM> codes are defined for the purpose of allowing the host software to send 0x13, 0x11, 0x19 and 0x99 bytes to/from the DCE. For example, if one <0x99> character needs to be sent as payload, the host software sends <EM><0x76> instead. For a complete list <EM> commands and statuses, see Table 86.

Table 85. Synchronous Access Mode Settings

AT\N0	Required to disable MNP,V.42 and other protocols
AT+ES = 6,,8	Enable synchronous access mode on originate or answer
AT+ESA = 0,0,0,,1,0	Send Abort on underrun/overrun in Framed Submode. Enable CRC generation and checking.
AT+IFC = 2,2	CTS/RTS Flow Control
AT+ITF = 0383,0128	Controls CTS Flow Control Threshold. CTS off at 383 bytes, CTS On at 128 bytes.
AT:U87,050A	Direct to Framed Sub-mode upon connection. DCE starts to transmit upon receipt of 10 bytes from the DTE.

SILICON LABS

Table 86. EM In-Band Commands and Statuses

Command–Indicator pair	Hex Code	Transmit Direction	Receive Direction	Supported in Transparent Submode	Supported in Framed Submode
<EM><t1>	0x5C	Transmit one 0x19 byte	Received one 0x19 byte	Yes[1]	Yes[1]
<EM><t2>	0x76	Transmit one 0x99 byte	Received one 0x99 byte	Yes[1]	Yes[1]
<EM><t3>	0xA0	Transmit one 0x11 byte	Received one 0x11 byte	Yes[1]	Yes[1]
<EM><t4>	0xA1	Transmit one 0x13 byte	Received one 0x13 byte	Yes[1]	Yes[1]
<EM><t5>	0x5D	Transmit two 0x19 bytes	Received two 0x19 bytes	Yes	Yes
<EM><t6>	0x77	Transmit two 0x99 bytes	Received two 0x99 bytes	Yes	Yes
<EM><t7>	0xA2	Transmit two 0x11 bytes	Received two 0x11 bytes	Yes	Yes
<EM><t8>	0xA3	Transmit two 0x13 bytes	Received two 0x13 bytes	Yes	Yes
<EM><t9>	0xA4	Transmit 0x19, 0x99	Received 0x19, 0x99	Yes	Yes
<EM><t10>	0xA5	Transmit 0x19, 0x11	Received 0x19, 0x11	Yes	Yes
<EM><t11>	0xA6	Transmit 0x19, 0x13	Received 0x19, 0x13	Yes	Yes
<EM><t12>	0xA7	Transmit 0x99, 0x19	Received 0x99, 0x19	Yes	Yes
<EM><t13>	0xA8	Transmit 0x99, 0x11	Received 0x99, 0x11	Yes	Yes
<EM><t14>	0xA9	Transmit 0x99, 0x13	Received 0x99, 0x13	Yes	Yes
<EM><t15>	0xAA	Transmit 0x11,0x19	Received 0x11,0x19	Yes	Yes
<EM><t16>	0xAB	Transmit 0x11,0x99	Received 0x11,0x99	Yes	Yes
<EM><t17>	0xAC	Transmit 0x11,0x13	Received 0x11,0x13	Yes	Yes
<EM><t18>	0xAD	Transmit 0x13,0x19	Received 0x13,0x19	Yes	Yes
<EM><t19>	0xAE	Transmit 0x13,0x99	Received 0x13,0x99	Yes	Yes
<EM><t20>	0xAF	Transmit 0x13,0x11	Received 0x13,0x11	Yes	Yes
<EM><mark>	0xB0	Begin Transparent Mode	Abort Detected in Framed Submode	Yes	Yes, Receive Only
<EM><flag>	0xB1	Transmit a flag; enter Framed Submode if currently in Transparent Submode. If +ESA[E] = 1, append FCS to end of frame before sending closing HDLC flag.	Detected a non-flag to flag transition. Preceding data was a valid frame. If +ESA[E]=1, sent FCS matches that of the calculated CRC.	Yes	

Table 86. EM In-Band Commands and Statuses (Continued)

Command– Indicator pair	Hex Code	Transmit Direction	Receive Direction	Supported in Transparent Submode	Supported in Framed Submode
<EM><err>	0xB2	Transmit an Abort	Detected a non-flag to flag transition. Preceding data are not a valid frame.	Yes	
<EM><under>	0xB4	not applicable	Detected Transmit Data Underrun	Yes	Yes
<EM><tover>	0xB5	not applicable	Detected Transmit Data Over-run	Yes	Yes
<EM><rover>	0xB6	not applicable	Detected Receive Data Over-run	Yes	Yes
<EM><resume>	0xB7	Resume after a data underrun or overrun (applicable if +ESA[C] = 1)	Not applicable		Yes
<EM><bnum>	0xB8	not applicable	<octnum0><octnum1> specifies number of octets in the transmit data buffer if +ITF[C] is non-zero2.	Yes	Yes
<EM><unum>	0xB9	not applicable	<octnum0><octnum1> specifies number of discarded octets following a data overrun/underrun, after the <EM><resume> command. This is applicable if +ESA[C] = 12.		
<EM><eot>	0xBA	Terminate carrier, return to command mode.	Loss of carrier detected, return to command mode	Yes	Yes
<EM><ecs>	0xBB	Escape to On-Line command mode	Confirmation of Escape to On-Line command mode.	Yes	Yes
<EM><rrn>	0xBC	Request rate renegotiation	Indicate rate renegotiation	Yes	Yes

Table 86. EM In-Band Commands and Statuses (Continued)

Command–Indicator pair	Hex Code	Transmit Direction	Receive Direction	Supported in Transparent Submode	Supported in Framed Submode
<EM><rate>	0xBE	not supported	Retrain/Rate Reneg completed, following octets <tx><rx> indicate tx and rx rates. 0x20–1200 bps 0x21–2400 bps 0x22–4800 bps 0x23–7200 bps 0x24–9600 bps 0x25–12 kbps 0x26–14.4 kbps 0x27–16.8 kbps 0x28–19.2 kbps 0x29–21.6 kbps 0x2A–24 kbps 0x2B–26.4 kbps 0x2C–28.8 kbps 0x2D–31.2 kbps 0x2E–33.6 kbps	Yes	Yes

Notes:
1. U87 [10] = 1 Can be used to limit the transparency characters in the receive direction, to these four cases only.
2. The actual value represented in <octnum0><octnum1> = (octnum0 / 2) + (octunum1 x 64)
3. <EM><0x45> indicates that an unrecognized <EM> command was sent to the modem.

In addition, a common Point-of-Sale V.22 Fast Connect Handshake Protocol (with transparent HDLC) requires these additional settings:

Table 87. Fast Connect Settings

AT+MS = V22	V22 Protocol
AT:U7A,3	Set Fast Connect, Transmit HDLC Flags instead of Marks during handshake negotiation.

Given the example initialization settings shown in Table 87, after an ATDT command has been sent to establish a connection, the modem responds with the following:

```
ATDT12345
```

```
CONNECT 1200
```

```
PROTOCOL: NONE
```

```
<0x19> <0xBE> <0x20> <0x20> <0x19> <0xB1>
```

The first <EM><rate> indicator shows that the modem connected with a transmit rate of 1200 bps and a receive rate of 1200 bps. The <EM><flag> that occurs immediately after the <EM><rate> indicates that a non-flag to flag transition has occurred and that the receiver has now been synchronized. An <EM><flag> indicator is applicable only to the first occurrence of a non-flag to flag transition. Future occurrences of non-flag to flag transitions are indicated with an <EM><err> instead. Also, this feature is unique to the U87 [8]=1 option. Also, with U87 [8]=1, the Framed Submode is entered immediately upon connection. Otherwise, if U87 [8]=0, the Transparent Submode is entered instead, and the host is expected to send an <EM> <flag> to switch to the Framed Submode.

After a connection has been established, the modem is ready to transmit and receive frames. For example, if it is desired to send a frame whose contents are:

```
<0x10><0x11><0x12><0x13><0x14><0x15>
```

The host software sends the following:

```
<0x10><0x19><0xA0><0x12><0x19><0xA1>
<0x14><0x15><0x19><0xB1>
```

Note the bytes <0x11> and <0x13> are <EM> shielded because these bytes could have been used for XON / XOFF handshaking. In this example, CTS/RTS hardware handshaking is used, so it is also possible for the host to have sent this series of bytes instead:

```
<0x10><0x11><0x12><0x13><0x14><0x15>
<0x19><0xB1>
```

However, if the host does not <EM> shield the 0x11 and 0x13 characters, XON / XOFF software handshaking can no longer be used.

In either of the above transmit frames, the <EM><flag> is used to indicate that a logical frame has completed. The modem does not begin transmitting the frame at the DCE until the <EM><flag> is received or the number of bytes sent to the modem exceeds the number of bytes programmed into U87 [7:0].

In the above example, the following transmission:

```
<0x10><0x19><0xA0><0x12><0x19><0xA1>
<0x14><0x15><0x19><0xB1>
```

meets both criteria of having 10 bytes received at the DTE and receipt of an <EM><flag> command. In this example, the transmission at the DCE begins approximately after the receipt of the <0xB1> byte.

Once an HDLC frame begins transmitting at the DCE, the host must ensure transmit overrun and underrun do not occur. It is expected that the +ITF command be used to adjust the transmit flow control thresholds so that it is tuned to the system's ability to process the interrupt.

If a transmit underrun occurs, the <EM><tunder> indicator always appears in the receive path, regardless of how +ESA[C] is programmed.

If +ESA[C] = 0, the modem transmits an abort character at the DCE at the point of the transmit underrun. Additional transmit frames can then be transmitted normally.

If +ESA[C] = 1, the modem transmits an HDLC flag at the point of the transmit underrun, and the DCE continues to send only HDLC flags until the host sends an <EM><resume> command. The <EM><resume> is then followed by the <EM><unum> command so that the host software can correct this problem.

A transmit overrun can occur if the host does not properly implement transmit flow control. When a transmit overflow occurs, the <EM><tover> indicator always appears in the receive path. A transmit overflow is considered to be a catastrophic failure and results in non-deterministic behavior at the DCE. It is recommended that the session be terminated immediately.

SILICON LABS

It is expected that the <EM><tover> and <EM><tunder> indicators be encountered during system debug, and designing the system software properly to avoid having these indicators occur should be the design goal.

In the receive direction, assuming that the remote modem is another Si2493/57/34/15, this is the expected sequence at the remote receiver DTE, representing the frame sequence of:

<0x10><0x11><0x12><0x13><0x14><0x15>

<0x10><0x19><0xA0><0x12><0x19><0xA1>

<0x14><0x15><0x19><0xB1>

In the receive direction, the <EM><flag> indicates that the CRC check is successful, and the preceding frame was received correctly. If there had been an error in the preceding frame, the <EM><err> would have been sent instead of the <EM><flag>. The host is expected to discard the entire frame based on whether or not the frame is terminated with an <EM><flag> or <EM><err>. The host should also expect to occasionally see the <EM><mark> indicator if the sending modem experienced a transmitter underrun or overrun problem.

In general, the RTS flow control is not used. However, if it is used, and if RTS is negated for too long, the receive buffers will eventually overflow. This is called a receiver overrun, and the modem sends an <EM><rover> indicator. A receiver overrun is considered to be a catastrophic failure, and the host is expected to terminate the session. Host software must be designed so that an <EM><rover> indicator never occurs.

It is expected that the <EM><rover> indicator be encountered during system debug, and designing the system software properly to avoid having these indicators occur should be the design goal.

Please note that there is an option available in the U87 [10]. The reason for this option is to determine what the modem sends to the DTE when the modem receives back-to-back occurrences of the special characters, 0x19, 0x99, 0x11, and 0x13, at the DCE.

As an example, if the following string is received at the DCE:

<0x19><0x19><0x11><0x11>

If U87 [10] = 0, this is what the host software will receive at the DTE:

<0x19><0x5D><0x19><0xA2>

If U87 [10] = 1, this is what the host software will receive at the DTE:

<0x19><0x5C><0x19><0x5C><0x19><0xA0><0x19><0xA0>

The choice of how to program U87 [10] is based on whether or not it is desired to simplify the host receive parsing algorithm or to guarantee that the receive throughput is not overly affected by the <EM> <shielding>. In the worst case, if there is a large frame consisting only of special characters, the required throughput at the DTE will have to be at least 2x that of the DCE rate to account for the <EM> shielding overhead.

There are two methods of ending a call. One is to use the <EM><eot> command followed by an ATH. Sending the <EM><eot> command will cause the modem to go to command mode and stop the transmitter; however, the modem does not go back on hook until ATH. The other method is to use the <EM><esc> command to escape to command mode, and then issue the ATH command. The main difference is that the <EM><esc> does not shut off the transmitter. The <EM><esc> can also be followed by an ATO to resume the connection.

6. Programming Examples

The following programming examples are intended to facilitate the evaluation of various modem features and serve as example command strings that can be used singly or in combination to create the desired modem operation.

6.1. Quick Reference

Table 88 summarizes the modem function/feature and the associated hardware pins, AT commands, S registers, and U registers. When a command string is created to enable a particular feature, Table 88 should be reviewed to make sure all necessary commands and registers have been considered.

Table 88. Modem Feature vs. Hardware, AT Command and Register Setting

Function/Feature	AT Commands	S Registers	U Registers
Autobaud	\T16, \T17		
Blacklisting	%B	42, 43, 44	
Type I Caller ID	+VCID, +VCDT		U70 [12,4]
Type II Caller ID	+PCW +VCID +VCIDR		
Country-dependent settings			U0–U4C, U4D [10,1,0], U50–U52, U62 [8], U67 [6, 3:2, 1, 0], U68 [2, 1, 0], U69 [6, 5, 4]
DTE interface	En, \Bn, \Pn, \Qn, \Tn, \U		
DTMF dialing	D	6, 8, 14	U46–U48, U4E
EEPROM	:E, :M		
Escape (parallel/SPI)			U70 [15], Parallel Register 1 [2]
Escape (UART)	\B6	12	U70 [13,15]
Intrusion detection			U6A [1], U69 [2], U70 [10, 2], U76 [15:9, 8, 7:5, 4:0], U77 [15:12, 11], U78 [15:14, 7:0], U79 [4:0], UAE
Line rate	&Gn, &Hn		
Modem-on-hold	+PCW +PMHF +PMHR +PMHT +PMH +ATO		
Overcurrent detection			U67 [7], U70 [11, 3], U77 [10, 9, 8:0], U79 [4:0]
Power control	&Z	24	U65 [13]
Pulse dialing	D	6, 8, 14	U37–U45, U4E

SILICON LABS

Table 88. Modem Feature vs. Hardware, AT Command and Register Setting (Continued)

Function/Feature	AT Commands	S Registers	U Registers
Quick connect	+PQC +PSS		
Reset	Z		U6E [4], U70 [7,5]
SAS detect			U9F–UA9
Self Test	&Tn, &Hn	40, 41	
SMS	+FCLASS +FRM +FTM		
V.29	+FCLASS +FTM +FRM		
V.42/V.42b	+DR, %Cn, \Nn, +DS		
V.44*	+DS44, +DR		
V.92	+MS +PIG		
*Note: Si2493 only.			

6.2. Country-Dependent Setup

Configuring the ISOmodem for operation in different countries is done easily with AT commands. In all but rare instances, no hardware change is required (the exceptions being an optional maximum ringer impedance, a billing-tone filter, etc.). For this reason, the ISOmodem is truly a global modem solution. Modem initialization commands for various countries are presented in "6.2.2.1. Country Initialization Table". All U-register values are in hexadecimal. The settings for different countries can be broken into three groups: call progress, dialing, and line-interface control. Call-progress settings include filter coefficients, cadence data, and threshold values. Dialing includes DTMF levels, thresholds, timing and pulse-dialing parameters. Line-interface settings include ac line impedance, off-hook voltage and current characteristics, ringer sensitivity, and transmit levels. CID (Caller ID) settings are discussed in a separate section. Tables 89–93 describe the registers and bits used for global configuration and the functions performed by each. Many countries use some or all of the default FCC settings.

6.2.1. DC Termination

The ISOmodem offers a great deal of flexibility in setting dc termination. Several bits can be used to adapt to particular country requirements and unusual line conditions. The dc termination control bits are shown in Table 89.

Table 89. DC Termination Control Bits

Reg	Bit	Val	Function
U67	7	DCR	DC Impedance Select
U67	3:2	DCV	DC Termination Select
U7D	10	LLV	Special low-voltage mode

A detailed description of each bit is given in the relevant U-register description section of this manual. The following discussion centers on the use of these bits alone or in combination to meet particular country requirements.

6.2.2. Country Configuration

The modem default settings are for the US-like countries. Many countries use at least some of the default register settings. Default values do not have to be written when configuring the modem to operate in a particular country, assuming the modem was reset just prior to the configuration process. **To avoid confusion and possible errors, the modem should be reset prior to reconfiguration between countries.**

Some countries have unusual requirements. For example, registers U37–U40 set the number of pulses to dial digits 0 through 9, respectively. By default, digit 1 has a setting of 1 pulse; digit 2 has a setting of 2 pulses, and so on. Digit 0 has a setting of 0xA (10 decimal) pulses. This pulse arrangement is used nearly universally throughout the world. However, New Zealand requires ten pulses for 0, nine pulses for 1, eight pulses for 2, and so on. Sweden, on the other hand, requires one pulse for 0, two pulses for 1, and so on.

Japan requires both the usual 10 pps pulse dialing and 20 pps pulse dialing. To configure the modem for 20 pps, set U42 (PDBT) = 0x0022, U43 (PDMT) = 0x0010, and U45 (PDIT) = 0x0258. The %P command may also be used.

The Netherlands has a unique dial-tone filter. Other countries, such as Japan, have special low-voltage loop requirements. South Korea, Poland, and South Africa have special ringer impedance requirements. Set all country-specific parameters listed in Table 90.

In order to use the +GCI command for a given country and modify one or more U registers, it is necessary to execute the +GCI command first, then modify the desired register or registers. The +GCI command resets all U registers through U86 and S7 to factory defaults before applying the country-specific settings. A compliance laboratory can verify whether the countries that accept the legacy TBR21 specification still accept their previous settings. It is advantageous in terms of heat dissipation to disable the TBR21 current limit. In order to disable loop-current limiting, bit ILIM (U67 [9]) should be set to zero after the +GCI command.

Table 90 contains recommended updates to the +GCI register settings. The U-register writes must be loaded after the +GCI command. Some TBR21 and ES 203 021 countries require blacklisting. This can be enabled with S42 = 1. Some also require a minimum period of time between calls that can be set with S50 = 6.

6.2.2.1. Country Initialization Table

Table 90. Country Initialization Table

Country	Initialization
Algeria*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
Argentina*	AT+GCI=51 AT:U46,680 AT:U52,1 ATS007=50
Armenia*	AT+GCI=73 ATS007=80
Australia	AT+GCI=9 AT:U42,55,F AT:U4F,79 AT:U52,2 ATS006=3
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
Austria	AT+GCI=A AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Bahamas	Defaults
Bahrain*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
Belarus*	AT+GCI=73
Belgium	AT+GCI=F AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Bermuda	Defaults
Brazil	AT+GCI=16 AT:U67,8
Brunei*	AT+GCI=9C
Bulgaria	AT+GCI=1B AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Canada	AT+GCI=20
Caribbean	Defaults
Chile*	AT+GCI=73 AT:U49,28,83 ATS007=180
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

Table 90. Country Initialization Table (Continued)

Country	Initialization
China	AT+GCI=26 AT:U67,8
Colombia	AT+GCI=27
Costa Rica	Defaults
Croatia*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
Cyprus*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Czech Republic	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Denmark	AT+GCI=31 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Dominican Republic	Defaults
Dubai	Defaults
Egypt*	AT+GCI=6C AT:U35,10E0 AT:U62,904,33 AT:U67,208 ATS006=3
El Salvador	Defaults
Ecuador	AT+GCI=35
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
Estonia*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Finland	AT+GCI=3C AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
France	AT+GCI=3D AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
French Polynesia*	AT+GCI=1B AT:U62,904
Georgia*	AT+GCI=73
Germany	AT+GCI=42 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Ghana*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

Table 90. Country Initialization Table (Continued)

Country	Initialization
Greece	AT+GCI=46 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Guadeloupe*	AT+GCI=1B AT:U62,904 AT:U67,8
Guam	Defaults
Hong Kong	AT+GCI = 50
Hungary	AT+GCI=51 AT:U35,10E0 AT:U62,904,33
Iceland*	AT+GCI=2E AT:U62,904
India	AT+GCI=53 AT:U63,3 AT:U67,8
Indonesia	Defaults
Ireland	AT+GCI=57 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Israel	AT+GCI=58 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,1 AT:U62,904 AT:U67,1004
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
Italy	AT+GCI=59 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Japan	AT+GCI=0
Jordan*	AT+GCI=16 AT:U49,22,7A
Kazakhstan*	AT+GCI=73
Korea (South)	AT+GCI=61 AT:U67,A
Kuwait	Defaults
Kyrgyzstan*	AT+GCI = 73
Latvia*	AT+GCI=1B AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Lebanon*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
Lesotho*	AT+GCI=9F AT:U63,33 AT:U67,A ATS006=3
Liechtenstein*	AT+GCI=2E AT:U62,904
Lithuania*	AT+GCI=73 AT:U45,344 AT:U62,904,33
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
Luxembourg	AT+GCI=69 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Macao	Defaults
Malaysia	AT+GCI=6C AT:U46,A80
Malta*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
Martinique*	AT+GCI=1B AT:U62,904 AT:U67,8 ATS007=50
Mexico	AT+GCI=73
Moldova*	AT+GCI=73
Morocco*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
Netherlands	AT+GCI=7B AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
New Zealand	AT+GCI=7E AT:U38,9,8,7,6 AT:U3D,4,3,2,1 AT:U46,8A0 AT:U52,2 AT:U67,8
Nigeria*	AT+GCI=1B AT:U62,904
Norway	AT+GCI=82 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 ATS006=3
Oman*	AT+GCI=89
Pakistan*	AT+GCI=89 AT:U46,8A0
Paraguay	AT+GCI=87
Peru	Defaults
Philippines	AT+GCI=89
Poland	AT+GCI=8A AT:U14,7 AT:U52,2 AT:U62,904 AT:U67,8 AT:U77,4410 ATS006=3
Portugal	AT+GCI=8B AT:U35,10E0 AT:U42,41,21 AT:U46,9B0 AT:U4F,64 AT:U52,1 AT:U62,904 AT:U67,8
Puerto Rico	Defaults
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

Table 90. Country Initialization Table (Continued)

Country	Initialization
Qatar*	AT+GCI=16 AT:U49,22,7A
Reunion*	AT+GCI=1B AT:U62,904 AT:U67,8
Romania*	AT+GCI=73 AT:U62,904,33
Russia	AT+GCI=B8 AT:U67,4
Saudi Arabia	Defaults
Singapore	AT+GCI=9C
Slovakia*	AT+GCI=73 AT:U35,10E0 AT:U47,5A,5A AT:U62,904,33
Slovenia*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904 AT:U67,8
South Africa	AT+GCI=9F AT:U63,33 AT:U67,A ATS006=3
Spain	AT+GCI=A0 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Sri Lanka*	AT+GCI=9C
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
Sweden	AT+GCI=A5 AT:U14,7 AT:U35,10E0 AT:U37,1,2,3,4,5,6,7,8,9,A AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Switzerland	AT+GCI=A6 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 ATS006=3
Syria*	AT+GCI=16 AT:U49,22,7A
Taiwan	AT+GCI=FE AT:U67,8
Thailand*	AT+GCI=6C AT:U46,240 AT:U67,4
Tunisia*	AT+GCI=51 AT:U46,680 AT:U52,1 ATS007=50
Turkey*	AT+GCI=1B AT:U35,10E0 AT:U46,9B0 AT:U62,904
UAE*	AT+GCI=6C AT:U67,8 ATS006=3
USA	AT+GCI=B5
Ukraine*	AT+GCI=73
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

Table 90. Country Initialization Table (Continued)

Country	Initialization
United Kingdom	AT+GCI=B4 AT:U14,7 AT:U35,10E0 AT:U46,9B0 AT:U4F,64 AT:U52,2 AT:U62,904 AT:U67,8 ATS006=3
Uruguay	Defaults
Uzbekistan	Defaults
Venezuela	Defaults
Yemen	Defaults
Zambia*	AT+GCI=2E AT:U35,10E0 AT:U46,9B0 AT:U62,904
*Note: These countries do not have a built-in +GCI support but are using the settings of other countries as a shortcut.	

SILICON LABS

6.2.2.2. Country-Setting Register Tables

Table 91. International Call Progress Registers

Register	Value	Function
Dial Tone Control		
U0–U14		Dial Tone Detect Filter Coefficients
U15	DTON	Dial Tone On Threshold
U16	DTOF	Dial Tone Off Threshold
U34	DTWD	Dial Tone Detect Window
U35	DMOT	Dial Tone Minimum On Time
Busy Tone Control		
U17–U2B		Busy Tone Detect Filter Coefficients
U2C	BTON	Busy Tone On Threshold
U2D	BTOF	Busy Tone Off Threshold
U2E	BMTT	Busy Tone Minimum Total Time
U2F	BDLT	Busy Tone Delta Time
U30	BMOT	Busy Tone Minimum On Time
Ringback Cadence Control		
U31	RMTT	Ringback Tone Minimum Total Time
U32	RDLT	Ringback Tone Delta Time
U33	RMOT	Ringback Tone Minimum On Time
Ring Detect Control		
U49	RGFH	Ring Frequency High
U4A	RGFD	Ring Frequency Delta
U4B	RGMN	Ring Cadence Minimum On Time
U4C	RGNX	Ring Cadence Maximum Total Time

Table 92. Dial Registers

Register	Value	Function
Pulse Dial Control		
U37–U40		Pulse per Digit Definition
U42	PDBT	Pulse Dial Break Time
U43	PDMT	Pulse Dial Make Time
U45	PDIT	Pulse Dial Interdigit Time
DTMF Control		
U46	DTPL	DTMF Power Level (and Twist)
U47	DTNT	DTMF On Time
U48	DTFT	DTMF Off Time

Table 93. Line Interface/Control Registers

Register	Bit	Value	Function
U4D	10	CLPD	Check Loop Current Before Dialing
	1	LLC	Low Loop Current Detect (set for legacy TBR21)
	0	LCN	Loop Current Needed
U50		LCDN	Loop Current Debounce On Time
U51		LCDF	Loop Current Debounce Off Time
U52		XMTL	Transmit Level
U67: 13:12 MINI 9 ILIM	7	DCR	DC Impedance Select
	6	OHS	On-Hook Speed
	3:2	DCV	DC Termination Select
	1	RZ	Ringer Impedance
	0	RT	Ringer Threshold Select
U68	2	BTE	Billing Tone Protect Enable
	1	ROV	Receive Overload
	0	BTD	Billing Tone Detected

6.2.2.3. Special Requirements for India

To output a 0 dBm sine wave, use the following commands:

```
AT:PF800, C4DD, 7B5C, 595F
AT*Y254:W50, 0, 5B86,1
AT:U46,0
AT*Y1X1DT1
```

This command string turns off the high-frequency DTMF tone, leaving only the low-frequency DTMF tone when an ATDT is sent. The tone is output continuously until any key is pressed. To restart the tone output, type AT*Y1DT1. To change the tone power level, type ATU46,00X0 (where X is a hexadecimal value 0–F representing output power in –1 dBm steps from 0 to –15 dBm).

SILICON LABS

6.2.2.4. Special Requirements for Serbia and Montenegro

The following are special network requirements for Serbia and Montenegro. These specifications are based on the best information available and are believed to be correct.

- DC Feed: 48 or 60 V
- Feeding Bridge: 2 x 400 Ω or 2 x 500 Ω
- Network Impedance: 600 Ω resistive
- On-Hook (Idle State) Noise: < –60 dBm
- On-Hook ac (Ringer) impedance: >2.5 kΩ
- DTMF Transmit: –11 to –9 dBm and –8 to –6 dBm
- Data Transmit Level: 0 dBm to –15 dBm in 1 dB steps (average –13 dBmo)
- Out-of-band energy: not specified
- Pulse Dial: 1.6/1 ±15 % (pulse/pause)
  - Rep Rate: 10 pps
  - Interdial Pause: 250 ms <x> 800 ms, ±10 %
- Ring signal: 25 Hz 80–90 V_{RMS}
- Dial Tone: 425 Hz ±15 %
  - Level: –8 dBm $\geq$ x $\geq$ –12 dBm
  - Cadence: 200 ms ±10% ON
    300 ms ±10% OFF
    700 ms ±10% ON
    800 ms ±10% OFF
- Busy Tone: 425 Hz ±15 %
  - Level: –8 dBm $\geq$ x $\geq$ –12 dBm
  - Cadence: 500 ms ±10 % ON
    500 ms ±10 % OFF

6.2.3. Blacklisting

Blacklisting prevents dialing the same phone number more than three times in three minutes. Any attempt to dial a fourth time within three minutes results in a BLACKLISTED result code. If the blacklisting memory is full, any dial to a new number results in a BLACKLIST FULL result code. The number of allowable calls may be adjusted in S43. If S43 = 3, the third call in S44 seconds is blacklisted. The blacklisting time may be adjusted with register S44 (second units). A number is added to the blacklist only if the connection fails. The S42 register controls blacklisting.

Any number that is currently blacklisted is reported with the %B command.

S42	Blacklisting
0 (default)	Disabled
1	Enabled

AT Command	Function
%B	Report blacklisted number (if any) followed by OK Example: AT%B\r 5121234567 OK

6.3. Caller ID

The ISOmodem supports all major Caller ID (CID) types. CID is disabled by default (+VCID = 0). Setting +VCID = 1 via the AT+VCID = 1 command enables decoded (formatted) CID, while setting +VCID = 2 causes raw Caller ID data to be output. The specific CID mode is selected by +VCDT, which is set to the US Telcordia standard by default. The AT+VCDT = n command is used to define the CID mode according to the decimal values of n defined in Table 94. U70 [4] (CID) is a sticky bit that is set when a CID preamble is received and cleared with an AT:I ("Interrupt read") command.

Table 94. Caller ID Modes

n	+VCDT Settings
0	After ring only (default)
1	Force CID monitor (always on)
2	UK with wetting pulse
3	Japan

The following sections describe each CID mode.

6.3.1. Force Caller ID Monitor (Always On)

In this mode, the ISOmodem, when on-hook, continuously monitors the line for the CID mark sequence and FSK data. This mode can be used in all systems, especially those requiring detection of CID data before the ring burst. It is also useful for detecting voicemail indicator signals and for supporting Type II Caller ID. In most systems, "Always On" is the preferred method, since it separates CID detection from ring detection.

6.3.2. Caller ID After Ring Only

The ISOmodem detects the first ring burst, echoes RING to the host, and prepares to detect the CID preamble. On preamble detection, the modem echoes the CIDM response to the host (indicating the preamble was received and FSK modulated CID data will follow), and INT is triggered if enabled.

Next the CID algorithm looks for the start bit, assembles the characters, and sends them to the host as they are received. When the CID burst is finished, there is no more carrier and NO CARRIER is echoed to the host. The ISOmodem continues to detect subsequent ring bursts, echoes RING to the host, increments the ring counter, S1, and automatically answers after the number of rings specified in S0.

6.3.3. UK Caller ID with Wetting Pulse

The ISOmodem first detects a line-polarity reversal, echoes FLASH to the host, and triggers the INT pin. The ISOmodem then searches for the Idle State Tone Alert signal and, when detected, echoes STAS to the host. After the Idle State Tone Alert Signal is completed, the ISOmodem goes off-hook then on-hook to apply the 15 ms wetting pulse to the local loop. Next, the ISOmodem prepares to detect the CID preamble. After 50 continuous mark bits (1s) are detected, the CIDM response is echoed to the host indicating that the mark sequence was received and that FSK-modulated CID data will follow, and INT is again triggered. Then, the CID algorithm looks for the start bit, assembles the characters, and sends them to the host as they are received. When the CID burst is finished, the carrier is lost, and NO CARRIER is echoed to the host. The ISOmodem detects ring bursts, echoes RING to the host, increments the ring counter, S1, and automatically answers after the number of rings specified in S0. If the wetting pulse is not required, +VCDT = 0 or 1 can be used in the UK.

6.3.4. Japan Caller ID

The ISOmodem detects a line-polarity reversal and a brief ring burst, then goes off-hook and triggers the INT pin. CID data are sent using the V.23 specification. After detecting 40 mark bits (1s), the ISOmodem searches for a start-bit. CIDM is echoed to the host when a start bit is received. The ISOmodem then begins to assemble characters and sends them to the host. When the CID signal ends, the ISOmodem hangs up and echoes NO CARRIER to the host. The modem then waits for the normal ring signal. Table 95 shows the AT command strings that configure the ISOmodem for Japan Caller ID.

Table 95. Japan Caller ID

Command	Function
AT+VCID = 1	Enables Caller ID.
AT+VCDT = 3	Selects Japan CID mode.

6.3.5. DTMF Caller ID

DTMF Caller ID is supported in the Si2493/57/34/15/04 Revision D or above and Si2494/39 Revision A or above. DTMF Caller ID detection is needed to provide complete CID support for Brazil, China and other countries. The ISOmodem detects the preamble and start code (0x41, or ASCII 'A'), then echoes CIDM to the host. The ISOmodem assembles the rest of the characters in the message and sends them to the host. It detects the stop code (0x44, or ASCII 'D') and proceeds with the rest of the call processing.

For ISOmodems that support voice mode, detection of DTMF CID is done automatically in +FCLASS = 8 mode after being enabled by a "+VLS = 14" command. The user can also enable FSK CID with the AT+VCID and AT+VCDT commands. This gives simultaneous support of DTMF and FSK modes.This is useful in countries like Brazil, China and Taiwan, where the use of DTMF or FSK varies from region to region.

6.4. SMS Support

Short Message Service (SMS) allows text messages to be sent and received from one telephone to another via an SMS service center. The ISOmodem provides a flexible interface that can handle multiple SMS standards. This flexibility is possible because most of the differences between standards is handled by the host in the data stream itself. The ISOmodem performs the necessary data modulation and provides two options for message packet structure (Protocol 1 and Protocol 2, as defined in ETSI ES 201 912). The rest of the data link layer and transfer layer are defined by the host system. The ISOmodem uses a V.23 half-duplex modulation to transmit and receive the data over the PSTN. Protocol 2 differs from Protocol 1 in that a packet is preceded by a 300-bit long channel-seizure preamble. ETSI ES 201 912 describes the other differences between Protocols 1 and 2, but the host processor handles these when structuring the data within the packet.

Table 96. Protocol 1

80 bits of mark (constant ones)	Message

Table 97. Protocol 2

Channel seizure (300-bit stream of alternating ones and zeroes)	80-bit stream of ones	Message

Four commands control the behavior of the SMS feature, as described in Table 98 below:

Table 98. SMS Commands

Command	SMS Feature Behavior
AT+FCLASS = 256	Prepares the modem for handling SMS calls.
ATDT;	Goes off-hook and returns to command mode. If a phone number is provided, it is dialed prior to returning to command mode.

Table 98. SMS Commands

AT+FRM = 200	Returns to data mode prepared to receive an SMS message.
AT+FTM = 201	Returns to data mode prepared to transmit an SMS Protocol 1 message.
AT+FTM = 202	Returns to data mode prepared to transmit an SMS Protocol 2 message.

To enable the SMS features on the ISOmodem, the host must send AT+FCLASS = 256 to the modem prior to handling an SMS call. The host can then dial or answer an SMS call using ATDTxxxx; (where xxxx is the number to be dialed), or ATDT; respectively. Note the semicolon at the end of the command, which places the modem into command mode immediately after dialing and returns OK. The host can then prepare the modem for transmitting or receiving SMS data.

To receive Protocol 1 or Protocol 2 data, the host must send AT+FRM = 200. This causes the modem to return to data mode silently, listening for data from the remote SMS server. If the modem detects a valid Protocol 1 or Protocol 2 packet, it responds with a CONNECT 1 or CONNECT 2 message respectively, followed by the SMS message (without channel seizure and mark). When the carrier stops, the modem returns to command mode and responds with OK.

To transmit Protocol 1 or Protocol 2 data, the host must send AT+FTM = 201 or AT+FTM = 202. This causes the modem to return to data mode and wait silently until data are received from the host processor for transmission. Once data are received from the host, the modem transmits the proper number of channel seizure and mark bits followed by the data it received from the host. After the modem has begun transmitting, it will send marks when it does not have data to send and will continue to do so until the host escapes to command mode.

The content of the data message is entirely up to the host including any checksum or CRC. ETSI ES 201 912 describes two standard data and transfer layers that are commonly used. SMS typically relies on caller identification information to determine if the call should be answered using an SMS device or not. Refer to "6.3. Caller ID" for more information on how to configure the modem for Caller ID detection.

6.5. Type II Caller ID/SAS Detection

When a call is in progress, the Subscriber Alerting Signal (SAS) tone is sent by the central office to indicate a second incoming call. The central office may also issue a CPE Alert Signal (CAS) after the SAS to indicate that call waiting Caller ID (CWCID) information is available. If properly configured, the modem will acknowledge the CAS tone, receive the CWCID data, and perform a retrain.

The ISOmodem is configured through the +PCW command to toggle the RI pin (+PCW=0), hang up (+PCW=1), or do nothing (+PCW=2) upon receipt of the SAS tone. The default is to ignore the SAS tone. The modem, enabled through the +VCID command, will collect Caller ID information if +PCW is set to toggle the RI pin. The AT:I command can be used to verify receipt of the SAS and CWCID data. Bit 9 will be set for SAS receipt due to the RI toggle. Bit 4 will be set if CWCID data are received.

The CWCID data are collected using the +VCIDR? command. The data message is displayed in hexadecimal format using ASCII text. The modem will return NO DATA if no Caller ID is available. The +VCIDR response is listed below for the following example CWCID message:

```
Date & Time:  09/11 16:21
ICLID Number: 512-555-1234
Calling Name: JOHN_DOE


+VCIDR:
80 20 01 08 30 39 31 31 31 36 32 31 02 0A 35 31
32 35 35 35 31 32 33 34 07 08 4A 4F 48 4E 5F 44
4F 45 40
OK
```

Table 99 defines the Multiple Data Message Format (MDMF) parameters in the example response.

Table 99. MDMF Parameters

Character Description	Hexadecimal Value	ASCII Value
Message Type (MDMF)	80	
Message Length	20	
Parameter Type (Date/Time)	01	
Parameter Length	08	
Month	30 39	09
Day	31 31	11
Hour	31 36	16
Minutes	32 31	21
Parameter Type (Number)	02	
Parameter Length	0A	
Number	35 31 32 35 35 35 31 32 33 34	5125551234
Parameter Type (Name)	07	
Parameter Length	08	
Name	4A 4F 48 4E 5F 44 4F 45	JOHN_DOE
Checksum	40	

The SAS tone varies between countries and requires configuration of user registers U9F to UA9. The SAS_FREQ (U9F) register sets the expected SAS tone frequency as shown in Table 100. The default SAS frequency is 440 Hz. The expected cadence is set in cadence registers SAS_CADENCE0 (UA0) through SAS_CADENCE9 (UA9).

The even-numbered registers, (UA0, UA2, etc.), control the amount of time the tone is expected to be present, and the odd-numbered registers select the amount of time the tone must not be present. The values are expressed in 10 millisecond units. For example, a cadence of on 500 ms, off 300 ms then on for 500 ms may be selected by writing 0x0032 to UA0, 0x001E to UA1 and 0x0032 to UA2. The unused registers should be written to 0. The default cadence setting is UA0 equal to 001Eh, and the remaining nine registers are set to zero.

Table 101 defines the SAS cadence for each supported country. The on-time is listed in bold. These data were obtained from ITU-T Recommendation E.180 Supplement 2 (04/98).

Table 100. SAS Tone Frequency

SAS_FREQ (U9F)	SAS Frequency
0x0000	440 Hz (Default)
0x0001	400 Hz
0x0002	420 Hz
0x0003	425 Hz
0x0004	480 Hz
0x0005	450 Hz
0x0006	900 Hz
0x0007	950 Hz
0x0008	523 Hz
0x0009	1400 Hz

Table 101. SAS Cadence for Supported Countries*

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Angola	Waiting Tone	400	**1.0** – 5.0	U9F = 0x0001 UA0 = 0x0064 UA1 = 0x01F4
Anguilla	Waiting Tone	440	**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
Antigua and Barbuda	Call Waiting Tone	480	**0.6** – 10.0	U9F = 0x0004 UA0 = 0x003C UA1 = 0x03E8
Argentine Republic	Waiting Tone	425	**0.4** – 0.2 – **0.4** – 4.0	U9F = 0x0003 UA0 = 0x0028 UA1 = 0x0014 UA2 = 0x0028 UA3 = 0x0190

SILICON LABS

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Aruba	Call Waiting Tone	425	**0.2** – 0.2 – **0.2** – 4.4	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x01B8
Australia	Call Waiting Tone	425	**0.2** – 0.2 – **0.2** – 4.4	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x01B8
Austria	Waiting Tone	420	**0.04** – 1.95	U9F = 0x0002 UA0 = 0x0004 UA1 = 0x00C3
Bermuda	Waiting Tone	440	(Two bursts, ten seconds apart)	U9F = 0x0000
Bhutan	Waiting Tone	400	**0.5** – 0.25	U9F = 0x0001 UA0 = 0x0032 UA1 = 0x0019
Botswana	Waiting Tone	425	**0.2** – 1.0	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0064
Brazil	Waiting Tone	425	**0.05** – 1.0	U9F = 0x0003 UA0 = 0x0005 UA1 = 0x0064
British Virgin Islands	Waiting Tone	440	**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
Brunei Darussalam	Call Waiting Tone	400×24	**0.5** – 0.25	U9F = 0x0001 UA0 = 0x0032 UA1 = 0x0019
Channel Islands: Jersey	Waiting Tone	400	**0.1** – 2.5 – **0.1**	U9F = 0x0000 UA0 = 0x000A UA1 = 0x00FA UA2 = 0x000A
Chile	Waiting Tone	900+1300	**0.5** – 0.5	U9F = 0x0006 UA0 = 0x0032 UA1 = 0x0032

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
China	Waiting Tone	450	**0.4** – 4.0	U9F = 0x0005 UA0 = 0x0028 UA1 = 0x0190
Croatia	Call Waiting Tone	425	**0.3** – 8.0	U9F = 0x0003 UA0 = 0x001E UA1 = 0x0320
Cyprus	Call Waiting Tone	425	**0.1** – 0.1 – **0.1** – 5.3	U9F = 0x0003 UA0 = 0x000A UA1 = 0x000A UA2 = 0x000A UA3 = 0x0212
Czech Republic	Call Waiting Tone	425	**0.33** – 9.0	U9F = 0x0003 UA0 = 0x0021 UA1 = 0x0384
Dominica (Commonwealth of)	Call Waiting Tone	440	1**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
Ecuador	Call Waiting Tone	425	**0.2** – 0.6	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x003C
Estonia	Call Waiting Tone	950/1400/1800	**3×(0.33** – 0.3)	U9F = 0x0007
Ethiopia	Call Waiting Tone	425	**0.2** – 0.6	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x003C
Finland	Waiting Tone	425	**0.15** – 8.0	U9F = 0x0003 UA0 = 0x000F UA1 = 0x0320
Germany	Waiting Tone	425	**0.2** – 0.2 – **0.2** – 5.0	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x01F4
Ghana	Waiting Tone	400	**0.8** – 0.2 – **0.3** – 3.2	U9F = 0x0001 UA0 = 0x0050 UA1 = 0x0014 UA2 = 0x001E UA3 = 0x0140

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Gibraltar	Waiting Tone	400	**0.1** – 3.0	U9F = 0x0001 UA0 = 0x000A UA1 = 0x012C
Greece	Call Waiting Tone	425	**0.3** – 10.0 – **0.3** – 10.0	U9F = 0x0003 UA0 = 0x001E UA1 = 0x03E8 UA2 = 0x001E UA3 = 0x03E8
Guyana	Waiting Tone	480	**0.5** – 18.0	U9F = 0x0004 UA0 = 0x0032 UA1 = 0x0708
Honduras	Call Waiting Tone	440	**0.5** – 0.5 – **0.2** – 4.0	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x0032 UA2 = 0x0014 UA3 = 0x0190
Hong Kong	Call Waiting Tone	440	3×(**0.5** – 0.5) – 8.0)	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x0032 UA2 = 0x0032 UA3 = 0x0032 UA4 = 0x0032 UA5 = 0x0352
Hungary	Waiting Tone	425	**0.04** – 1.96	U9F = 0x0003 UA0 = 0x0004 UA1 = 0x00C4
Iceland	Waiting Tone	425	4x (**0.2** – 0.2 – **0.2** – 3.6 – **0.2** – 0.2 – **0.2)**	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x0168 UA4 = 0x0014 UA5 = 0x0014 UA6 = 0x0014
Iran	Waiting Tone	425	**0.2** – 0.2 – **0.2** – 10.0	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x03E8

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Israel	Call Waiting Tone	400	1x(**0.15** – 10.0 – **0.15**)	U9F = 0x0001 UA0 = 0x000F UA1 = 0x03E8 UA2 = 0x000F
Japan	Call Waiting Tone I	400x16/400	**0.5** – 0.0~4.0 – **0.05** – 0.45 – **0.05** – 3.45 – **0.05** – 0.45 – **0.05** – 3.45	U9F = 0x0001 UA0 = 0x0032 UA1 = 0x0000 to 0x0190 UA2 = 0x0005 UA3 = 0x002D UA4 = 0x0005 UA5 = 0x0159 UA6 = 0x0005 UA7 = 0x002D UA8 = 0x0005 UA9 = 0x0159
	Call Waiting Tone Ii	400×16/400	**0.1** – 0.1 – **0.1** – 3.0	U9F = 0x0001 UA0 = 0x000A UA1 = 0x000A UA2 = 0x000A UA3 = 0x012C
	Call Waiting Tone Iii	400×16/400	**0.064** – 0.436 – **0.064** – 3.436	U9F = 0x0001 UA0 = 0x0007 UA1 = 0x002C UA2 = 0x0007 UA3 = 0x0158
	Call Waiting Tone Iv	400×16/400	**0.25** – 0.25 – **0.25** – 3.25	U9F = 0x0001 UA0 = 0x0019 UA1 = 0x0019 UA2 = 0x0019 UA3 = 0x0145
Jordan	Waiting Tone	420×40// 400+440	**0.5** – 2×(0.3 – **0.2**) – 3.0	U9F = 0x0001 or 0x0002 UA0 = 0x0032 UA1 = 0x001E UA2 = 0x0014 UA3 = 0x001E UA4 = 0x0014 UA5 = 0x012C
Kenya	Call Waiting Tone	425	CONTINUOUS	U9F = 0x0003

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Kiribati	Waiting Tone	425	**0.1** – 0.2 – **0.1** – 4.7	U9F = 0x0003 UA0 = 0x000A UA1 = 0x0014 UA2 = 0x000A UA3 = 0x01D6
Korea (Republic Of)	Waiting Tone	350+440	**0.25** – 0.25 – **0.25** – 3.25	U9F = 0x000 UA0 = 0x0019 UA1 = 0x0019 UA2 = 0x0019 UA3 = 0x0145
Lao P.D.R.	Waiting Tone	425	**0.4** – 0.4	U9F = 0x0003 UA0 = 0x0028 UA1 = 0x0028
Lithuania	Waiting Tone	950/1400/1800	**3×(0.333** – 1.0)	U9F = 0x0007
Macau	Call Waiting Tone	425	**0.2** – 0.6	U9F = 0x0001 UA0 = 0x0014 UA1 = 0x003C
Madagascar	Call Waiting Tone	440	**0.1** – 1.9	U9F = 0x0000 UA0 = 0x000A UA1 = 0x00BE
Malaysia	Waiting Tone	425	**1.0** – 10.0 – **0.5** – 0.25 – **0.5** – 10.0 – **0.5** – 0.25	U9F = 0x0003 UA0 = 0x0064 UA1 = 0x03E8 UA2 = 0x0032 UA3 = 0x0019 UA4 = 0x0032 UA5 = 0x03E8 UA6 = 0x0032 UA7 = 0x0019
Maldives	Call Waiting Tone	400	**1.0** – 10.0	U9F = 0x0001 UA0 = 0x0064 UA1 = 0x03E8
Montserrat	Waiting Tone	440	**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
Netherlands	Waiting Tone	425	**0.5** – 9.5	U9F = 0x0003 UA0 = 0x0032 UA1 = 0x03B6
New Zealand	Waiting Tone I	400+450	0.5	U9F = 0x0001 UA0 = 0x0032

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
	Waiting Tone Ii	400	**0.25** – 0.25 – **0.25** – 3.25	U9F = 0x0001 UA0 = 0x0019 UA1 = 0x0019 UA2 = 0x0019 UA3 = 0x0145
	Waiting Tone Iii	523/659	3×(**0.2** – 3.0) – **0.2**	U9F = 0x0008 UA0 = 0x0014 UA1 = 0x012C UA2 = 0x0014 UA3 = 0x012C UA4 = 0x0014 UA5 = 0x012C UA6 = 0x0014
Nigeria	Call Waiting Tone	400	**2.0** – 0.2	U9F = 0x0001 UA0 = 0x00C8 UA1 = 0x0014
Oman	Waiting Tone	425	**0.3** – 1.0	U9F = 0x0003 UA0 = 0x001E UA1 = 0x0064
Papua New Guinea	Waiting Tone	425	**0.04** – 10.0 – **0.04** – 20.0 – **0.04** – 20.0	U9F = 0x0003 UA0 = 0x0004 UA1 = 0x03E8 UA2 = 0x0004 UA3 = 0x07D0 UA4 = 0x0004 UA5 = 0x07D0
Paraguay	Waiting Tone	950/950/1400	**0.65** – 0.325 – **0.125** – 1.3 – **2.6**	U9F = 0x0007 UA0 = 0x0041 UA1 = 0x0021 UA2 = 0x00D UA3 = 0x0082 UA4 = 0x0104
Poland	Waiting Tone	425	**0.15** – 0.15 – **0.15** – 4.0	U9F = 0x0003 UA0 = 0x000F UA1 = 0x000F UA2 = 0x000F UA3 = 0x0190
Portugal	Call Waiting Tone	425	**0.2** – 0.2 – **0.2** – 5.0	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x01F4

SILICON LABS

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Russia	Waiting Tone	950/1400/1800	**3×0.333** – 1.0	U9F = 0x0007
St.-Kitts-and-Nevis	Waiting Tone	440	**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
St. Lucia	Call Waiting Tone	425	**0.2** – 0.2 – **0.2** – 0.2	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x0014
Saudi Arabia	Call Waiting Tone	425	**0.15** – 0.2 – **0.15** – 10.0	U9F = 0x0003 UA0 = 0x000F UA1 = 0x0014 UA2 = 0x000F UA3 = 0x03E8
Sierra Leone	Waiting Tone	425	1.0	U9F = 0x0003 UA0 = 0x0064
Singapore	Call Waiting Tone	425	**0.3** – 0.2 – **0.3** – 3.2	U9F = 0x0003 UA0 = 0x001E UA1 = 0x0014 UA2 = 0x001E UA3 = 0x0140
Slovenia	Waiting Tone	425	**0.3** – 10.0	U9F = 0x0003 UA0 = 0x001E UA1 = 0x03E8
Solomon	Waiting Tone	400+450/400	**0.5** – 0.5	U9F = 0x0001 UA0 = 0x0032 UA1 = 0x0032
South Africa	Call Waiting Tone	400×33	**0.4** – 4.0	U9F = 0x0001 UA0 = 0x0028 UA1 = 0x0190
Spain	Call Waiting Tone	425	**0.175** – 0.175 – **0.175** – 3.5	U9F = 0x0003 UA0 = 0x0012 UA1 = 0x0012 UA2 = 0x0012 UA3 = 0x015E
Sri Lanka	Call Waiting Tone	425	**0.5** – 2.5	U9F = 0x0003 UA0 = 0x0032 UA1 = 0x00FA

Table 101. SAS Cadence for Supported Countries* (Continued)

Country	Tone	Frequency (Hz)	Cadence (seconds)	U Registers
Sweden	Call Waiting Tone I	425	**0.2** – 0.5 – **0.2**	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0032 UA2 = 0x0014
Tajikistan	Call Waiting Tone	950/1400/1800	**0.8** – 3.2	U9F = 0x0007 UA0 = 0x0050 UA1 = 0x0140
Trinidad and Tobago	Waiting Tone	440	**0.3** – 10.0	U9F = 0x0000 UA0 = 0x001E UA1 = 0x03E8
Turkey	Call Waiting Tone	450	**0.2** – 0.6 – **0.2** – 8.0	U9F = 0x0005 UA0 = 0x0014 UA1 = 0x003C UA2 = 0x0014 UA3 = 0x0320
Turks and Caicos Islands	Waiting Tone	440	**0.5** – 10.0 – **0.5**	U9F = 0x0000 UA0 = 0x0032 UA1 = 0x03E8 UA2 = 0x0032
United States	Call Waiting Tone	440	0.3	U9F = 0x0000 UA0 = 0x001E UA1 = 0x03E8 UA2 = 0x001E UA3 = 0x03E8
Uruguay	Waiting Tone	425	**0.2** – 0.2 – **0.2** – 4.4	U9F = 0x0003 UA0 = 0x0014 UA1 = 0x0014 UA2 = 0x0014 UA3 = 0x01B8
Vanuatu	Call Waiting Tone	425	**0.3** – 10.0	U9F = 0x0003 UA0 = 0x001E UA1 = 0x03E8
Zimbabwe	Call Waiting Tone	523/659	**1.5** – 1.5	U9F = 0x0003 UA0 = 0x0096 UA1 = 0x0096
*Note:	**Explanation of Symbols:** 1×f2　　f1 is modulated by f2. f1+f2　　the juxtaposition of two frequencies, f1 and f2, without modulation. f1/f2　　f1 is followed by f2. f1//f2　　in some exchanges, frequency f1 is used, and in others, frequency f2 is used.			

SILICON LABS

6.6. Intrusion/Parallel Phone Detection

The modem may share a telephone line with a variety of other devices, especially telephones. In most cases, the modem has a lower priority for access to the phone line. Someone dialing 911 in an emergency, for example, has a higher priority than a set-top box updating billing information. If someone is using a telephone, the modem should not go off-hook. If someone picks up a phone while the modem is connected or dialing, the modem should drop the connection and allow the phone call to proceed. The modem must monitor the phone line for intrusion in both the on-hook and off-hook conditions.

6.6.1. On-Hook Condition

When the ISOmodem is on-hook, the U79 [4:0] (LVCS) value represents Tip-Ring voltage; the ISOmodem is in the command mode, and the host can easily monitor LVCS with the AT:R79 command. A typical local loop has a Tip-to-Ring voltage greater than 40 V if all devices sharing the line (telephones, fax machines, modems, etc.) are on-hook. The typical local loop has a large dc impedance that causes the Tip-Ring voltage to drop below 25 V when a device goes off-hook. The host can monitor LVCS to determine whether the Tip-Ring voltage is approximately 40 V or something less than 25 V to determine if a parallel device is off-hook. This type of monitoring may also be performed with the %V1 command. Alternatively, the host could be programmed to periodically monitor LVCS and store the maximum value as the "all devices on-hook" line voltage and establish the on-hook intrusion threshold as a fraction (possibly 50%) of that value. This allows the system to adapt to different or changing local loop conditions. An on-chip adaptive monitoring algorithm may be enabled with the %V2 command.

6.6.1.1. Line Not Present/In Use Indication (Method 1—Fixed)

If enabled with %V1, this feature checks the line status before going off-hook and again before dialing. Before going off-hook with the ATD, ATO, or ATA command, the ISOmodem reads the line voltage and compares it to U83 (NOLN) [15:0] and U84 (LIUS) [15:0].

Loop Voltage	Action
$0 \leq$ LVCS $\leq$ U83	Report NO LINE and remain on-hook
U83 < LVCS $\leq$ U84 (U register)	Report LINE IN USE and remain on-hook
U84 < LVCS	Go off-hook and establish connection

A debouncing timer controlled by U-registers 50 and 51 prevents polarity reversals from being detected as a loss of loop current. The intrusion detection algorithm continues to operate if U77 (HOI) [11] is set. In this case, a parallel phone intrusion while off-hook gives a LINE IN USE result code to indicate the ISOmodem has gone on-hook due to a parallel phone intrusion.

Note: This method may not be as desireable as method 2, particularly for low-voltage lines.

Pros:

- Easy to understand and predict
- Allows reference level control

Cons:

- Chosen levels must work for all lines—not adaptive

6.6.1.2. Line Not Present/In Use Indication (Method 2—Adaptive)

This method is enabled through %V2. This feature checks the line status before going off-hook and again before dialing. While on-hook, the part monitors line voltage and updates U85 (5 (NLIU) [15:0] with this value.

Before going off-hook with the ATD, ATO, or ATA command, the ISOmodem reads the line voltage and compares it with the stored reference.

Loop Voltage	Action
$0 \leq LVCS \leq 6.25$ % x U85	Report NO LINE and remain on-hook
6.25 % x U85 < LVCS ≤ 85% x U85	Report LINE IN USE and remain on-hook
85% x U85 < LVCS	Go off-hook and establish connection

To prevent polarity reversals from being detected as a loss of loop current, a debounce timer controlled by U-registers 50 and 51 is used. However, if the HOI bit is set, a parallel phone intrusion while off-hook will give a LINE IN USE result code to indicate that the ISOmodem has gone on hook due to a parallel phone intrusion.

6.6.2. Off-Hook Condition

When the ISOmodem is off-hook, the U79 [4:0] (LVCS) value represents loop current. Additionally, the ISOmodem is typically in the data mode, and it is difficult for the host to monitor the LVCS value. For this reason, a controller-based off-hook intrusion algorithm is used.

There is a delay between the ISOmodem going off-hook and the start of the intrusion algorithm set by U77 [15:12] (IST) (Intrusion Settling Time). This avoids false intrusion detections due to loop transients during the on-hook to off-hook transition. The off-hook intrusion algorithm monitors the value of LVCS at a sample rate determined by U76 [15:9] (OHSR). The algorithm compares each LVCS sample to the reference value in U76 [4:0] (ACL). ACL = 0 at the first off-hook event after reset unless a value is written to it by the host. If ACL = 0, the ISOmodem does not begin the intrusion algorithm until after two LVCS samples have been received. If the host writes a non-zero value to ACL prior to the ISOmodem going off-hook, a parallel phone intrusion occurring during the IST interval and maintained until the end of the IST interval triggers a PPD interrupt. The ISOmodem also automatically updates ACL with the LVCS value while off-hook if an intrusion has not occurred. An ACL value can be written by the host and forced to remain unchanged by setting U76 [8] (FACL) = 1. If LVCS is lower than ACL by an amount greater than the value set in U76 [7:5] (DCL) (6 mA default) for two consecutive samples, U70 [2] (PPD), Parallel Phone Detect is set. If U70 [10] (PPDM) (Parallel Phone Detect Mask) is set to 1 (default condition), the $\overline{\text{INT}}$ pin in UART mode or the INT bit (Hardware Interface Register 1, bit 3) in parallel or SPI mode is also triggered. The host can monitor PPD or issue an AT:I to verify the cause of an interrupt and clear PPD. The host can take the appropriate action when the intrusion is confirmed.

The intrusion detection algorithm is as follows:

if LVCS(t) = LVCS (t – 40 ms x OHSR)

and ACL – LVCS(t) < DCL

then ACL = LVCS(t)

if (ACL – LVCS x (t – 40 ms x OHSR) > DCL

and ACL – LVCS x t > DCL

then PPD = 1

and the $\overline{\text{INT}}$ pin (or the INT bit in parallel or SPI mode) is asserted (PPDM = 1)

The ISOmodem can also be programmed to go on-hook automatically on a PPD interrupt by setting U77 (HOI) [11] (Hang-Up On Intrusion) to 1.

The off-hook intrusion algorithm may be suspended for a period defined by U78 [15:14] (IB) after the start of dialing. This guards against false PPD detects due to dial pulses or other transients caused by Central Office switching.

Table 102 lists the U registers and bits used for Intrusion Detection.

SILICON LABS

Table 102. Intrusion Detection

Register	Bit(s)	Name	Function
U70	10	PPDM	Parallel Phone Detect Mask
U70	2	PPD	Parallel Phone Detect
U76	15:9	OHSR	Off-Hook Sample Rate
U76	8	FACL	Force ACL
U76	7:5	DCL	Differential Current Level
U76	4:0	ACL	Absolute Current Level
U77	15:12	IST	Intrusion Settling Time
U77	11	HOI	Hang-Up On Intrusion
U78	15:14	IB	Intrusion Blocking
U78	7:0	IS	Intrusion Suspend
U79	4:0	LVCS	Line Voltage/Current Sense
U83	15:0	NOLN	No Line Threshold %V1
U84	15:0	LIUS	Line-in-use Threshold %V1
U85	15:0	NLIU	Line-in-use/No Line Threshold %V2

The ISOmodem has an internal analog-to-digital converter used to monitor the loop voltage when on-hook and loop current when off-hook to check for parallel devices going off-hook. The host measures loop voltage or current by reading U79 [4:0] (LVCS). To set the ISOmodem to monitor loop voltage in the on-hook state, the host issues the following commands:

Command	Function
AT:R79	Host reads the loop voltage from the LVCS Register U79 bits 4:0 while the modem is on-hook.

To set the ISOmodem to monitor loop current, the host issues the following commands:

Command	Function
ATH1	To go off-hook
AT:R79	Host reads loop current from the LVCS Register U79 bits 4:0 while the modem is off-hook.

6.7. Modem-On-Hold

The Si2494/93 supports modem-on-hold as defined by the ITU-T V.92 specification. This feature allows a connected Si2494/93 to place a server modem on hold while a second call, typically a voice call, uses the phone line. The maximum time the modems will remain on hold is controlled by the modem receiving the modem-on-hold request. Once the second call has ended, the Si2494/93 will reinitiate the data connection if the time elapsed has not exceeded the time negotiated by the two modems. The Si2494/93 can also be placed on hold itself by a remote modem allowing a far-end user to make or receive a voice call. Modem-on-hold is only supported on the Si2494/93 for V.34 (14400–33600 bps) and higher speed modulations. The AT+PMH command is used to enable (+PMH = 0) or disable (+PMH = 1) modem-on-hold.

6.7.1. Initiating Modem-On-Hold

Modem-on-hold is typically initiated when a connected client modem receives a subscriber alert signal (SAS) tone as described in "6.5. Type II Caller ID/SAS Detection" on page 151. However, it may be initiated any time the modem is on-line in command mode. The AT+PMHR command is used to initiate a modem-on-hold request. After this command is issued, the modem will place a modem-on-hold request to the server, and the +PMHR: command response will indicate the server's response to the request. The possible responses are shown in Table 103.

If the server refuses to grant a modem-on-hold request, the modem will use the +PMHT setting to determine what to do. If +PMHT = 0, the modem will remain connected to the server. If +PMHT is set to a non-zero value, the modems will disconnect. The Si2494/93 will indicate these conditions with the result code, "MHnack; Disconnecting…" or "MHnack; Reconnecting…"

Once modem-on-hold has been initiated, it may be necessary for the Si2494/93 to perform a hook-flash to indicate to the central office the incoming call may be accepted. This is initiated with the AT+PMHF command. The Si2494/93 will go on-hook for the time set in user register U4F and remain off-hook while on-hold. Usually, a second hook-flash is necessary to reestablish a data connection with the remote modem.

The Si2494/93 will attempt to reestablish a data connection with the remote modem upon receipt of the ATO command and will indicate the connection has been reestablished with the CONNECT message. If the modems fail to renegotiate the connection, the Si2494/93 will send the NO CARRIER message.

Table 103. Possible Responses to PMHR Command from Remote Modem

<Value>	Description
0	Modem-on-hold request denied or not available. The modem may initiate another modem-on-hold request at a later time.
1	MOH with 10 second timeout granted
2	MOH with 20 second timeout granted
3	MOH with 30 second timeout granted
4	MOH with 40 second timeout granted
5	MOH with 1 minute timeout granted
6	MOH with 2 minute timeout granted
7	MOH with 3 minute timeout granted
8	MOH with 4 minute timeout granted
9	MOH with 6 minute timeout granted
10	MOH with 8 minute timeout granted
11	MOH with 12 minute timeout granted
12	MOH with 16 minute timeout granted
13	MOH with indefinite timeout granted
14	MOH request denied. Future requests in the same session will also be denied.

SILICON LABS

6.7.2. Receiving Modem-On-Hold Requests

If modem-on-hold is enabled via the +PMH=1 command, the Si2493 may be placed on hold by a remote modem. The maximum time the modem will remain on hold is configured with the +PMHT setting. Possible values of +PMHT are given in Table 107. Upon receipt of a modem-on-hold request, the Si2493 will indicate +PMHR: followed by the code corresponding to the timeout granted. The DCD pin will be deasserted while the modem is on hold, and the CONNECT result code will indicate a return to data mode. A modem disconnect due to a timeout or failed negotiation will result in a NO CARRIER result code.

6.8. HDLC: Bit Errors on a Noisy Line

Bit errors can occur on an impaired line. The problem lies in determining and ignoring the spurious data resulting from poor line conditions and recovering valid data. This example illustrates a typical data-corruption problem due to a noisy line and the method used to analyze it. Here, the modem is an Si2404 configured with the following initialization string after reset.

```
AT+ES=6,,8
AT+ESA=0,0,0,,1,0
AT+ITF=0383,0128
AT:U87,010A
AT+MS=V22
AT:U7A,3
```

The following data stream was received over a noisy line.

```
0D 0A 43 4F 4E 4E 45 43 54 20 31 32 30 30 0D 0A 19 BE 20 20 19 B1 19 B0 19 B2 30 93
19 B1 19 B2 30 93 19 B1 19 B2 30 93 19 B1 19 B2 30 93 19 B1 19 B2 19 B2 B6 9E F7 46
19 B0 19 B2 29 C6 19 B0 19 B2 FF 98 89 18 19 B0 19 B2 92 6E EF 14 65 19 B0 19 B2 DA
BE C6 07 EA D8 31 C2 05 3C FA C8 86 C4 40 E6 19 A0 CA EA A8 F9 19 B2 8D 00 57 A5 43
29 19 B0 19 B2 05 CB 14 9F 7C 2D 19 B0 19 B2 19 B2 19 BA 0D 0A 4E 4F 20 43 41 52 52
49 45 52 0D 0A
```

First, the data will be analyzed to point out the occurrence of bit errors and spurious data. Secondly, a simple algorithm to filter the data will be proposed. Finally, the resulting valid data will be presented.

Table 104 lists an initial analysis of some recurring data patterns.

Table 104. Bit Errors

Data	Meaning
`19 B0`	Is an indication the modem has detected a pattern with more than 6 marks in a row. Once this occurs, the receiver begins looking for HDLC flags. Until the occurrence of HDLC flags, 19 B2 and subsequent data are discarded.
`19 B2`	This pattern has three meanings. ■ If the receiver is looking for HDLC flags, 19B2 means that the receiver has found an HDLC flag. ■ If 19B2 is received after a packet has started (prior data exists), the receiver assumes the CRC check does not match the FCS bytes sent by the remote transmitter and declares the packet bad. ■ An isolated 19 B2 pattern (no preceding data) is normal. This can occur when the following example data pattern is seen: 7E 7E XX 7E 7E (where XX can be up to 2 bytes of non-FLAG bit patterns at the DCE). The data can be analyzed as follows with valid data shown in bold.
`0D 0A 43 4F 4E 4E 45 43 54 20 31 32 30 30 0D 0A`	CONNECT 1200
`19 BE 20 20`	tx 1200 rx 1200
`19 B1`	Received first flag.
Beginning of Packet	
`19 B0`	A spurious byte received with more than 6 mark bits in a row. The modem is looking for HDLC flags.
`19 B2`	HDLC flag detected.
Beginning of Packet	
`30 93` **`19 B1`**	Good Packet.
Beginning of Packet	
`19 B2`	If a 1-bit error is received in an HDLC flag, the modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by modem.
Beginning of Packet	
`30 93` **`19 B1`**	Good Packet
Beginning of Packet	

SILICON LABS

Table 104. Bit Errors (Continued)

Data	Meaning
19 B2	A 1-bit error is received in an HDLC flag. The modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by modem.
Beginning of Packet	
30 93 **19 B1**	Good Packet
Beginning of Packet	
19 B2	A 1-bit error is received in an HDLC flag. The modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by modem.
Beginning of Packet	
30 93 **19 B1**	Good Packet
Beginning of Packet	
19 B2	A 1-bit error received in an HDLC flag. The modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by modem.
Beginning of Packet	
19 B2	A 1-bit error received in an HDLC flag. The modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by modem.
Beginning of Packet	
B6 9E F7 46	Spurious data
19 B0	Followed by a data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.
19 B2	HDLC Flag detected
Beginning of Packet	
29 C6	Spurious data
19 B0	Followed by a data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.
19 B2	HDLC Flag detected
Beginning of Packet	
FF 98 89 18	Spurious data
19 B0	Data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.

SILICON LABS

Table 104. Bit Errors (Continued)

Data	Meaning
19 B2	HDLC Flag detected
Beginning of Packet	
92 6E EF 14 65	Spurious data
19 B0	Data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.
19 B2	HDLC Flag detected
Beginning of Packet	
DA BE C6 07 EA D8 31 C2 05 3C FA C8 86 C4 40 E6	Spurious data
19 A0	Transparency code, represents 0x11 data byte found in receive data.
CA EA A8 F9	Spurious data
19 B2	Calculated CRC not equal FCS. The modem assumes this is a bad Frame.
Beginning of Packet	
8D 00 57 A5 43 29	Spurious data
19 B0	Followed by a data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.
19 B2	HDLC Flag detected
Beginning of Packet	
05 CB 14 9F 7C 2D	Spurious data
19 B0	Followed by a data byte with more than 6 mark bits in a row. The modem looks for HDLC flags.
19 B2	HDLC Flag Detected
19 B2	If there is 1-bit error received in an HDLC flag, the modem assumes a new single-byte packet. Since a 1-byte packet is invalid, 19 B2 is generated by the modem.
19 BA	Loss of Carrier Detected
0D 0A 4E 4F 20 43 41 52 52 49 45 52 0D 0A	NO CARRIER

The following steps will allow the spurious data and bit errors to be eliminated while preserving the valid data.

1. Ignore 19 B0.
2. Use 19 B2 to discard all collected receive data.

The filtered version of the HDLC frames, based on this algorithm, is shown below with the valid data in bold.

0D 0A 43 4F 4E 4E 45 43 54 20 31 32 30 30 0D 0A 19 BE 20 20 19 B1 19 B0 19 B2 **30 93**
19 B1 19 B2 **30 93 19 B1** 19 B2 **30 93 19 B1** 19 B2 **30 93 19 B1** 19 B2 19 B2 B6 9E F7 46
19 B0 19 B2 29 C6 19 B0 19 B2 FF 98 89 18 19 B0 19 B2 92 6E EF 14 65 19 B0 19 B2 DA
BE C6 07 EA D8 31 C2 05 3C FA C8 86 C4 40 E6 19 A0 CA EA A8 F9 19 B2 8D 00 57 A5 43
29 19 B0 19 B2 05 CB 14 9F 7C 2D 19 B0 19 B2 19 B2 **19 BA 0D 0A 4E 4F 20 43 41 52 52**
49 45 52 0D 0A

6.9. Overcurrent Detection

The ISOmodem has a built-in overcurrent detection feature (disabled by default) that measures loop current a programmable amount of time after going off-hook. This allows the modem to detect an improper line condition. The overcurrent detect feature is enabled by setting U70 [11] (OCDM) = 1. During the time after the modem goes off-hook, loop current is measured and set by U77 [8:0] (OHT). The default delay is 16 ms. After the delay, current is sampled every 1 ms. An overcurrent is detected if two consecutive samples indicate an overcurrent condition. If this feature is enabled and excessive current is detected, the ISOmodem sends the X result code and triggers an interrupt by asserting the INT pin or by setting the INT bit in the parallel or SPI mode. After an interrupt is received, the host issues the AT:I command to verify the OCD interrupt and clear the OCD bit. The delay between modem off-hook and loop current measurement is set by the OHT bits. OHT is a 9-bit register with 1 ms units. The default delay is 16 ms. When the modem is off-hook in an overload condition, LVCS = 11111 (full scale—overload error condition), an X is sent to the DTE, and the OCD bit is set.

The Overcurrent Detection feature is controlled by changing U-register settings. The registers and bits that control these features are shown in Table 105.

Table 105. Overcurrent Detection

Register	Bit	Value	Function
U67	7	DCR	DC Impedance Select
U70	11	OCDM	Overcurrent Detect Mask
U70	3	OCD	Overcurrent Detect
U77	8:0	OHT	Off-Hook Time
U79	4:0	LVCS	Line Voltage Current Sense

6.10. Pulse/Tone Dial Decision

There are three methods to detect whether a telephone line supports DTMF dialing or pulse dialing only. The first method, which is the simplest, may require the modem to go off-hook more than once. The second method is slightly more complicated but does not require the modem to go off-hook multiple times.

6.10.1. Method 1: Multiple Off-Hook Transitions

Use DTMF to dial the desired number with the ATDT command. If the line accepts tone dialing, the call is completed, and connection to the remote modem proceeds as usual.

If the line only allows pulse dialing, the modem hangs up and reports UN-OBTAINABLE NUMBER. This indicates that the modem detected a dial tone after the DTMF dial attempt. Dial the number again using the ATDP command instead of ATDT to use pulse dialing.

6.10.2. Method 2: Single Off-Hook Transition

Use this method if it is undesirable for the modem to go off-hook more than once or to DTMF dial a single digit. This method is somewhat more complicated and is best illustrated with an example, dialing the number 1234 below.

Set bit 7 of U-register 7A (U7A [7] (DOP) = 1) and send ATDT1;<CR> (Dial the first digit using DTMF and wait for a response). A response of OK indicates that DTMF digit 1 was sent, and the rest of the digits can be dialed. If a response of NO DIALTONE is received, the command failed because there was no dial tone (no line available), and the call cannot be completed.

If a response of OK is received after sending ATDT1;<CR>, continue by sending ATDTW;<CR> to perform the second dial tone detection and wait for a response. A response of NO DIALTONE indicates that no dial tone was detected for two seconds, and the line is DTMF capable. Complete the dialing by sending ATDT2345<CR> (DTMF dial beginning with the second number since the first number was successfully sent initially).

If an OK (dial tone present) was received after the ATDTW;<CR>, the line requires pulse dialing. Pulse dial the entire telephone number using ATDP12345<CR>.

6.10.3. Method 3: Adaptive Dialing

Adaptive dialing attempts to dial with DTMF, then falls back to pulse dialing. It is enabled with bit 6 of U7A. If bit 6 is set, the first digit is dialed with DTMF, and the ISOmodem waits two seconds. If a dial tone is still present, the first digit is resent with pulse dialing followed by the other digits in the dial string. If a dial tone is not present, the remaining digits are dialed with DTMF. Adaptive dialing does not select 10 pps vs. 20 pps dialing. This must be configured beforehand. In a PBX installation, this method typically results in pulse dialing, because the first digit dialed, usually 8 or 9, is used to obtain an outside line and therefore results in a dial tone.

6.10.4. Automatic Phone-Line Configuration Detection

The modem may automatically determine the following characteristics of the telephone line:
DTMF or pulse dialing only

- Determine if 20 pps is supported on a pulse dial only line.
- Identify it as an outside line or extension network (PBX).
- If connected to a PBX, determine if the dial tone is constant or make/break.
- If connected to a PBX, determine the number to dial for an outside line.

The AT&X1 command automatically determines the above parameters through a series of off-hooks and dialed digits.

Table 106. Automatic Phone Line Configuration

AT Command	Result Code

&X1	WXYZn
	W = 0 line supports DTMF dialing
	    1 line is pulse dial only
	X = 0 line supports 20 pps dialing
	    1 line supports 10 pps dialing only
	Y = 0 extension network (PBX)
	    1 connected to outside line
	Z = 0 continuous dial tone
	    1 make-break dial tone
	n = 0–9, number for outside line

6.10.5. Line Type Determination

The digit dialed to determine 10 pps vs. 20 pps is programmable through S51. The &X2 command works as described above; however, only DTMF/20 pps/10 pps determination is made (no PBX). The &X1 and &X2 commands may be aborted by sending the command, AT&X0. The result code will be OK.

SILICON LABS

6.11. Telephone Voting Mode

The telephone voting mode (TVM) of operation monitors the line to detect polarity reversals after dialing. It waits for a busy tone to be detected and reports POLARITY REVERSAL or NO POLARITY REVERSAL followed by OK.

To enable TVM, use the G character in the dial string (eg. ATDTG1). The G character must be used for each TVM call. The S7 timer operates during TVM and indicates NO CARRIER if a timeout occurs before the busy tone is detected. Polarity reversal monitoring begins after the last digit is dialed and ends at the detection of the busy tone. Any loss of line-side power (drop out) is considered a polarity reversal if loop current is restored within U51 milliseconds.

6.12. V.92 Quick Connect

The Si2493 supports ITU-T V.92 shortened Phase 1 and Phase 2 to decrease the time required to connect to a server modem using the V.90 modulation. After the first call, the Si2493 will retain line parameters that allow it to use shortened Phase 1 and 2 to reduce the total negotiation time. If line conditions change or the remote server does not support the shortening of these phases, the modem will automatically connect with the normal Phase 1 and Phase 2 negotiation unless specifically commanded not to. Two AT commands control this feature: AT+PQC and AT+PSS.

The AT+PQC command controls the enabling and disabling of shortened Phase 1 and Phase 2 individually according to Table 108. It is recommended that both shortened phases be used to realize the maximum reduction in connect time. The possible settings of the AT+PSS command are shown in Table 109. The AT+PSS command may be used to force quick connect by setting AT+PSS = 1; however, this is not recommended because calling a server that does not support this feature will result in a failed connection.

Table 107. Possible +PMHT Settings

<Value>	Description
0	Deny V.92 Modem-on-Hold Request
1	Grant MOH with 10 second timeout
2	Grant MOH with 20 second timeout
3	Grant MOH with 30 second timeout
4	Grant MOH with 40 second timeout
5	Grant MOH with 1 minute timeout
6	Grant MOH with 2 minute timeout
7	Grant MOH with 3 minute timeout
8	Grant MOH with 4 minute timeout
9	Grant MOH with 6 minute timeout
10	Grant MOH with 8 minute timeout
11	Grant MOH with 12 minute timeout
12	Grant MOH with 16 minute timeout
13	Grant MOH with indefinite timeout

Table 108. AT+PQC Parameters

<Value>	Description
0	Enable Short Phase 1 and Short Phase 2
1	Enable Short Phase 1
2	Enable Short Phase 2
3	Disable Short Phase 1 and Short Phase 2

Table 109. AT+PSS Parameters

<Value>	Description
0	The DCEs decide whether or not to use the short startup procedures. The short startup procedures shall only be used if enabled by the +PQC command.
1	Forces the use of the short startup procedures on the next and subsequent connections if they are enabled by the +PQC command.
2	Forces the use of the full startup procedures on the next and subsequent connections independent of the setting of the +PQC command.

7. Handset, TAM, and Speakerphone Operation

This section covers the voice functionality of the Si2494/39. The voice features of the Si2494/39 are divided into three major categories: handset, telephone answering machine (TAM), and speakerphone. The Si2494/39 implements ITU-T V.253 commands for TAM and speakerphone operation. The TAM voice compression support includes the following formats:

- Signed linear 8-bit, 64 kbps
- Unsigned linear 8-bit, 64 kbps
- G.711 µ-law 8-bit, 64 kbps
- G.711 A-law 8-bit, 64 kbps
- G.726 ADPCM 2-bit, 16 kbps
- G.726 ADPCM 4-bit, 32 kbps

All formats use a fixed 8 kHz sampling rate. For most applications, the user wants a high-quality message format (64 kbps) for the Outgoing Message (OGM) and is less concerned about the quality of the Incoming Message (ICM).

Speakerphone operation employs an acoustical echo canceller (AEC), acoustical echo suppressor (AES), double-talk detector (DTD), and line-echo canceller (LEC). This solution provides the following performance:

- Programmable echo tail filter length: up to 64 ms
- Convergence speed (white noise): less than 1.6 s
- Single-talk echo suppression: better than 48 dB
- Double-talk echo suppression: better than 30 dB

The software reference section presents the implemented V.253 AT Commands, V.253 <DLE> commands, V.253 <DLE> events, and U registers. The voice reference section covers the functional operation of handset, TAM, and speakerphone modes and includes use cases with programming examples.

7.1. Software Reference

7.1.1. AT Command Set

In Voice Command State, AT commands are used to control the DCE. The DCE responds with verbose response strings during Voice Command State. During the Voice Transmit, Voice Receive, and Voice Duplex States, the <DLE> shielded commands are used. The <DLE> events can appear in all states.

7.1.2. AT+ Extended Commands

Table 110. Extended AT+ Command Set

Command	Action
+FCLASS = <mode>	**Data/Voice Mode Selection** _<mode>_ _Description_ **0** **Data (default)** 8 Voice mode 256 SMS mode **Note:** An ATH command will automatically transition the DCE to +FCLASS=0.
+IPR = <rate>	**Fixed DTE Rate** _<rate>_ _Description_ **0** **Automatically detect the baud rate.** [BPS] The decimal value of the rate in bits per second. The <rate> parameter represents the DTE rate in bps and may be set to any of the following values: 300, 600, 1200, 2400, 4800, 7200, 9600, 12000, 14400, 19200, 38400, 57600, 115200, 230400, 245760, and 307200.

Table 110. Extended AT+ Command Set (Continued)

Command	Action
+VCDT = <n>	**Caller ID Type** _<n>_ _Description_ **0** **After ring only** 1 Always on 2 UK 3 Japan 4 DTMF after polarity reversal 5 DTMF after polarity reversal (off-hook reception) 6 Always-on DTMF 7 DTMF after ring
+VCID = <pmode>	**Caller ID Enable** _<pmode>_ _Description_ 0 Off 1 On—formatted 2 On—raw data format
+VDR = <enable>, <report>	**Distinctive Ring Cadence Reporting** _<enable>,<report>_ Mode 0, x Disable distinctive ring 1, 0 Enable distinctive ring. The DCE will report DROF and DRON result codes only. DROF and DRON are reported in 100 ms units. 1, 1 Enable distinctive ring. The DCE will report DROF and DRON result codes as well as well as a Ring result code x/10 seconds after the falling edge of a ring pulse. DROF and DRON are reported in 100 ms units.
+VGR = <gain>	**Receive Gain Selection** The <gain> parameter has a range of 112-134 with 128 marking the nominal value. **The default is 128, which represents 0 dB. Step size is 3 dB.** This represents a range of -48 dB to 18 dB. This command is used to control the receive gain at the DTE from either the Si3000 Codec or the DAA. The purpose is to adjust the DTE receive gain for the TAM voice stream during idle state. See the <DLE><d> and <DLE><u> commands discussed in Table 111 on page 178 for information on how to control the receive gain during active voice stream processing.
+VGT = <gain>	**Transmit Gain Selection** The <gain> parameter has a range of 112-134 with 128 marking the nominal value. **The default is 128, which represents 0 dB. Step size is 3 dB.** This represents a range of -48 dB to 18 dB. This command is used to control the transmit gain at the DTE to either the Si3000 Codec or the DAA. The purpose is to adjust the DTE transmit gain for the TAM voice stream during idle state. See the <DLE><d> and <DLE><u> commands discussed in Table 111 on page 178 for information on how to control the transmit gain during active voice stream processing.
+VIP	Load Voice Factory Defaults.
+VIT = <timer>	**DTE/DCE Inactivity Timer** The <timer> parameter has a range of 0-255 with units of seconds. **The default is 0 (disable).**

SILICON LABS

Table 110. Extended AT+ Command Set (Continued)

Command	Action

+VLS = <label>	**Analog Source / Destination Selection**
	<u><label></u> <u>Description</u>
	0 DCE is on-hook. AOUT disabled. Tone detectors disabled.
	                   Si3000 sample pass-through to DAA is inactive.
	1 DCE is off-hook. AOUT disabled. Tone detectors disabled.
	4 DCE is on-hook. AOUT connected to tone generators.
	                   Tone detectors disabled.
	5 DCE is off-hook. AOUT connected to PSTN.
	                   Tone detectors enabled.
	13 DCE is off-hook. V.253 tone event reporting enabled. Si3000 sample pass-through to DAA is active with options for speakerphone operation.
	14 DCE is on-hook. V.253 tone event reporting enabled. Si3000 interface is active for DTE voice stream pass-through.
	15 DCE is off-hook. V.253 tone event reporting enabled. Si3000 sample pass-through to DAA is active with options for handset operation.
	20 DCE is on-hook. AOUT disabled. Tone detectors enabled.
	21 DCE is on-hook. AOUT connected to tone generators. Tone detectors enabled.
	Table 117 on page 190 shows the voice-mode operation and the signal paths. See 10.2.4.2 of V.253 for an explanation of the AT +VLS=? command results. If an ATD command is sent while the DCE is in VLS=0 and +FCLASS=8, the DCE will automatically transition to VLS=1. The ATH command will automatically force the DCE to VLS=0. The main options of interest are the 0, 13, 14, and 5. The +VLS=0 setting must be applied first before applying a new +VLS value to ensure the mode is exited properly.

+VNH = <hook>	**Automatic Hangup Control** <u><hook></u> <u>Description</u> 0 The DCE retains automatic hangups as is normal in the other modes (such as hanging up the phone when the ISOmodem does not detect a data carrier with a given time interval). 1 The DCE shall disable automatic hangups in the other non-voice modes. 2 The DCE shall disable all hang-ups in other non-voice modes. The DCE shall only perform a "logical" hangup (return the OK result code).
+VRA = <interval>	**Ringing Tone Goes Away Timer** The DCE only uses this command in call origination transactions. This command sets the amount of time in 0.1 second units the DCE shall wait between Ringing Tone before it can assume that the remote modem has gone off-hook. Default time is five seconds.
+VRID = <rmode>	**Repeat Caller ID** <u><rmode></u> <u>Description</u> 0 Display Caller ID information of the last incoming call in formatted form. 1 Display Caller ID information of the last incoming call in unformatted form.

SILICON LABS

Table 110. Extended AT+ Command Set (Continued)

Command	Action
+VRN	**Ringing Tone Never Appeared Timer** This command sets the amount of time in seconds the DCE will wait looking for Ringing Tone. If the DCE does not detect Ringing Tone in this time period, the DCE shall assume that the remote station has gone off-hook and return an OK result code. Default time is 0 seconds.
+VRX	**Receive Voice Stream** Enable DTE receive of voice stream. The DCE will return a CONNECT response followed by the voice stream as defined by the +VSM command. The DTE can issue a <DLE><!> or <DLE><ESC> sequence to terminate the receive stream. The DCE will return a <DLE><ETX> followed by an OK response for <DLE><!> and <DLE><ESC> followed by an OK response for <DLE><ESC>. The DCE can be configured to terminate the stream using the DTE/DCE Inactivity Timer, which is configured using the +VIT command. The DTE will need to process any <DLE> shielded events present in the data stream. Any <DLE><DLE> sequences can be preserved to allow less overhead during playback of the stream with the +VTX command.
+VSD = <sds>, <sdi>	**Silence Detection** <u><sds></u> <u>Silence Detection Sensitivity</u> 118 More sensitive: lower noise levels considered to be silence 128 Nominal level of sensitivity. 138 Less sensitive: higher noise levels considered to be silence <u><sdi></u> <u>Silence Detection Interval</u> The time interval in 0.1 second units, which must contain no or little activity, before the DCE will report (QUIET) (<DLE><q>). Default is five seconds.

+VSM = <cml>	**Compression Selection Method**
	<u><cml></u> <u>Compression Mode</u>
	  0 Signed linear PCM, 8-bit, 64 kbps
	  1 Unsigned linear PCM, 8-bit, 64 kbps
	  4 G.711U µ-law companding PCM, 8-bit, 64 kbps
	  5 G.711A A-law companding PCM, 8-bit, 64 kbps
	 129 G.726 ADPCM, 2-bit, 16 kbps
	 131 G.726 ADPCM, 4-bit, 32 kbps
	All compression modes use a fixed sampling rate of 8 kHz. See 10.2.8.2 of V.253 for an explanation of the +VSM=? command results.

+VSP = <mode>	**Voice Speakerphone State**
	<u><mode></u> <u>Description</u>
	  0 **Speakerphone AEC, AES and LEC disabled. Handset FIR filter coefficients are selected.**
	  1 Speakerphone AEC, AES and LEC enabled. Speakerphone FIR filter coefficients are selected. The +VLS=13 command must be used in combination with this setting.

+VTD = <dur>	**DTMF / Tone Duration Timer** This command sets the default DTMF / tone generation duration in 10 ms units for the +VTS command. **Default time is 1 second (<dur> = 100).**

SILICON LABS

Table 110. Extended AT+ Command Set (Continued)

Command	Action
+VTS = [<freq1>, <freq2>, <dur>],[...]...	**DTMF and Tone Generation** This command can be used to produce single-frequency tones and double-frequency tones (i.e. DTMF digit). All three parameters are required for correct operation. <freq1>　　　　Frequency one, which has a range of 0, 200-3200 Hz. <freq2>　　　　Frequency two, which has a range of 0, 200-3200 Hz. <dur>　　　　Duration of the tone(s) in 10 ms units. For only a single tone, use <freq1> with zero value for <freq2>. Bracket syntax can be used to group sets of tones to generate simple melodies, e.g. +VTS=[500,0,10],[600,200,20],[700,250,30]
+VTX	**Transmit Voice Stream** Enable DTE transmit of voice stream to DCE. The DCE will return a CONNECT response. The DTE sends the voice stream as defined by the +VSM command. Any 0x10 character in the voice stream must be shielded with a <DLE>. The DTE issues a <DLE><ETX> sequence to terminate the transmit stream. The DCE will respond with <DLE><ETX> followed by OK. The DCE can be configured to terminate the stream using the DTE/DCE Inactivity Timer, which is configured using the +VIT command.

7.1.3. <DLE> Commands (DTE-to-DCE)

The characters listed in the Code column of Table 111 are referenced throughout this document with the <> notation. Simple action commands consist of a <DLE> character plus a simple action-command character (two bytes total).

Table 111. <DLE> Commands (DTE-to-DCE)

Format: <DLE>[Code]		
Code	**Hex**	**Simple Action Command Description**
<DLE>	0x10	The DTE must shield any 0x10 characters in the voice data stream sent to the DCE to avoid creation of a <DLE> simple-action command.
<SUB>	0x1A	More efficient representation of two 0x10 0x10 characters in the voice data stream.
<CAN>	0x18	Clear transmit buffer of voice data during +VTX session.
<NUL>	0x00	Do nothing. Refresh +VIT Inactivity Timer.
/	0x3C	Disable DTMF reporting.
~	0x2F	Enable DTMF reporting.
<ESC>	0x1B	End Voice Receive State started by the +VRX command.
!	0x21	Abort Voice Receive State started by the +VRX command.
u	0x75	Increase volume or gain during voice stream processing. For +VRX, increase the UBF and UC0 receive gains by 3 dB. For +VTX, increase the UB8 and UB3 transmit gains by 3 dB. The voice driver should track this command and update the +VGR or +VGT setting. Since this <DLE><u> command affects RS232 DAA and RS232 Si3000 gain registers, the voice driver should maintain two sets of +VGT and +VGR. The voice driver will need to know the +VLS state to determine if RS232 is connected to the Si3000 or the DAA. This command is only processed during an active +VRX or +VTX operation.
d	0x64	Decrease volume or gain during voice stream processing. For +VRX, decrease the UB3 and UB8 receive gains by 3 dB. For +VTX, decrease the UB8 and UB3 transmit gains by 3 dB. The voice driver should track this command and update the +VGR or +VGT setting. Since this <DLE><d> command affects RS232 DAA and RS232 Si3000 gain registers, the voice driver should maintain two sets of +VGT and +VGR. The voice driver will need to know the +VLS state to determine if RS232 is connected to the Si3000 or the DAA. This command is only processed during an active +VRX or +VTX operation.

SILICON LABS

7.1.4. <DLE> Events (DCE-to-DTE)
7.1.4.1. Simple Event Reporting

Table 112. <DLE> Simple Events (DCE-to-DTE)

Format: <DLE>[Code]		
Code	**Hex**	**Description**
<DLE>	0x10	The DCE will shield a 0x10 character in the voice stream to create a 0x10 0x10 sequence sent to the DTE.
<SUB>	0x1A	DLE DLE in datastream
<ETX>	0x03	End of voice stream data state.
X	0x58	Packet Header "Complex Event Detection Report". Implemented for CID and Distinctive Ring report only.
.	0x2E	Packet Terminator "Complex Event Detection Report". Implemented for CID and Distinctive Ring report only.
/	0x2F	DTMF tone detection started.
~	0x7F	DTMF tone detection ceased.
R	0x52	Ring incoming.
1	0x31	DTMF 1
2	0x32	DTMF 2
3	0x33	DTMF 3
4	0x34	DTMF 4
5	0x35	DTMF 5
6	0x36	DTMF 6
7	0x37	DTMF 7
8	0x38	DTMF 8
9	0x39	DTMF 9
0	0x30	DTMF 0
A	0x41	Extended keypad DTMF A
B	0x42	Extended keypad DTMF B
C	0x43	Extended keypad DTMF C
D	0x44	Extended keypad DTMF D
*	0x2A	Extended keypad DTMF E
#	0x23	Extended keypad DTMF F

Table 112. <DLE> Simple Events (DCE-to-DTE) (Continued)

		Format: <DLE>[Code]
Code	**Hex**	**Description**
o	0x6F	Receive buffer overrun
u	0x75	Transmit buffer underrun.
c	0x63	Fax Calling. DCE has detected T.30 1100 Hz tone.
e	0x65	Data Calling. DCE has detected V.25 1300 Hz tone.
h	0x68	Line voltage collapsed (phone line detached).
H	0x48	Line voltage restored (phone line reattached).
q	0x71	Presumed End of Message (QUIET).
l	0x6C	Loop current interruption.
b	0x62	Busy tone detected.
d	0x64	Dial tone detected.
r	0x72	Ringing tone detected.
p	0x70	Line voltage increased (parallel phone goes on-hook). DCE monitors loop current when off-hook and line voltage when on-hook.
P	0x50	Line voltage decreased (parallel phone goes off-hook). DCE monitors loop current when off-hook and line voltage when on-hook.
a	0x61	Fax or data answer. DCE has detected T.30 2100 Hz or V.21 1650 Hz answer tone.
f	0x66	Data answer. DCE has detected 2225 Hz, USB1 or AC answer sequence.
(	0x28	Negative (decreased) loop-current drift detected.
)	0x29	Positive (increased) loop-current drift detected.

SILICON LABS

7.1.4.2. Complex Event Reporting

Table 113. <DLE> Complex Event Reports (DCE-to-DTE)

Format: <DLE><X>[Response]<DLE><.>	
Response Tag	**Description**
DRON	Distinctive Ring Cadence On-time tag. See +VDR for details.
DROF	Distinctive Ring Cadence Off-time tag. See +VDR for details.
DATE	CID DATE tag. Full format is DATE=HHMM. Type I and II supported.
TIME	CID TIME tag. Full format is TIME=MMDD. Type I and II supported.
NMBR	CID NMDR tag. Full format is NMBR=<Number> or P or O. Type I and II supported.
NAME	CID NAME tag. Full format is NAME=<Listing>. Type I and II supported.
MESG	CID MESG tag. Full format is MESG=<Data Tag><Length of Message><Data><Checksum>. Type I and II supported.
TA, TB	Tone Detector A and B Format is TA=<tonestate> or TB=<tonestate> tonestate[31:16] millisecond timestamp tonestate[15:2] reserved tonestate[1] Tone B detected tonestate[0] Tone A detected

7.1.5. U Registers

This section presents the set of U registers needed for the voice modes.

Table 114. Voice Mode U Registers

Register	Address	Name	Description	Default
U72	0x0072	CDCCTRL	Si3000 Audio Codec Control Interface.	—
UB1	0x00B1	TXGAIN	Si3000-to-DAA Transmit Gain.	0x1000
UB3	0x00B3	TXGAIN1	RS232-to-DAA Transmit Gain.	0x1000
UB4	0x00B4	TXGAIN2	VTS-to-DAA Transmit Gain.	0x1000
UB5	0x00B5	RXGAIN	DAA-to-Si3000 Receive Gain.	0x1000
UB6	0x00B6	STGAIN	Si3000-to-DAA Side Tone Gain.	0x0000
UB8	0x00B8	TXGAIN3	RS232-to-Si3000 Transmit Gain.	0x1000
UB9	0x00B9	TXGAIN4	VTS-to-Si3000 Transmit Gain.	0x0000
UBF	0x00BF	RXGAIN1	DAA-to-RS232 Receive Gain.	0x1000
UC0	0x00C0	RXGAIN2	Si3000-to-RS232 Receive Gain.	0x1000

Table 114. Voice Mode U Registers (Continued)

Register	Address	Name	Description	Default
U156	0x0156	HTXFIR1		0x4000
U157	0x0157	HTXFIR2		0x0000
U158	0x0158	HTXFIR3		0x0000
U159	0x0159	HTXFIR4		0x0000
U15A	0x015A	HTXFIR5		0x0000
U15B	0x015B	HTXFIR6		0x0000
U15C	0x015C	HTXFIR7		0x0000
U15D	0x015D	HTXFIR8		0x0000
U15E	0x015E	HTXFIR9		0x0000
U15F	0x015F	HTXFIR10		0x0000
U160	0x0160	HTXFIR11	Handset TX FIR Filter Coefficients.	0x0000
U161	0x0161	HTXFIR12		0x0000
U162	0x0162	HTXFIR13		0x0000
U163	0x0163	HTXFIR14		0x0000
U164	0x0164	HTXFIR15		0x0000
U165	0x0165	HTXFIR16		0x0000
U166	0x0166	HTXFIR17		0x0000
U167	0x0167	HTXFIR18		0x0000
U168	0x0168	HTXFIR19		0x0000
U169	0x0169	HTXFIR20		0x0000
U16A	0x016A	HTXFIR21		0x0000

Table 114. Voice Mode U Registers (Continued)

Register	Address	Name	Description	Default
U16B	0x016B	HRXFIR1		0x4000
U16C	0x016C	HRXFIR2		0x0000
U16D	0x016D	HRXFIR3		0x0000
U16E	0x016E	HRXFIR4		0x0000
U16F	0x016F	HRXFIR5		0x0000
U170	0x0170	HRXFIR6		0x0000
U171	0x0171	HRXFIR7		0x0000
U172	0x0172	HRXFIR8		0x0000
U173	0x0173	HRXFIR9		0x0000
U174	0x0174	HRXFIR10		0x0000
U175	0x0175	HRXFIR11	Handset RX FIR Filter Coefficients.	0x0000
U176	0x0176	HRXFIR12		0x0000
U177	0x0177	HRXFIR13		0x0000
U178	0x0178	HRXFIR14		0x0000
U179	0x0179	HRXFIR15		0x0000
U17A	0x017A	HRXFIR16		0x0000
U17B	0x017B	HRXFIR17		0x0000
U17C	0x017C	HRXFIR18		0x0000
U17D	0x017D	HRXFIR19		0x0000
U17E	0x017E	HRXFIR20		0x0000
U17F	0x017F	HRXFIR21		0x0000
U196	0x0196	OUTLIM	Output Limiter Threshold.	0x5000
U197	0x0197	INLIM	Input Limiter Threshold.	0x2000
U199	0x0199	VPCTRL	This is a bit-mapped register.	—
U19A	0x019A	AECHLEN	AEC Filter Length.	0x0200
U19B	0x019B	AECDLY	AEC Adjustable Delay.	0x001F
U19C	0x019C	AECREFG	AEC Reference Gain.	0x1000
U19D	0x019D	AECMICG	AEC Microphone Gain.	0x1000
U19E	0x019E	AECNRG	This is a bit-mapped register.	—

Table 114. Voice Mode U Registers (Continued)

Register	Address	Name	Description	Default
U1A0	0x01A0	STXFIR1		0x0000
U1A1	0x01A1	STXFIR2		0x0000
U1A2	0x01A2	STXFIR3		0x0000
U1A3	0x01A3	STXFIR4		0x0000
U1A4	0x01A4	STXFIR5		0x0000
U1A5	0x01A5	STXFIR6		0x0000
U1A6	0x01A6	STXFIR7		0x0000
U1A7	0x01A7	STXFIR8		0x0000
U1A8	0x01A8	STXFIR9		0x0000
U1A9	0x01A9	STXFIR10		0x0000
U1AA	0x01AA	STXFIR11	Speakerphone TX FIR Filter Coefficients.	0x0000
U1AB	0x01AB	STXFIR12		0x0000
U1AC	0x01AC	STXFIR13		0x0000
U1AD	0x01AD	STXFIR14		0x0000
U1AE	0x01AE	STXFIR15		0x0000
U1AF	0x01AF	STXFIR16		0x0000
U1B0	0x01B0	STXFIR17		0x0000
U1B1	0x01B1	STXFIR18		0x0000
U1B2	0x01B2	STXFIR19		0x0000
U1B3	0x01B3	STXFIR20		0x0000
U1B4	0x01B4	STXFIR21		0x0000

SILICON LABS

Table 114. Voice Mode U Registers (Continued)

Register	Address	Name	Description	Default
U1B5	0x01B5	SRXFIR1		0x0000
U1B6	0x01B6	SRXFIR2		0x0000
U1B7	0x01B7	SRXFIR3		0x0000
U1B8	0x01B8	SRXFIR4		0x0000
U1B9	0x01B9	SRXFIR5		0x0000
U1BA	0x01BA	SRXFIR6		0x0000
U1BB	0x01BB	SRXFIR7		0x0000
U1BC	0x01BC	SRXFIR8		0x0000
U1BD	0x01BD	SRXFIR9		0x0000
U1BE	0x01BE	SRXFIR10		0x4000
U1BF	0x01BF	SRXFIR11	Speakerphone RX FIR Filter Coefficients.	0x0000
U1C0	0x01C0	SRXFIR12		0x0000
U1C1	0x01C1	SRXFIR13		0x0000
U1C2	0x01C2	SRXFIR14		0x0000
U1C3	0x01C3	SRXFIR15		0x0000
U1C4	0x01C4	SRXFIR16		0x0000
U1C5	0x01C5	SRXFIR17		0x0000
U1C6	0x01C6	SRXFIR18		0x0000
U1C7	0x01C7	SRXFIR19		0x0000
U1C8	0x01C8	SRXFIR20		0x0000
U1C9	0x01C9	SRXFIR21		0x0000
U1CD	0x01CD	LECHLEN	LEC Filter Length.	0x0020
U1CE	0x01CE	LECDLY	LEC Adjustable Delay.	0x002E

SILICON LABS

Table 115. U199 and U19E Register Bit Maps

Reg	Name	Bits 15-9	Bit8	Bit7	Bit6	Bits 4-5	Bit 3	Bit 2	Bit 1	Bit 0
U199	VPCTRL		SSP_LOCTALK	SSP_PTT	SSP_FLAG		MMUTE	SPCAL	SMUTE	
U19E	AECREF	SPKREF		MICREF						

The SMUTE bit (U199 [1]) mutes the speaker output audio path. The bit should be cleared for normal speakerphone operation. For recording during hands-free TAM, the bit should be set to mute the speaker output.

The MMUTE bit (U199 [3]) mutes the microphone input audio path. The bit should be cleared for the normal speakerphone operation. For message review during hands-free TAM, the bit should be set to mute the microphone.

Bit SPCAL (U199 [2]) in U199 must be set for speakerphone's calibration and cleared for normal speakerphone operation.

Bit fields SPKREF and MICREF in U19E contain the speakerphone's speaker and microphone levels during speakerphone calibration.

Table 116. U199 Bit Definitions

Bit	Name	Function
8	SSP_LOCTALK	1 = Local talker enabled 0 = Remote talker enabled Toggled by <DLE><0x27>
7	SSP_PTT	1 = Manually switch between near/far talker (push-to-talk mode) 0 = Automatically switch based on signal levels Toggled by <DLE><0x26>
6	SSP_FLAG	1 = Enable SSP mode 0 = Disable SSP mode Toggled by <DLE><0x25>
3	MMUTE	1 = Mute speaker of speakerphone or handset 0 = Unmute speaker
2	SPCAL	1 = AEC speaker / microphone calibration 0 = Normal mode
1	SMUTE	1 = Mute local talker 0 = Unmute local talker

7.2. Voice Reference—Overview

This document uses the term "handset mode" to describe the use of the microphone (MIC) and speaker (SPKRL/SPKRR) connections on the Si3000. The term "hands-free or speakerphone mode" describes the use of the line input (LINEI) and line out (LINEO) connections on the Si3000.

The term "handset" describes a handheld device containing a microphone and a speaker with a four-wire connection for microphone signal pair (MIC/MBIAS and GND) and speaker signal pair (SPKRL and GND or SPKRL and SPKRR). The Si3000 datasheet uses the term "handset" to describe a two-wire device that is connected directly to the Public Switch Telephone Network (PSTN). This two-wire device is referenced as a "telephone instrument" to avoid confusion.

The Si24xx-VMB EVB Rev. 2.0 mainboard with Si24xx2G-QFN Rev 1.0 daughtercard serves as the general evaluation platform for the Si2494/39 parts. See the Si24xx-VMB Global Voice ISOmodem EVB User's Guide for details.

Figure 29 illustrates the handset and speakerphone voice path. The gain registers in Figure 29 use a 4.12 format, with a range of 0x0001 (–72.247 dB) to 0xFFFF (24.082 dB). For the Si3000-to-DAA gain (UB1) and the DAA-to-Si3000 gain (UB5), a value of zero is used to disable the path.

The Si2494/39 enters voice mode with +FCLASS=8. Figure 30 illustrates the gain and signal selection options for the Si3000 codec. Table 117 provides a summary of how the +VLS command is used to control the various voice mode operations. Table 118 shows the summary of +FCLASS and IDLE state transitions and the expected responses.
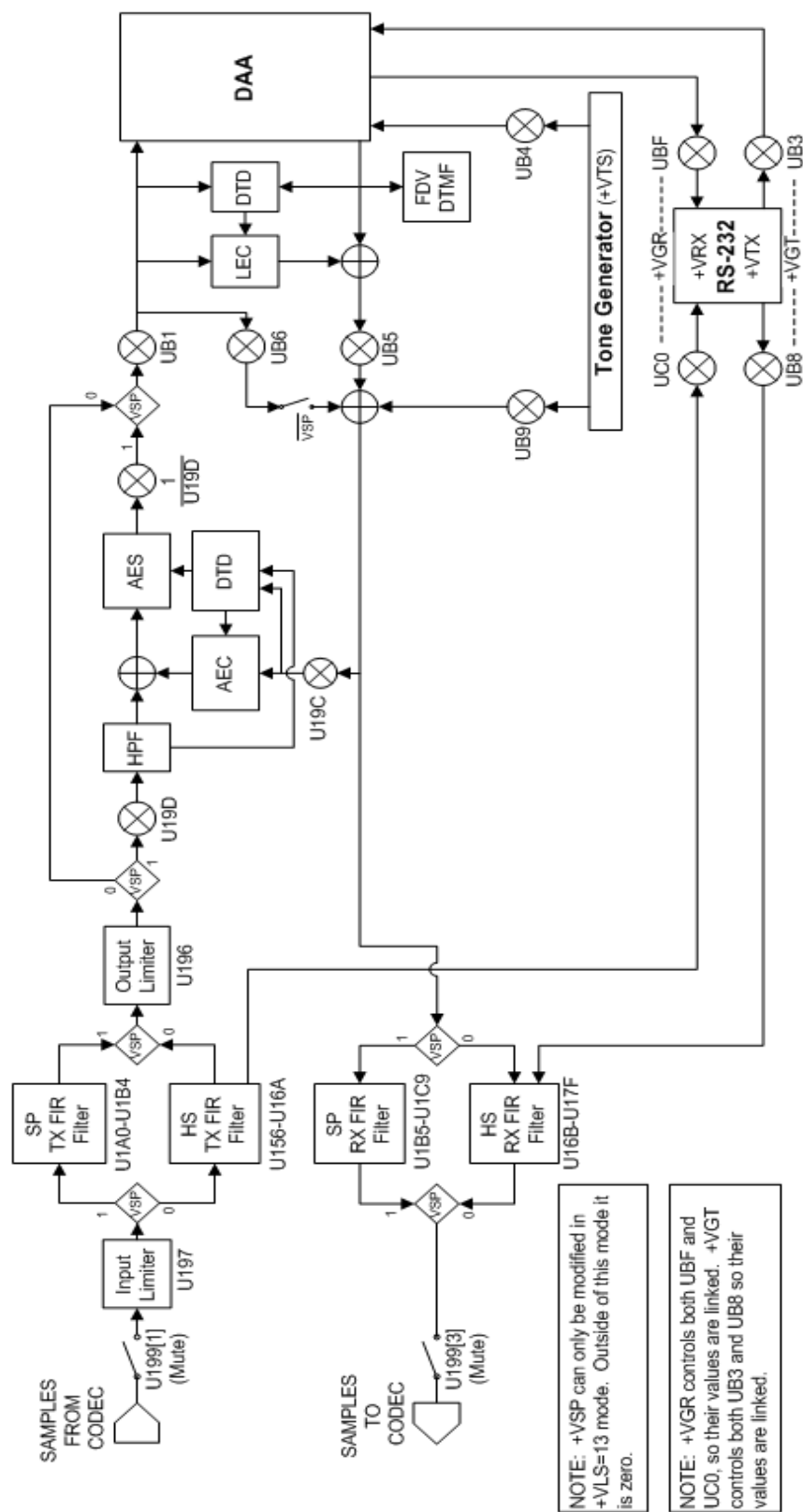
Figure 29. TAM, Handset, and Speakerphone Voice Paths
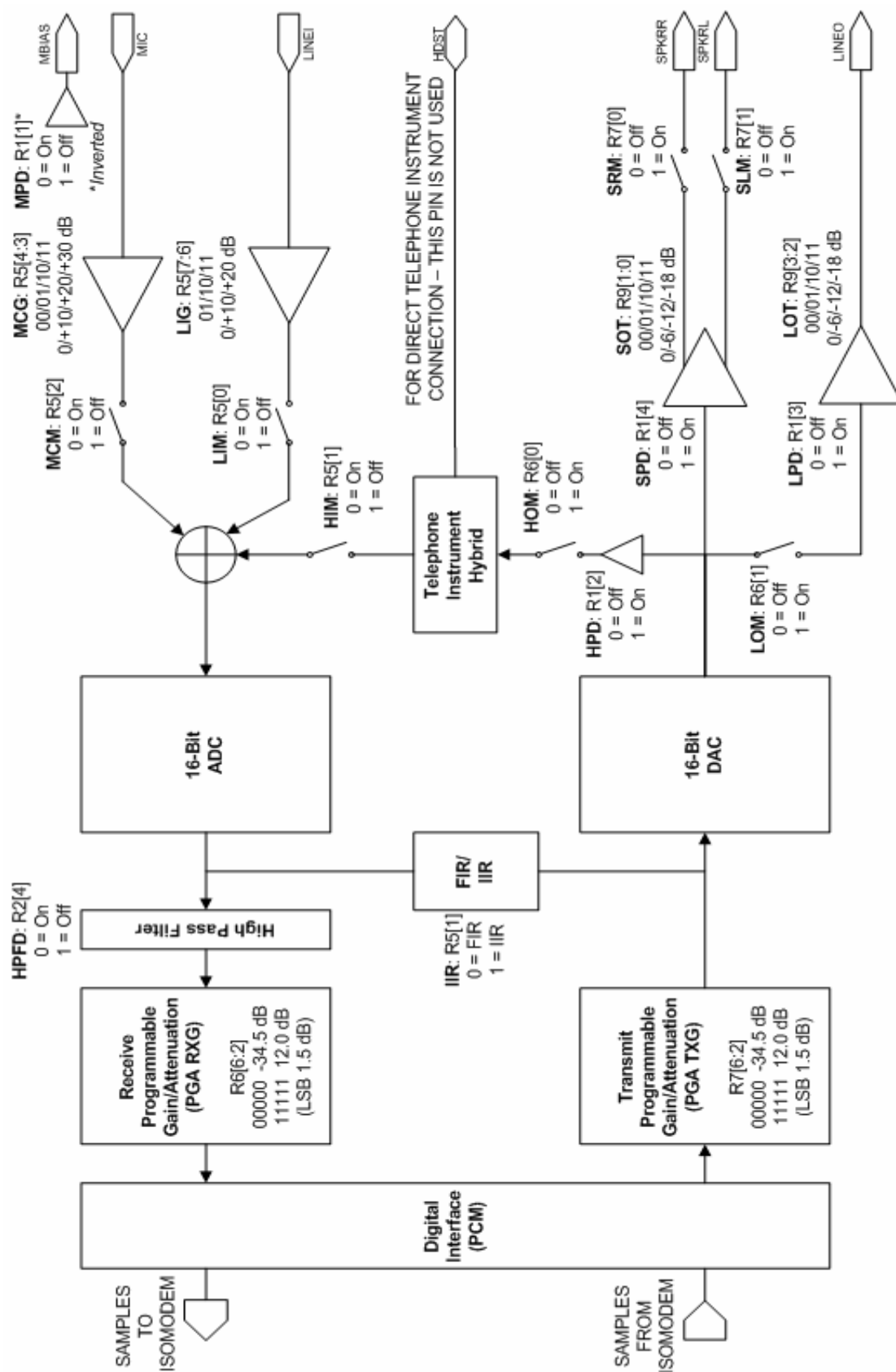
NOTE: +VSP can only be modified in +VLS=13 mode. Outside of this mode it is zero.

NOTE: +VGR controls both UBF and UC0, so their values are linked. +VGT controls both UB3 and UB8 so their values are linked.

SILICON LABS

Figure 30. Si3000 Codec Gain and Signal Selection Options

Table 117. Voice Mode Operations (+FCLASS=8)

+VLS Mode	Primitive	DAA	Active Detectors	Description	+VTX	+VRX	+VSP	+VTS
0	None	On-Hook	Ring, CID1	Voice mode is disabled.				
1	T	Off-Hook	FDV DTMF 2Tones*	TAM operation for call answer with OGM playback and record message using DTE voice stream pass through with no audio monitoring using Si3000.	RS232->DAA	DAA->RS232		RS232->DAA
4	S	On-Hook	Ring, CID1	Await call. Use +VTX for melody playback via AOUT.	RS232->AOUT			RS232->AOUT
5	ST	Off-Hook	FDV DTMF 2Tones*	Place call with audio call progress on AOUT. +VTS tone signal can be heard at AOUT via DAA echo-back.	RS232->DAA	DAA->RS232		RS232->DAA
13	M1S1T	Off-Hook	CID2 FDV DTMF 2Tones*	Speakerphone operation: Use +VSP=1 to enable AEC/LEC and speaker-phone FIR filters without side-tone gain. Only CID2 detector is active. Handset operation: Use +VSP=0 for handset operation with handset FIR filters and side tone gain. All the detectors are active. Same as +VLS=15 without TAM operation.			Si3000<-->DAA	RS232->DAA RS232->Si3000
14	H	On-Hook	Ring, CID1 FDV DTMF 2Tones*	TAM operation for OGM record and OGM/message playback via DTE voice stream pass through.	RS232->Si3000	DAA->RS232 Si3000->RS232		
15	HT	Off-Hook	CID2 FDV DTMF 2Tones*	Handset voice calls over Si3000<-->DAA path. TAM operation for call answer with OGM playback and record message using DTE voice stream pass through with audio monitoring using Si3000.	RS232->DAA RS232->Si3000	DAA->RS232 Si3000->RS232		RS232->DAA RS232->Si3000
20	S	On-Hook	Ring, CID1 FDV DTMF 2Tones*	Await call.				

SILICON LABS

Table 117. Voice Mode Operations (+FCLASS=8) (Continued)

+VLS Mode	Primitive	DAA	Active Detectors	Description	+VTX	+VRX	+VSP	+VTS
21	S	On-Hook	Ring, CID1 FDV DTMF 2Tones*	Await call with tone generator connections to AOUT for control beeps, ring tone, etc.				RS232->AOUT
* 2Tones = Detector for 2 programmed tones.								

Table 118. +FCLASS and IDLE State Transitions Expected Response

Input Command or Event	Current Modem Settings					
	+FCLASS=0,1			+FCLASS=8		
	+VNH = 0	+VNH = 1	+VNH = 2	+VNH = 0	+VNH = 1	+VNH = 2
ATH or DTR off (&D2)	ON-HK	ON-HK, +VNH = 0	OFF-HK, +VNH = 0	ON-HK, +FCLASS = 0 +VLS = 0	ON-HK, +VNH = 0, +FCLASS = 0 +VLS = 0	ON-HK, +VNH = 0, +FCLASS = 0 +VLS = 0
AT&F	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0 +VLS = 0	ON-HK, +VNH = 0, +FCLASS = 0 +VLS = 0	ON-HK, +VNH = 0, +FCLASS = 0 +VLS = 0
ATZ or DTR off (&D3)	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0	ON-HK +VNH = 0 +FCLASS = 0 +VLS = 0	ON-HK +VNH = 0 +FCLASS = 0 +VLS = 0	ON-HK +VNH = 0 +FCLASS = 0 +VLS = 0
Key Abort	ON-HK	OFF-HK	OFF-HK	ON-HK +VLS = 0	ON-HK +VLS = 0	ON-HK +VLS = 0
DCE Initiated disconnects	ON-HK	OFF-HK	OFF-HK	ON-HK	OFF-HK	OFF-HK
+FCLASS = 8	+FCLASS = 8 Go to IDLE Keep HK	+FCLASS = 8 Go to IDLE Keep HK +VNH = 0*	+FCLASS = 8 Go to IDLE Keep HK +VNH = 0*			
+FCLASS = 0,1	Go to IDLE Keep HK	Go to IDLE Keep HK	Go to IDLE Keep HK	+FCLASS = 0,1 Go to IDLE Keep HK	+FCLASS = 0,1 Go to IDLE Keep HK +VNH = 0*	+FCLASS = 0,1 Go to IDLE Keep HK +VNH = 0*

Notes:
1. "HK": Hook
2. "Keep HK": Maintain ON or OFF hook status.
3. *If no +VNH=x command executed since last +FCLASS change.

7.3. Si3000 Configuration

7.3.1. Microphone and Speaker Ports

The TAM and Speakerphone applications use two sets of microphones and speakers: one for the handset and one for hands-free operation. For the Si24xxVMB REV 2.0, the handset circuit uses the MIC input and SPKR_L output. The Si24xxVMB REV 2.0 allows configuration of the MIC, SPKR_L, and matching ground signals on any handset pinout. There is no industry standard for handset pinout. For the Si24xx-VMB REV 2.0, the speakerphone/hands-free TAM circuit uses the LINEI input and the LINEO output. The LINEO is sent to an external amplifier.

7.3.2. Register Settings

Figure 30 illustrates the register bit fields and corresponding values used to control the gain/attenuation, filtering, output drivers, and signal selection. From the software driver perspective, the Si3000 has three configuration groups that are applied for the given system states: handset, speakerphone, and hands-free TAM. For applications requiring handset recording of the OGM, the software may use a fourth configuration for handset TAM. These configuration groups define the digital gains, analog gains, and control bit settings for registers 1, 5, 6, 7, and 9 of the Si3000. Speakerphone algorithm includes input and reference gains that require a lower gain in the Si3000. For Hands-Free TAM, the speakerphone voice path is disabled, so a higher analog gain can be used.

7.3.3. System Voice Modes

A system voice mode consists of the Si24xx ISOmodem and Si3000 settings combined with the PSTN status to achieve a desired function. These modes describe the status of the hook switch, the modem voice path, Si3000 configuration (input, output, and gains), and the allowed operations. Figure 31 illustrates the transition events among these modes.

7.3.3.1. TAM Hands-Free

This is the general idle mode for recording an OGM/local message (+VRX) and reviewing an ICM/local message (+VTX). All detectors are functional and incoming rings are indicated on the speaker via a tone or a melody. The modem is on-hook routing audio between the Si3000 and the DTE interface. The modem voice path is configured for half-duplex audio with speakerphone algorithm disabled. The Si3000 audio transmit and receive path is muted/unmuted to allow half-duplex control for proper TAM operations. Side tone is disabled. Handset TX/RX coefficients are applied. The Si3000 is using the LINEI and LINEO signals with hands-free TAM gain settings.

7.3.3.2. TAM Handset

This is variation to the TAM Hands-Free mode above, with the exception that the handset is used to review a locally-recorded message or ICM privately. The Si3000 is using the MIC and SPKRR and/or SPKRL signals with handset gain settings. A raised handset usually triggers off-hook transition, so the controller would have to support a special mode to not switch off-hook into Handset mode.

7.3.3.3. Speakerphone

This mode is used to conduct a hands-free voice call. The modem is off-hook and routing audio between Si3000 and DAA. The modem voice path is configured for full-duplex audio with speakerphone algorithm enabled. Side tone is disabled. Speakerphone TX/RX filter coefficients are applied. The Si3000 is using the LINEI and LINEO signals with speakerphone gain settings.

7.3.3.4. Handset

This mode is used to conduct a private voice call. The modem is off-hook and routing audio between the Si3000 and DAA. The modem voice path is configured for full-duplex audio with speakerphone algorithm disabled. Side tone is enabled. Handset TX/RX filter coefficients are applied. The Si3000 is using the MIC and SPKRR and/or SPKRL signals with handset gain settings. This mode is supported by all parts.

7.3.3.5. TAM PSTN

This mode is used to answer an incoming call with OGM playback and ICM recording. The caller may perform local TAM operations (i.e. record OGM, review ICM) via remote DTMF control. The modem is off-hook routing audio between the DAA and the DTE interface; however, audio is also available at the Si3000 (via UB5 path) so call screening is possible via the speaker (LINEO) while the microphone is muted. The modem voice path is configured for half-duplex audio with the speakerphone algorithm disabled. Side tone is disabled. Handset TX/RX coefficients are applied. The Si3000 is using the LINEI and LINEO signals with speakerphone gain settings. This mode is supported by the Si2418/29/36/38 parts.
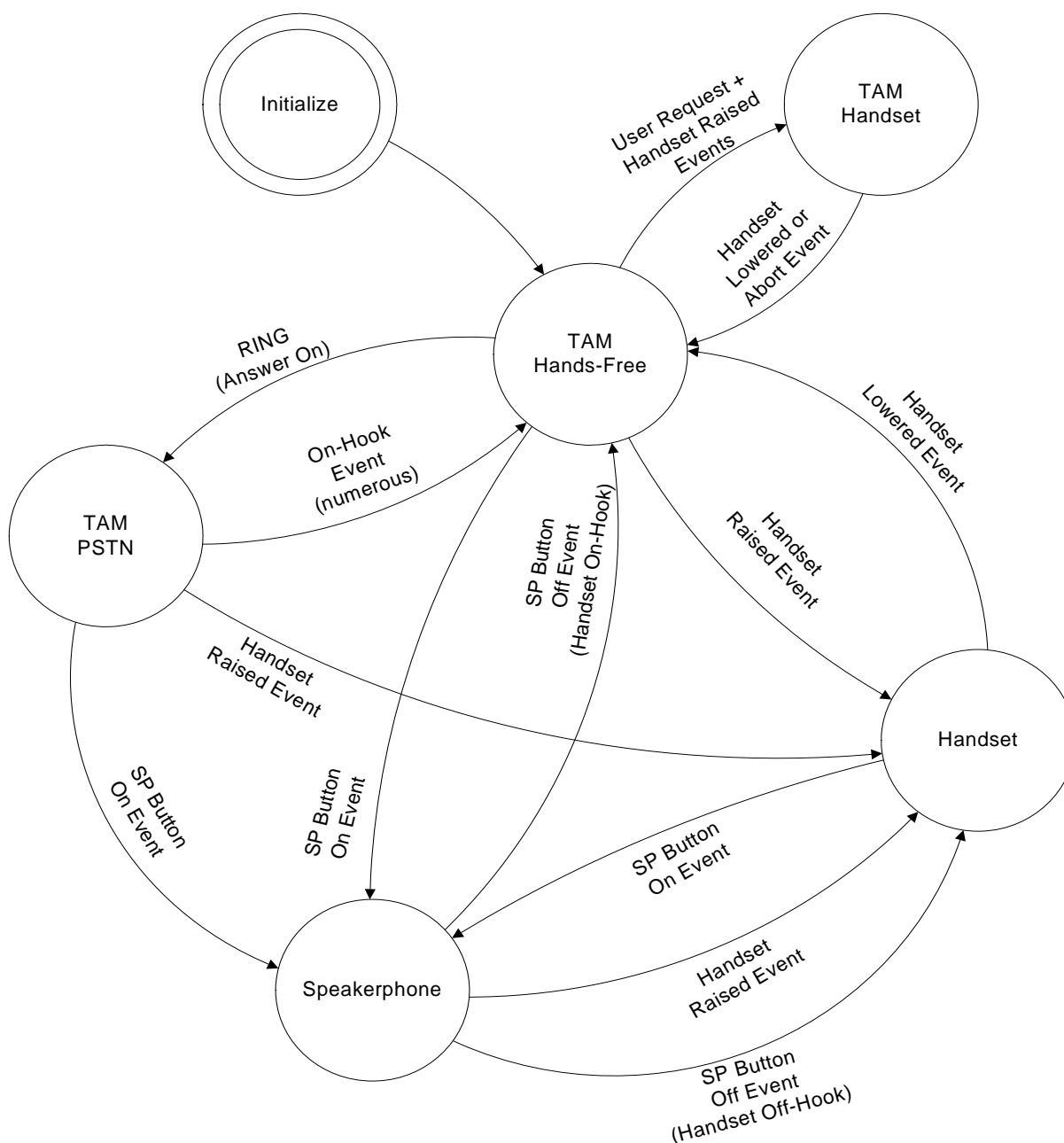
Figure 31. System Voice Modes

7.4. Initialization

The following sequence is used after power up or hardware reset to prepare the modem for voice operations. This procedure occurs in the Initialize state presented in Figure 31. After initialization, the system will be in the TAM Hands-Free mode, which is discussed in "7.3.3.1. TAM Hands-Free".

Table 119. Initialization Sequence

Host to Modem Commands	Modem to Host Result Codes	Local Modem Actions
ATZ	OK	Reset. The Si3000 is not reset by this command.
ATE0+FCLASS = 0	OK	Disable local AT command echo and enter data mode, which is necessary for patch loading.
AT+IPR = 115200	OK	Disable autobaud and set rate to 115,200 bps.
[Apply Patch Commands]	OK	Apply the modem patch commands.
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
ATE0+FCLASS = 8	OK	Disable local AT command echo and enter voice mode. Limited V.253 event reporting enabled with default setting of +VLS=0.
AT+VLS = 0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS = 14	OK	Setup on-hook TAM voice mode. See Table 117 on page 190 for details.
AT*Y254:W59|1	OK	Enable the SSI interface to the Si3000.
AT*Y0	OK	Exit the AT*Y command mode.
AT+VCDT = 1	OK	Enable always-on Type I Caller ID.
AT+VCID = 1	OK	Enable formatted Caller ID.
AT+VSD = 129	OK	Set silence detection sensitivity level.
AT+PCW = 0	OK	Enable Type II Caller ID reporting.
AT:U0B1,0500	OK	Set Si3000-to-DAA transmit gain.
AT:U0B5,0200	OK	Set DAA-to-Si3000 receive gain.
AT:U0B6,0100	OK	Set Sidetone gain.
AT:U0B9,0300	OK	Set VTS-to-Si3000 transmit gain.
AT:U0B4,0600	OK	Set VTS-to-DAA transmit gain.

SILICON LABS

Table 119. Initialization Sequence (Continued)

AT:U196,5000	OK	Set output limiter threshold gain.
AT:U197,2000	OK	Set input limiter threshold gain.
AT:U19C,2400	OK	Set AEC reference gain.
AT:U19D,1800	OK	Set AEC microphone gain.
AT:U19A,01E0	OK	Set AEC filter length.
AT:U19B,001F	OK	Set AEC adjustable delay.
AT:U04F,01F4	OK	Set flash hookswitch period.
AT:U156,FF10,FFA2,FFD7,FF35,FEF3,FE68,FB7E	OK	Set Handset Transmit FIR coefficients.
AT:U15D,F90C,FDDF,091D,4F51,091D,FDDF,F90C	OK	
AT:U164,FB7E,FE68,FEF3,FF35,FFD7,FFA2,FF10	OK	
AT:U16B,0041,00B1,00AA,0001,FF92,0042,0183	OK	Set Handset Receive FIR coefficients.
AT:U172,0165,FEC0,FB05,3940,FB05,FEC0,0165	OK	
AT:U179,0183,0042,FF92,0001,00AA,00B1,0041	OK	
AT:U1A0,0000,0000,0000,0000,0000,0000,0000	OK	Set Speakerphone Transmit FIR coefficients.
AT:U1A7,0000,0000,0000,0000,0000,0000,0000	OK	
AT:U1AE,0000,0000,0000,0000,0000,0000,4000	OK	
AT:U1B5,0173,0273,045A,043B,0121,FD54,FE41	OK	Set Speakerphone Receive FIR coefficients.
AT:U1BC,0197,0543,FD03,30D6,FD03,0543,0197	OK	
AT:U1C3,FE41,FD54,0121,043B,045A,0273,0173	OK	
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,05D7	OK	Configure Si3000 Register 5: 20 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output

Table 119. Initialization Sequence (Continued)

AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT:U0B1,0	OK	Disable Si3000-to-DAA transmit gain path. This ensures codec tones are not sent to the FDV and DTMF.
AT:U0B5,0	OK	Disable DAA-to-Si3000 receive gain path. This ensures line events such as CID and ring tone are not heard via the codec.
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.

7.5. Handset

7.5.1. Overview

This mode uses the voice pass-through connection to route SSI data between the Si3000 and the DAA. The modem remains in AT command mode and provides V.253 event notifications. The host controller is responsible for detecting the status of the handset position. The following sections provides detailed examples of originating and answering a voice call with the handset.

7.5.2. Handset Configuration

Table 120 contains the initial configuration that is used by all dialing use cases. The sequence is also sent for the answer case. The user will have been notified of the incoming call through a local +VTS ring tone and a raised handset event would prompt the Handset Configuration sequence to answer the call. The UB1, UB5, UB6, and Si3000 register configuration vary with the customer's production hardware. The UB5 register serves as the general volume control in this mode.

SILICON LABS

Table 120. Handset Configuration

Host to Modem Commands / Data	Modem to Host Result Codes/ Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS=13	OK	Setup off-hook voice mode. See Table 117 on page 190 for details.
AT:U0B1,0500	OK	Restore Si3000-to-DAA transmit gain path.
AT:U0B5,0200	OK	Restore DAA-to-Si3000 receive gain path.
AT:U72,0110	OK	Configure Si3000 Register 1: Enable speaker driver Disable line output driver Disable telephone instrument driver Enable MBIAS output
AT:U72,05B3	OK	Configure Si3000 Register 5: 10 dB Line In gain Mute Line In 20 dB MIC input gain Enable MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065C	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Disable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VSP=0	OK	Select handset voice path. See Figure 29 on page 188 for details.
AT:U199&FFF5	OK	Enable the microphone and speaker paths to the codec.

AN93

7.5.3. Call – Automatic Tone Dial

Table 121 lists the commands that occur after the configuration defined in Table 120.

Table 121. Handset Automatic Tone Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATDT102	OK	Perform automatic tone dial of 102. Modem will return OK. Depending on the number of rings the host may receive <DLE><r> events for ring-back notifications. If the line is busy, a <DLE><b> event will be sent to the host. After connection, the host will receive <DLE><q> events during quiet periods of no voice.

7.5.4. Call – Manual Off-Hook Tone Dial

Table 122 lists the commands that occur after the configuration defined in Table 120.

Table 122. Handset Manual Off-Hook Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VTS=[697,1209,20]	OK	The user is free to dial manually using the +VTS commands to create the DTMF digits. Generate DTMF 1 digit for 200 ms.
AT+VTS=[941,1336,20]	OK	Generate DTMF 0 digit for 200 ms. Generate DTMF 2 digit for 200 ms.
AT+VTS=[697,1336,20]	OK	Depending on the number of rings the host may receive <DLE><r> events for ring-back notifications. If the line is busy, a <DLE><b> event will be sent to the host. After connection, the host will receive <DLE><q> events during quiet periods of no voice.

7.5.5. Call – Automatic Pulse Dial

Table 123 lists the commands that occur after the configuration defined in Table 120.

Table 123. Handset Automatic Pulse Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATDP102	OK	Perform automatic pulse dial of 102. Modem will return OK. Depending on the number of rings the host may receive <DLE><r> events for ring-back notifications. If the line is busy, a <DLE><b> event will be sent to the host. After connection, the host will receive <DLE><q> events during quiet periods of no voice.

7.5.6. Answer

A ring event will prompt the user to lift the handset. This will generate a Handset Raised Event and the Handset Configuration procedure defined in Table 120 should be used to answer the call. For ring detection and local ring tone/melody generation, see "7.6.2. TAM Hands-Free—Idle" .

7.5.7. Terminate

Upon detection of the Handset Lowered Event, the host should issue the commands in Table 124 to transition to the TAM Hands-Free mode.

Table 124. Handset to TAM Hands-Free Transition

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT+VSP=0	OK	Select handset voice path. See Figure 29 on page 188 for details. +VSP must be zero when exiting from +VLS=13.
AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS=14	OK	Setup on-hook voice mode. See Table 117 on page 190 for details. This will return the modem to on-hook state.
AT:U0B1,0	OK	Disable Si3000-to-DAA transmit gain path. This ensures codec tones are not sent to the FDV and DTMF.
AT:U0B5,0	OK	Disable DAA-to-Si3000 receive gain path. This ensures line events such as CID and ring are not heard via the codec.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,05D7	OK	Configure Si3000 Register 5: 20 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.

SILICON LABS

7.5.8. Speakerphone Transition

In the Handset mode, the SP Button On Event will trigger the transition from Handset to Speakerphone mode. See "7.7. Speakerphone" on page 212 for details on Speakerphone mode. The voice driver should track the handset hook switch state, such that if the user exits Speakerphone mode, the system will switch back to Handset configuration without losing the active call.

Table 125. Handset to Speakerphone Transition

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,05D7	OK	Configure Si3000 Register 5: 20 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VSP=1	OK	Enable speakerphone voice path. See Figure 29 on page 188 for details.
AT:U199&FFF5	OK	Enable the microphone and speaker paths to the codec.

SILICON LABS

7.6. Telephone Answering Machine

7.6.1. Overview

The Si2494/39 supports telephone answering machine (TAM) operations. These parts use the V.253 command set to control operation. This section covers the three major TAM-related system voice modes. Some modes offer multiple operations.

The TAM Hands-Free mode is the general voice idle mode. It is used for OGM recording/review and local ICM recording/review via hands-free operation. The TAM Handset mode is similar to TAM Hands-Free except that the audio is handled over the handset. The TAM PSTN mode is for playback of the OGM and recording the ICM. The TAM PSTN mode also permits remote OGM and ICM record/review via DTMF tone control. The +VTX command is used to play voice menu options/prompts. **All the use cases in this section start with the modem in TAM Hands-Free mode, which is configured in the initialization sequence in Table 119 on page 194.**

7.6.2. TAM Hands-Free—Idle

The modem will use the events listed in Table 112 on page 179 to communicate status. The <DLE><R> event indicates ring detection. The +VTS command can be used to play one or more single/dual tone sequences. If enabled, Type I CID is decoded after the first ring and sent via a complex <DLE> event report. See Table 126 for details.

Table 126. Local Ring Notification with Type I CID Event

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
	<DLE><R>	Ring Detection
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><X> CIDM DATE=0101 TIME=0110 NMBR=102 NAME=JONES JENNIFER <DLE><.>	Receive Type I CID DLE complex report.
	<DLE><R>	Ring Detection.
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><R>	Ring Detection. The voice driver will use a rings-to-answer count. This example uses three rings before answer.
AT+VTS=[700,500,80]	OK	Play local ring tone.

Based upon the TAM answer function settings, a ring counter will validate the number of rings before answer. If the TAM Answer function is disabled or the number of rings before answer has not been reached, the user has the opportunity to answer the call via handset or speakerphone.

7.6.2.1. Record OGM

The Si3000-to-RS232 gain register UC0 in the ISOmodem can be used to adjust the voice stream gain. Use the +VGR command to adjust the UC0 value in command mode. It is best to maintain two versions of +VGR: one for Si3000-to-RS232 and another for DAA-to-RS232.

Table 127. TAM Hands-Free Record OGM

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VGR=128	OK	Set the Si3000-to-RS232 receive gain (UC0) for TAM Hands-Free.
AT:U0B1,0500	OK	Restore Si3000-to-DAA transmit gain path to allow voice samples to reach FDV block for silence detection. This allows the driver to automatically end OGM recording.
AT+VSD=129	OK	Set sensitivity level for OGM recording silence detection.
AT+VSM=4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.
AT+VTS=[1000,0,100]	OK	Play user record tone prompt.
AT:U199|8	OK	Mute speaker to avoid echo (speakerphone algorithm off).
AT:U199&FFFD	OK	Enable microphone for OGM recording.
AT+VRX	CONNECT	Trigger receive operation. The first byte after the new-line character following the CONNECT message will be the first data stream byte.
	[Voice Stream]	Receive OGM voice stream. During voice stream capture, the user can adjust the UC0 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGR value for future use.
<DLE><!>	<DLE><ETX> OK	Terminate the receive operation. The modem will respond with <DLE><ETX> to mark the end of the data stream. The OK denotes the return to command mode.
AT:U0B1,0	OK	Disable Si3000-to-DAA transmit gain path. This ensures codec tones are not sent to the FDV and DTMF.
AT:U199|2	OK	Mute the microphone.
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.

SILICON LABS

7.6.2.2. Review OGM

The RS232-to-Si3000 gain register UB8 in the ISOmodem can be used to adjust the voice stream gain. Use the +VGT command to adjust the UB8 value in command mode. It is best to maintain two versions of +VGT: one for RS232-to-Si3000 and another for RS232-to-DAA.

Table 128. TAM Hands-Free Review OGM

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VGT=128	OK	Set the RS232-to-Si3000 transmit gain (UB8) for TAM Hands-Free.
AT+VSM=4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.
AT+VTX	CONNECT	Trigger transmit operation.
	<DLE><u>	TX Underrun. Appears at the start of +VTX before transmit data are seen.
[Voice Stream]		Transmit OGM voice stream. During voice stream capture, the user can adjust the UB8 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGT value for future use.
<DLE><ETX>	OK	Terminate the transmit operation. The modem will respond with OK to denote the return to command mode.

7.6.2.3. Record Local ICM

The Record Local ICM is identical to the Record OGM procedure provided in Table 127 on page 202. The main difference is that one of the ADPCM formats is generally used and the PCM file is stored with the other ICM files recorded from the PSTN.

7.6.2.4. Review ICM

The Review ICM is identical to the Review OGM procedure provided in Table 128 on page 203. The main difference is that one of the ADPCM formats is generally used to conserve message space.

7.6.2.5. Speakerphone Transition

The SP Button On Event will trigger this transition. See Table 136 on page 219 for configuration sequence.

7.6.2.6. Handset Transition

The Handset Raised Event will trigger this transition. See Table 120 on page 197 for configuration sequence.

7.6.3. TAM Handset

Using the handset to record the OGM will result in better message quality. The handset can also be used to screen messages in private. The host will need to correctly process the Handset Raised Event to keep the modem on-hook during record/review operations.

7.6.3.1. Record OGM

The host will prompt the user to lift the handset to begin OGM recording. The procedure restores the TAM Hands-Free settings before completion.

Table 129. TAM Handset Record OGM

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0110	OK	Configure Si3000 Register 1: Enable speaker driver Disable line output driver Disable telephone instrument driver Enable MBIAS output
AT:U72,05B3	OK	Configure Si3000 Register 5: 10 dB Line In gain Mute Line In 20 dB MIC input gain Enable MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065C	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Disable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VGR=128	OK	Set the Si3000-to-RS232 receive gain (UC0) for TAM Hands-Free.
AT:U0B1,0500	OK	Restore Si3000-to-DAA transmit gain path to allow voice samples to reach FDV block for silence detection. This allows the driver to automatically end OGM recording.
AT+VSD = 129	OK	Set sensitivity level for OGM recording silence detection.
AT+VSM = 4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.
AT+VTS = [1000,0,100]	OK	Play user record tone prompt.
AT:U199|8	OK	Mute speaker.
AT:U199&FFFD	OK	Enable microphone for OGM recording.

SILICON LABS

Table 129. TAM Handset Record OGM (Continued)

AT+VRX	CONNECT	Trigger receive operation. The first byte after the newline character following the CONNECT message will be the first data stream byte.
	[Voice Stream]	Receive OGM voice stream. During voice stream capture, the user can adjust the UC0 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGR value for future use.
<DLE><!>	<DLE><ETX> OK	Terminate the receive operation. The modem will respond with <DLE><ETX> to mark the end of the data stream. The OK denotes the return to command mode. A Handset Lowered Event, timeout, or silence event can trigger the <DLE><!> transmission.
AT:U0B1,0	OK	Disable Si3000-to-DAA transmit gain path. This ensures codec tones are not sent to the FDV and DTMF.
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,05D7	OK	Configure Si3000 Register 5: 20 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR

Table 129. TAM Handset Record OGM (Continued)

AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.

7.6.3.2. Review OGM

The host will prompt the user to lift the handset to begin OGM review. The procedure restores the TAM Hands-Free settings before completion. The host will need to ensure the Handset Lowered Event is received before

Table 130. TAM Handset Review OGM

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0110	OK	Configure Si3000 Register 1: Enable speaker driver Disable line output driver Disable telephone instrument driver Enable MBIAS output
AT:U72,05B3	OK	Configure Si3000 Register 5: 10 dB Line In gain Mute Line In 20 dB MIC input gain Enable MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065C	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Disable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VGT=128	OK	Set the RS232-to-Si3000 transmit gain (UB8) for TAM Hands-Free.

Table 130. TAM Handset Review OGM (Continued)

AT+VSM=4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.
AT+VTX	CONNECT	Trigger transmit operation.
	<DLE><u>	TX Underrun. Appears at the start of +VTX before transmit data are seen.
[Voice Stream]		Transmit OGM voice stream. During voice stream capture, the user can adjust the UB8 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGT value for future use.
<DLE><ETX>	OK	Terminate the transmit operation. The modem will respond with OK to denote the return to command mode.
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,05D7	OK	Configure Si3000 Register 5: 20 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.

7.6.3.3. Record Local ICM

The Record Local ICM is identical to the Record OGM procedure provided in Table 129 on page 204. The main difference is that one of the ADPCM formats is generally used and the PCM file is stored with the other ICM files recorded from the PSTN.

7.6.3.4. Review ICM

The Review ICM is identical to the Review OGM procedure provided in Table 130 on page 206. The main difference is that one of the ADPCM formats is generally used to conserve message space.

7.6.4. TAM PSTN

This system voice mode differs from the TAM Hands-Free and TAM Handset modes in that the modem is off-hook and connected to the PSTN. Due to the paired nature of the +VGR and +VGT, the voice driver should maintain two copies of each: one for RS232-to-Si3000 and another for RS232-to-DAA. See Figure 29 on page 188 for details.

7.6.4.1. Normal Answer – OGM Playback with ICM Record

Table 131. TAM PSTN Normal Answer – OGM Playback with ICM Record

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
	<DLE><R>	Ring Detection
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><X> CIDM DATE=0101 TIME=0110 NMBR=102 NAME=JONES JENNIFER <DLE><.>	Receive Type I CID DLE complex report.
	<DLE><R>	Ring Detection.
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><R>	Ring Detection. The voice driver will use a rings-to-answer count. This example uses three rings before answer.
AT+VTS=[700,500,80]	OK	Play local ring tone.
AT:U199|8	OK	Mute the speaker so the OGM is not heard locally. The user may remove this command to allow local review.
AT+VGR=128	OK	Set the DAA-to-RS232 receive gain register (UBF) for TAM PSTN.
AT+VGT=128	OK	Set the RS232-to-DAA transmit gain register (UB3) for TAM PSTN.
AT+VSD=129	OK	Set sensitivity level for ICM recording silence detection.
AT+VSM=4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.

SILICON LABS

Table 131. TAM PSTN Normal Answer – OGM Playback with ICM Record (Continued)

AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS=15	OK	Setup off-hook voice to PSTN. See Table 117 on page 190 for details.
AT+VTX	CONNECT	Trigger transmit operation.
	<DLE><u>	TX Underrun. Appears at the start of +VTX before transmit data are seen.
[Voice Stream]		Transmit OGM voice stream. During voice stream capture, the user can adjust the UB3 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGT value for future use.
<DLE><ETX>	OK	Terminate the transmit operation. The modem will respond with OK to denote the return to command mode.
AT+VSM=131	OK	Select G.726 ADPCM, 4-bit, 32 kbps format.
AT+VTS=[1000,0,100]	OK	Play user record tone prompt.
AT:U0B5,0200	OK	Restore DAA-to-Si3000 receive gain path. This will allow call screening of the ICM.
AT:U199&FFF7	OK	Enable speaker for call screening of the ICM.
AT+VRX	CONNECT	Trigger receive operation. The first byte after the newline character following the CONNECT message will be the first data stream byte.
	[Voice Stream]	Receive ICM voice stream. During voice stream capture, the user can adjust the UBF value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGR value for future use.
<DLE><!>	<DLE><ETX> OK	Terminate the receive operation. The modem will respond with <DLE><ETX> to mark the end of the data stream. The OK denotes the return to command mode. A loss of loop current, parallel phone detect, timeout, or silence event can trigger the <DLE><!> transmission.

Table 131. TAM PSTN Normal Answer – OGM Playback with ICM Record (Continued)

AT:U0B5,0	OK	Disable DAA-to-Si3000 receive gain path. This ensures line events such as CID and ring tone are not heard via the codec.
AT:U199|2	OK	Mute the microphone.
AT:U199&FFF7	OK	Enable speaker for local ring tone/alert tones.
AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes. This will hang-up the call.
AT+VLS=14	OK	Setup on-hook TAM voice mode. See Table 117 on page 190 for details.

7.6.4.2. Interrupted Answer – OGM Playback with DTMF Menu Entry

The procedure listed in Table 132 uses a remote-access password of 1234. DTMF decoding is asynchronous. The host voice driver will need to employ a timer or timestamp to validate the consecutive DTMF digits that comprise the remote password.

Table 132. TAM PSTN Interrupted Answer – OGM Playback with DTMF Menu Entry

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
	<DLE><R>	Ring Detection
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><X> CIDM DATE=0101 TIME=0110 NMBR=102 NAME=JONES JENNIFER <DLE><.>	Receive Type I CID DLE complex report.
	<DLE><R>	Ring Detection.
AT+VTS=[700,500,80]	OK	Play local ring tone.
	<DLE><R>	Ring Detection. The voice driver will use a rings-to-answer count. This example uses three rings before answer.
AT+VTS=[700,500,80]	OK	Play local ring tone.
AT:U199|8	OK	Mute the speaker so the OGM is not heard locally. The user may remove this command to allow local review.
AT+VGR=128	OK	Set the DAA-to-RS232 receive gain register (UBF) for TAM PSTN.

SILICON LABS

Table 132. TAM PSTN Interrupted Answer – OGM Playback with DTMF Menu Entry (Continued)

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VGT=128	OK	Set the RS232-to-DAA transmit gain register (UB3) for TAM PSTN.
AT+VSD=129	OK	Set sensitivity level for ICM recording silence detection.
AT+VSM=4	OK	Select G.711U μ-law PCM, 8-bit, 64 kbps format. The voice driver will need to track the OGM format with the OGM PCM file.
AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS=15	OK	Setup off-hook voice to PSTN. See Table 117 on page 190 for details.
AT+VTX	CONNECT	Trigger transmit operation.
	<DLE><u>	TX Underrun. Appears at the start of +VTX before transmit data are seen.
[Voice Stream]		Transmit OGM voice stream. During voice stream capture, the user can adjust the UB3 value via the <DLE><u> and <DLE><d> commands. The host voice driver will need track the number of adjustments and update the +VGT value for future use.
	<DLE><~> <DLE><1> <DLE></>	DTMF 1 digit detected.
	<DLE><~> <DLE><2> <DLE></>	DTMF 2 digit detected.
	<DLE><~> <DLE><3> <DLE></>	DTMF 3 digit detected.
	<DLE><~> <DLE><4> <DLE></>	DTMF 4 digit detected. The password of 1234 has been matched. Abort answer sequence.
<DLE><ETX>	OK	Terminate the transmit operation. The modem will respond with OK to denote the return to command mode.

SILICON LABS

Table 132. TAM PSTN Interrupted Answer – OGM Playback with DTMF Menu Entry (Continued)

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VTS=[500,0,100]	OK	Play special administrator tone.
[Playback Menu Options]		Using the +VTX command, the voice driver can playback a menu and monitor DTMF digit events to perform operations remotely.

7.6.4.3. Speakerphone Transition

A SP Button On Event will trigger the transition to Speakerphone system voice mode. Based upon the point at which the event is received, the voice driver will vector to a user answer state to gracefully exit the TAM PSTN mode.

7.6.4.4. Handset Transition

A Handset Raised Event will trigger the transition to Handset system voice mode. Based upon the point at which the event is received, the voice driver will vector to a user answer state to gracefully exit the TAM PSTN mode.

7.7. Speakerphone

7.7.1. Overview

The Si2494/39 speakerphone consists of the following function components as shown in Figure 29 on page 188:

- Acoustical echo canceller (AEC)
- Acoustical echo suppressor (AES)
- AEC double-talk detector (DTD)
- Line echo canceller (LEC)
- Howling controller (HC)
- High-pass filter (HPF)

7.7.2. Simplex Speakerphone

Simplex Speakerphone (SSP) is a special case of speakerphone operation. Like Speakerphone, it allows two-way hands-free voice communication over a telephone line, but SSP allows communication in only one direction at a time. The direction of voice transmission can be done automatically, based on the presence of local and remote speech at the modem, or manually using a push-to-talk function. Simplex and full-duplex speakerphone modes are mutually exclusive. SSP supports the Ademco Contact ID and SIA security protocols. It also supports DTMF generation and detection. DTMF detection is enabled only during +VTR. Commonality in control registers between SSP and full duplex facilitates programming across platforms. SSP supports Type II Caller ID, but Caller ID is disabled during +VRX. A DLE<R> event report is sent to the DTE when a SAS Call Waiting tone is detected. If a CAS tone is detected, the modem mutes the Si3000 speaker while Caller ID Type II data are being captured. It then reports Caller ID info to the DTE as a DLE-shielded complex event. This happens automatically, without the need for an AT+VCIDR? command.

1. The microphone sample is taken after U19D; the speaker sample is taken after U19C. However, the scale factors are set to 1.0 internally, so U19C and U19D will not affect the SSP.

2. To mute the local talker, set U199 [1] to 1 and MUTE_DAA_TO_MIXER=1. To mute the remote talker, set U199 [3] to 1 and MUTE_MIXER_TO_DAA to 1.

Table 133. Simplex Speakerphone U Registers

Register	Name	Description	Default Value
U1D5	SSPHLDTIM	Extra time SSP stays in RX or TX mode to prevent frequent switching	0x0000
U1D6	SSPLTHRSH	Local talker threshold	0x0000
U1D7	SSPRTHRSH	Remote talker threshold	0x0000
U1D8	SSPBKTHRU	Break-through threshold for speaker in auto-switch mode. Disable feature by setting this to 7FFFh.	0x7FFF

7.7.3. External Microphone/Speaker Calibration

The Si2494/39 speakerphone calibration is required for a new external speaker and microphone pair to work properly with the speakerphone code. This section covers the following procedures:

- To calibrate the speaker and microphone module from a commercial reference platform to have the same speaker loudness and microphone sensitivity relative to those of the active reference system.
- To calibrate the speakerphone gains so that the AEC/DTD input signal levels are ensured for optimal AEC/AES/DTD performance.

The external analog gains on the Si24xx-VMB should be finalized before the performing the speakerphone calibration.

7.7.3.1. Transmit Gain Calibration—Speakerphone Disabled

Figure 32 illustrates the reference setup where the commercial speakerphone is active with default settings. Using the reference commercial speakerphone, call the remote telephone and establish a voice call. Place a sound source such as a PC speaker at a distance of one foot from the speakerphone's microphone. Play out white noise as the near-end speech through the sound source, and adjust the white noise level so that the level at the speakerphone's Tip/Ring is -15 dBm. Record the white noise level and disconnect the call.
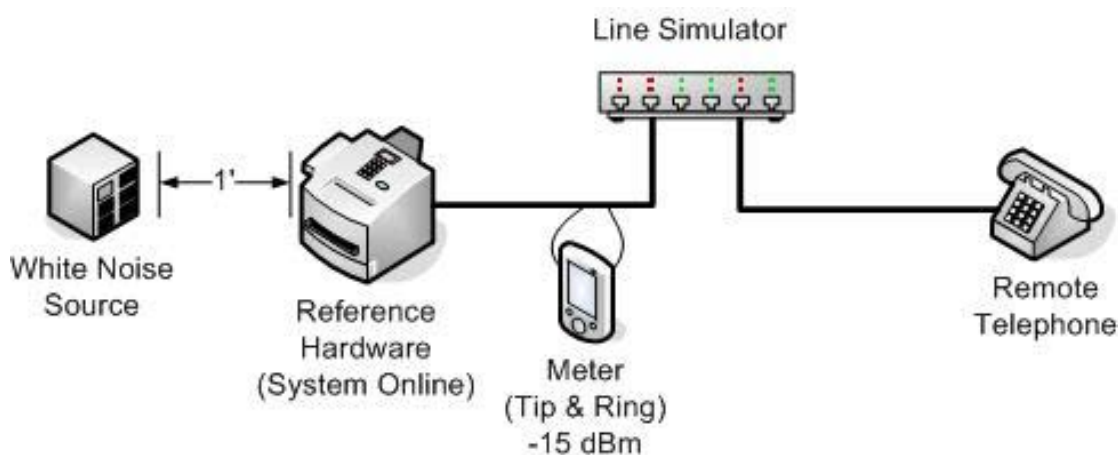
Figure 32. Transmit Gain Reference Measurements

Figure 33 illustrates the setup used to set the transmit gain. Here the modem has the AEC/AES disabled with AT+VSP=0. Using the Si24xx-VMB, call the remote phone and establish a voice call. Use the command sequence in Table 134. Place the same sound source at a distance of one foot from the speakerphone's microphone. Play out the same white noise as the near-end speech through the sound source, and adjust the transmit gain UB1 so that the level at the Si24xx Tip/Ring is –15 dBm. Record the calibrated UB1 value.
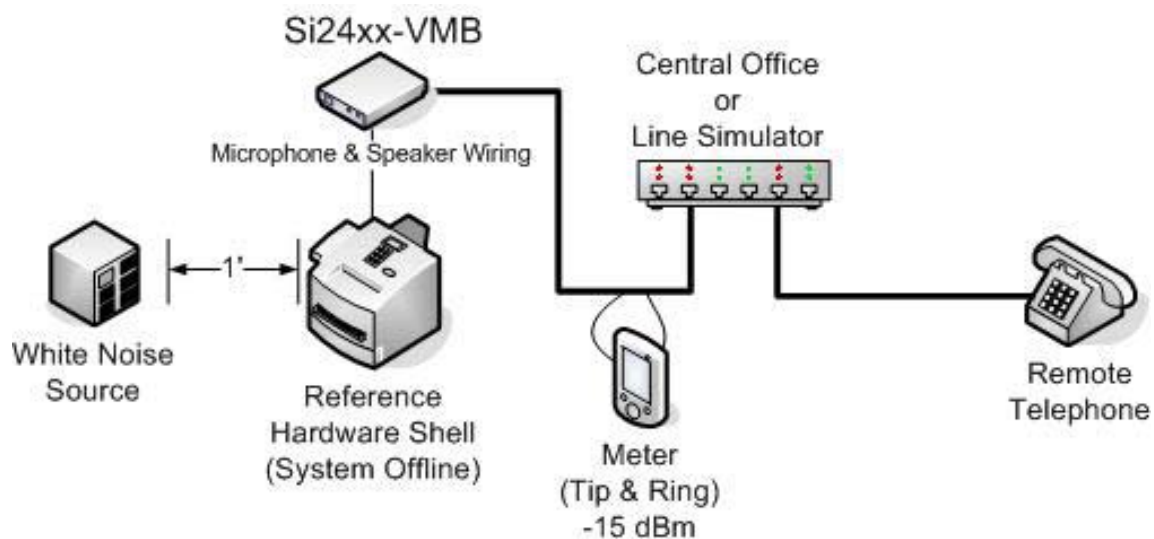
Figure 33. Transmit Gain Configuration

SILICON LABS

Table 134. Transmit/Receive Gain Calibration – Dial Remote Telephone

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATZ	OK	Reset the modem.
AT+FCLASS=8	OK	Enter voice mode.
AT:U199|4	OK	Set SPCAL (U199 [2]) to enable calibration.
AT*Y254:W59|1	OK	Enable the SSI interface to the Si3000.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,0597	OK	Configure Si3000 Register 5: 10 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VLS=13	OK	Setup off-hook voice mode. See Table 115 on page 186 for details. This command will switch the modem to off-hook state. The default value is +VSP=0 for disabled speakerphone.
[Dial Number]		

SILICON LABS

7.7.3.2. Receive Gain Calibration—Speakerphone Disabled

Figure 34 illustrates the reference setup where the commercial speakerphone is active with speaker set to maximum volume. Using the reference commercial speakerphone, call the remote telephone and establish a voice call. Place a sound source such as a PC speaker at a distance of one foot from the remote telephone microphone. Play out white noise as the far-end speech through the sound source, and adjust the white noise level so that the level at the speakerphone's Tip/Ring is -15 dBm. Next, measure the speaker loudness by using a sound meter (preferred) or a PC microphone to record the sound level at a distance of one foot from the speakerphone's speaker. Record the white noise level and speaker level loudness, and then disconnect the call.
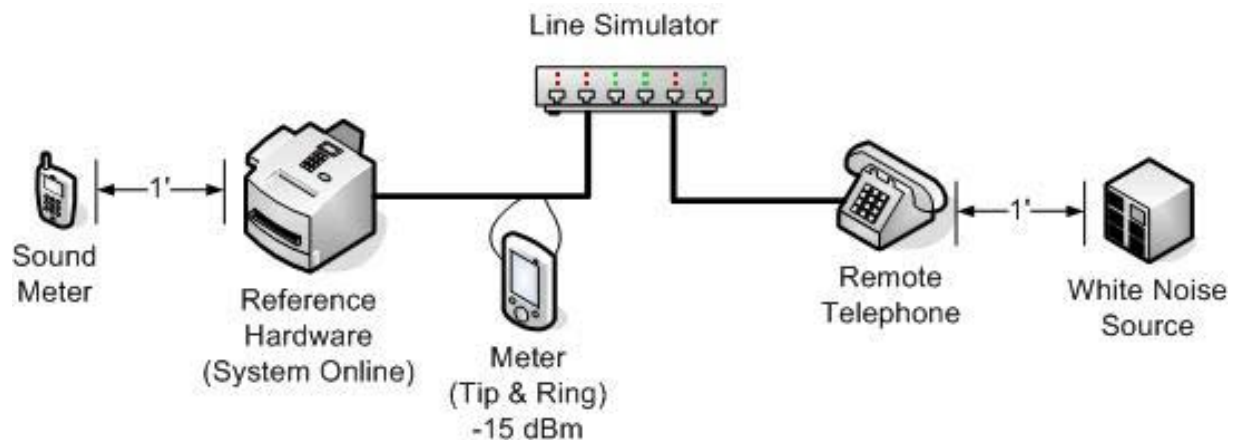
Figure 34. Receive Gain Reference Measurements

Figure 35 illustrates the setup used to set the transmit gain. Here the modem has the AEC/AES disabled with AT+VSP=0. Using the Si24xx-VMB, call the remote phone and establish a voice call. Use the command sequence in Table 135. Send the same white noise as the far-end speech from the remote phone, and adjust the receive gain UB5 so that the speaker loudness is the same as that of the reference speakerphone. Record the calibrated UB5 value.
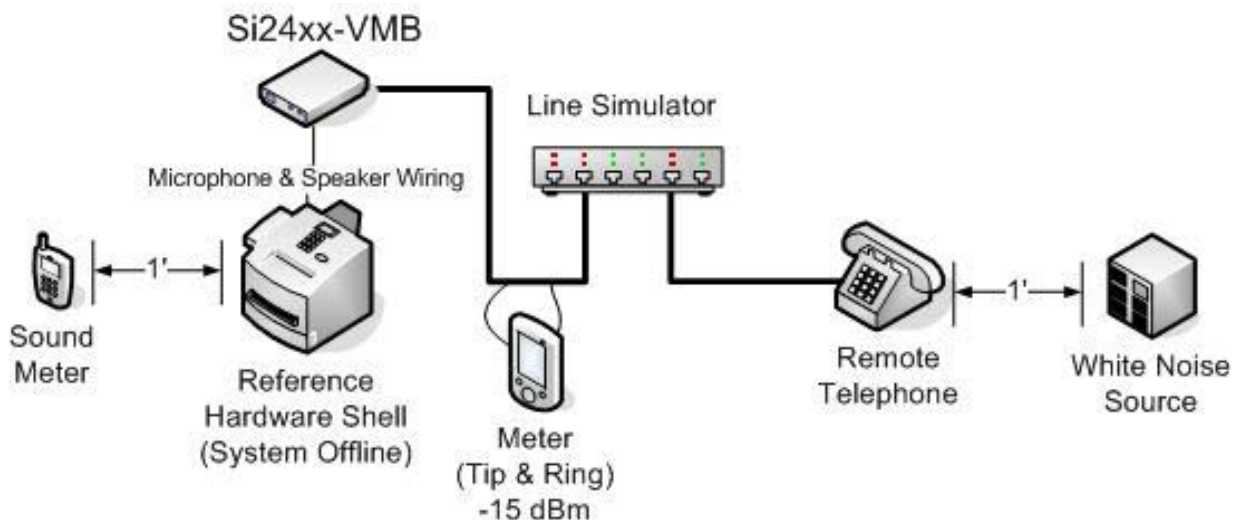
Figure 35. Receive Gain Configuration

SILICON LABS

7.7.3.3. Speakerphone Calibration—AEC Gain Calibration

Figure 36 illustrates the setup used to set AEC speaker reference gain (U19C) and the AEC microphone input signal gain (U19D). Here the modem has the AEC/AES enabled (AT+VSP=1) with the calibrated UB1 and UB5 values, which where obtained from the two previous sections. Using the Si24xx-VMB, call the remote phone and establish a voice call. Use the command sequence in Table 135.

The AECREF (U19E) contains the energy information of both the AEC speaker reference signal (SPKREF) and the microphone signal (MICREF). The SPKREF bits represent the AEC speaker reference energy, and MICREF bits represent the AEC microphone input energy. The energy value is computed from average($s[t]^2$).

Reg.	Name	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
U19E	AECREF	SPKREF								MICREF							

Send the white noise from the remote phone so that the energy level at the meter (Tip and Ring) is -15dBm. Use the AT:R19E command to read the contents of the U19E register. Adjust the AEC gain (U19C) of the speaker reference signal until SPKREF reaches a value as close to 0x38 as possible. Adjust the AEC gain (U19D) of the microphone input signal until MICREF has a value as close as possible to 0x38.

U19C and U19D are calibrated when the AT:R19E reading is close to 0x3838, with a power-level difference of less than 2dB. Record these values and use them in the initialization sequence defined in Table 119, "Initialization Sequence," on page 194.
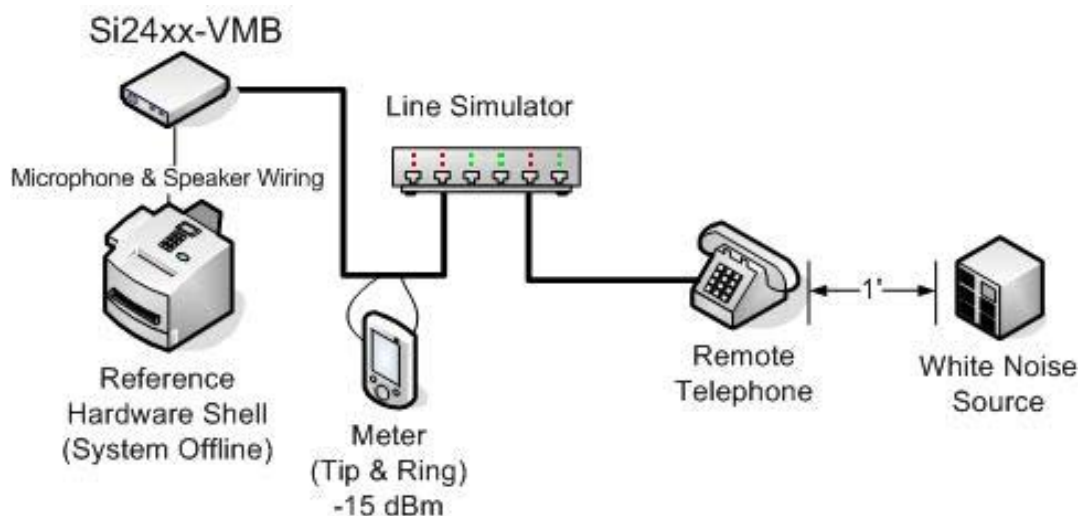
Figure 36. AEC Gain Calibration

Table 135. AEC Gain Calibration – Dial Remote Telephone

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATZ	OK	Reset the modem.
AT+FCLASS=8	OK	Enter voice mode.
AT:U199|4	OK	Set SPCAL (U199 [2]) to enable calibration.
AT*Y254:W59|1	OK	Enable the SSI interface to the Si3000.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,0597	OK	Configure Si3000 Register 5: 10 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT:UB1,xxxx	OK	Use calibrated value from "Transmit Gain Calibration – Speakerphone Disabled" section.
AT:UB5,xxxx	OK	Use calibrated value from "Receive Gain Calibration – Speakerphone Disabled" section.
AT+VLS=13	OK	Setup off-hook voice mode. See Table 122 on page 198 for details. This command will switch the modem to off-hook state.
AT+VSP=1	OK	Enable speakerphone voice path. See Table 136 for details.
[Dial Number]		

SILICON LABS

7.7.4. Speakerphone Configuration

This section covers the speakerphone call and answer cases, and the switching between the handset mode and speakerphone mode. Table 136 contains the initial configuration that is used by all dialing use cases. The sequence is also sent for the answer case. The user will have been notified of the incoming call through a local +VTS ring tone and a SP Button On Event would prompt the Speakerphone Configuration sequence to answer the call. The UB1, UB5, UB6, and Si3000 register configurations vary with the customer's production hardware. The UB5 register serves as the general volume control in this mode.

Table 136. Speakerphone Configuration

Host to Modem Commands / Data	Modem to Host Result Codes/ Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT+VLS=0	OK	Disable voice mode. Used as a transition point between non-zero +VLS voice modes.
AT+VLS=13	OK	Setup off-hook voice mode. See Table 117 on page 190 for details. This command will switch the modem to off-hook state.
AT:U0B1,0500	OK	Restore Si3000-to-DAA transmit gain path.
AT:U0B5,0200	OK	Restore DAA-to-Si3000 receive gain path.
AT:U72,0108	OK	Configure Si3000 Register 1: Disable speaker driver Enable line output driver Disable telephone instrument driver Disable MBIAS output
AT:U72,0597	OK	Configure Si3000 Register 5: 10 dB Line In gain Enable Line In 20 dB MIC input gain Mute MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065E	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Enable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR

Table 136. Speakerphone Configuration (Continued)

Host to Modem Commands / Data	Modem to Host Result Codes/ Data	Local Modem Actions
AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VSP=1	OK	Enable speakerphone voice path. See Figure 29 on page 188 for details.
AT:U199&FFF5	OK	Enable the microphone and speaker paths to the codec.

7.7.5. Simplex Speakerphone Configuration

Configuring the modem to automatically switch between local talker and remote talker is as follows:

■ For the SSP auto-switch (VOX) function, set SSP_FLAG to 1 (U199 [6] = 1) and SSP_PTT to 0 (U199 [7] = 0).

■ Set the speaker and microphone level thresholds, which determine whether remote speech or local speech is active. The thresholds are defined in U19C and U19D. Typical values for the speaker and microphone thresholds are 0x700 and 0x600, respectively. These thresholds are not affected by the speaker and microphone control gains UB5 and UB1.

■ Set the holding time, which is the time that the SSP holds the current mode after the signal level falls below the threshold. Holding time prevents frequent mode switching between RX and TX. A typical value for holding time is 0xC8 (200 ms).

For manual operation (push-to-talk):

■ Set SSP_FLAG to 1 (U199 [6] = 1) and SSP_PTT to 1 (U199 [7] = 1).

■ Use the SSP_LOCTALK bit (U199 [8]) to set the speech direction: U199 [8] = 1 for local talker; U199 [8] = 0 for remote talker.

U1D8 is the break-through threshold for the speaker signal in SSP auto-switch mode. If the speaker signal is above the threshold U1D8 and holds at least for the holding time, the direction is switched to remote talker, no matter how strong the signal in the microphone is. To disable break-through, set the threshold to 7FFFh (AT:U1D8,7FFF).

■ U1D8 greater than U1D6: when the speaker signal is greater than or equal to U1D8, the microphone is muted and speaker unmuted immediately, regardless of the microphone holding time. When the speaker signal is greater than U1D6 but less than U1D8, the speaker signal goes through after the expiration of the microphone holding time.

■ U1D8 less than U1D6: the break-through threshold U1D8 takes over and the speaker level threshold U1D6 becomes inactive.

■ The default value for U1D8 is 7FFFh. A typical value for U1D8 is 0x1000. Adjust U1D8 according to the needs of the application.

SILICON LABS

Table 137. Simplex Speakerphone Configuration

Host to Modem Command	Modem to Host Result Code	Local Modem Actions
AT:U1CD,40,10	OK	Set LEC Filter Length Set LEC Delay
AT:U1D5,C8,400,400,7FFF	OK	Set Holding Time (ms) Set Speaker Threshold Set Microphone Threshold Disable break-through
AT:U199|40	OK	Enable SSP, configure for automatic switch mode

7.7.6. Call—Automatic Tone Dial

Table 138 lists the commands that occur after the configuration defined in Table 136.

Table 138. Speakerphone Automatic Tone Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATDT102	OK	Perform automatic tone dial of 102. Modem will return OK. The user will not receive <DLE> events for dial tone, ring-back, busy, and quiet since the detectors are disabled. See Table 117 for details on active detectors.

7.7.7. Call—Manual Off-Hook Tone Dial

Table 139 lists the commands that occur after the configuration defined in Table 136.

Table 139. Speakerphone Manual Off-Hook Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
AT+VTS=[697,1209,20]	OK	The user is free to dial manually using the +VTS commands to create the DTMF digits. Generate DTMF 1 digit for 200 ms.
AT+VTS=[941,1336,20]	OK	Generate DTMF 0 digit for 200 ms. Generate DTMF 2 digit for 200 ms.
AT+VTS=[697,1336,20]	OK	The user will not receive <DLE> events for dial tone, ring-back, busy, and quiet since the detectors are disabled. See Table 117 on page 190 for details on active detectors.

SILICON LABS

7.7.8. Call—Automatic Pulse Dial

Table 140 lists the commands that occur after the configuration defined in Table 136.

Table 140. Speakerphone Automatic Pulse Dial

Host to Modem Commands / Data	Modem to Host Result Codes/Data	Local Modem Actions
ATDP102	OK	Perform automatic pulse dial of 102. Modem will return OK. The user will not receive <DLE> events for dial tone, ring-back, busy, and quiet since the detectors are disabled. See Table 122 on page 198 for details on active detectors.

7.7.9. Answer

A ring event will prompt the user to press the speakerphone button. This will generate a SP Button On Event and the Speakerphone Configuration procedure defined in Table 136 on page 219 should be used to answer the call. For ring detection and local ring tone/melody generation, see "7.6.2. TAM Hands-Free—Idle".

7.7.10. Handset Transition

For a SP Button Off Event (Handset Off-Hook), the voice driver should use the command sequence in Table 141 to return to the Handset mode. Note the voice driver is responsible for tracking the handset hook switch state.

Table 141. Speakerphone to Handset Transition

Host to Modem Commands / Data	Modem to Host Result Codes/ Data	Local Modem Actions
AT:U199|A	OK	Mute the microphone and speaker paths to the codec.
AT:U72,0110	OK	Configure Si3000 Register 1: Enable speaker driver Disable line output driver Disable telephone instrument driver Enable MBIAS output
AT:U72,05B3	OK	Configure Si3000 Register 5: 10 dB Line In gain Mute Line In 20 dB MIC input gain Enable MIC input Mute telephone instrument input Enable IIR filter
AT:U72,065C	OK	Configure Si3000 Register 6: 0 dB RX PGA gain Disable Line Out Disable telephone instrument output
AT:U72,075E	OK	Configure Si3000 Register 7: 0 dB RX PGA gain Enable SPKRL Mute SPKRR

SILICON LABS

Table 141. Speakerphone to Handset Transition (Continued)

AT:U72,0900	OK	Configure Si3000 Register 9: 0 dB Line Out attenuation 0 dB Speaker output attenuation
AT+VSP=0	OK	Select handset voice path. See Figure 29 on page 188 for details.
AT:U199&FFF5	OK	Enable the microphone and speaker paths to the codec.

7.7.11. Termination

A SP Button Off Event (Handset On-Hook) will cause the system to return to the TAM Hands-Free mode. Use the same configuration listed in Table 124 on page 199. Note the voice driver is responsible for tracking the handset hook-switch state.

7.8. Glossary

- AEC   Acoustical Echo Canceller of speakerphone
- AES   Acoustical Echo Suppressor of speakerphone
- Convergence Rate   Rate at which AEC or LEC converges
- DCE   Data Circuit-terminating Equipment
- DLE   Data Link Escape (0x10)
- DTE   Data Terminal Equipment
- DTD   Double talk detector of AEC or LEC
- Double-Talk   Both the near-end and far-end users talk
- ETX   End of Text (0x03)
- ICM   Incoming Message
- LEC   Line Echo Canceller of speakerphone
- OGM   Outgoing Message
- PSTN   Public Switch Telephone Network
- Single-Talk   Either the near-end or far-end user talks
- TAM   Telephone Answering Machine

7.9. References

- ITU-T G.711   Pulse code modulation (PCM) of voice frequencies – 11/1998
- ITU-T G.726   40, 32, 24, 16 kbit/s adaptive differential pulse code modulation (ADPCM) – 12/1990
- ITU-T V.253   Control of voice-related functions in a DCE by an asynchronous DTE - 02/1998.

8. Security Protocols

The Si24xx ISOmodem can handle a variety of security protocols. Two are specifically described here. The "Ademco® Contact ID Protocol" and the SIA protocol.

8.1. Implementing the SIA Protocol

The SIA protocol defines communication between an alarm panel and a central station. In a traditional security system, the alarm panel always calls the central station and sends data; the central station only acknowledges its readiness to receive data and that data has been received. For this reason, the communication part of the alarm panel has been called the transmitter; the communication part of the central station has been called the receiver. With the SIA protocol, the central station can also send data to the alarm panel; since data is sent using FSK, the communication can be half-duplex or full-duplex. Nevertheless, the traditional nomenclature of transmitter for the alarm panel and receiver for the central station is still used for the SIA protocol.

The communication session consists of four elements:

- The Handshake Tone (a single tone)
- The Speed Synchronization Signal (two tones)
- Data Blocks and Control Signals (transmitted using Bell 103 FSK encoded data)
- Acknowledgement Blocks (can be either single tones or Bell 103 FSK encoded data, according to the capabilities of the transmitter)

8.1.1. Modem-Specific Implementation Details

8.1.1.1. Listen-In and V-channel Periods (Voice Pass-Through)

This can be accomplished with the following procedure using standard voice modem commands:

1. Prior to making the call, the host issues AT+VNH=2 to modem. This will keep the modem off-hook when the host clears down the FSK data connection using ATH.

2. After the modem has negotiated a Listen-in period using the SIA protocol in Bell 103, the host clears down the FSK data link with ATH.

3. The host issues AT+VNH=2 to the modem again to maintain off-hook status for next cleardown.

4. The host then issues AT+FCLASS=8 followed by the usual Si3000 voice pass-through command sequence. (To minimize the transition time, the host should set up the Si3000, TX/RX voice filters and all gain stages before the call.)

5. AT+VLS=5 starts the Si3000 pass through, which supports Listen-in as well as V-Channel (bi-directional voice) operation. Use +VLS=13, +VSP=1 etc. if speakerphone is desired.

6. When voice period is over, the host puts the modem back in data mode using AT+FCLASS=0. This will terminate voice operation as well as going to +FCLASS=0. ATH and +VLS=0 must not be used in +FCLASS=8 to terminate the voice session because they override +VNH=2 (per V.253 standard).

7. The host again issues AT+VNH=2 to the modem to keep it off-hook for the next cleardown.

8. AT+F0 puts the transmitter in Bell 103, SIA mode to resume SIA protocol communication.

8.1.1.2. Inserting a V.32bis period (e.g., SIA Level-3 Video Block Support)

This can be accomplished with the following procedure using standard voice modem commands:

1. After clearing down the SIA FSK link, the host issues AT+VNH=2 to the modem to maintain off-hook status for the next cleardown.

2. The host sets the modem to V.32bis; i.e., AT&H4, AT\N3 (if error correction is desired)

3. The host selects V.32bis originate or answer mode: AT%O2 if the transmitter should assume the handshake mode of an originating V.32bis modem; AT%O1 if it should assume the handshake mode of an answering modem.

SILICON LABS

4. Issuing ATO to modem will start the V.32bis handshake. The host then waits for the CONNECT message before sending data. (For an originating modem, the ATO command must be sent as soon as possible so the modem will be ready when the remote answering modem starts. For an answering modem, the ATO should be delayed a little to give the remote originating modem a chance to get ready first.)

5. The host disconnects the V.32bis session (using either +++ followed by ATH, or with DTR, if it has previously been enabled with AT&D2).

6. The host issues AT+VNH=2 to the modem again to maintain off-hook status for next cleardown.

7. AT\N0 removes error-correction, if it was used during the V.32bis period.

8. SIA protocol communication resumes by starting up the transmitter in Bell 103, SIA mode with AT+F0.

8.1.1.3. Considerations when Disconnecting the Session

Because AT+VNH=2 keeps the modem off-hook during a cleardown, the first ATH or DTR desertion will not put modem back on-hook but only force AT+VNH=0 (per V.253). The host must issue a second ATH to put the modem back in on-hook idle state. Alternatively the host could issue a AT+VNH=0, then ATH (or AT+VNH=0;H)

Table 142 lists the AT Commands provided to support SIA Level-3 Protocol communication.

Table 142. AT Commands Provided to Support SIA Level-3 Protocol Communication

AT Command	Modem Function	Remarks
AT+F0	Enable B103 Transmitter for Data Block transmission.	Modem turns on FSK transmitter and starts marking for the minimum duration required by standard. Sends CONNECT message to DTE when that is accomplished. Modem will then interpret the first character from DTE as Block Header and use the byte count to allow transmission of the specified number of characters to the remote modem and then send OK message to DTE to indicate ready for next AT command. Note1: FSK transmitter remains on. DTE is expected to issue either a +F2 (detect ACK/NACK) or another +F0 (to send another data block) command to the modem. Note2: The "+++" escape sequence can be used to abort the data block transmission and return the modem to AT command mode. Note3: The +F0 command can be used to resume SIA protocol communication after a voice listen-in or V.32bis interruption.

SILICON LABS

Table 142. AT Commands Provided to Support SIA Level-3 Protocol Communication (Continued)

AT Command	Modem Function	Remarks
AT+F1	Enable B103 Receiver for Data Block reception.	Modem enables FSK receiver, waits for >12T marks to be detected, then sends CONNECT message to DTE to indicate a received Data Block follows. Modem will stay in this mode indefinitely until an AT command is issued by DTE. It is usually a +F3(ACK), +F4(NACK) or +F5(ACK followed by Data Block transmission) command. Note1: Modem will wait for up to 1 second to detect >12T marks before unclamping RXD. After 1 second RXD will be unclamped regardless. Note 2: The +F1 command can be used to resume SIA protocol communication after a voice listen-in or V.32bis interruption.
AT+F2	Enable tonal ACK/NACK detection.	Detect and report ACK or NACK to DTE. 'OK' for ACK and 'ERROR' for NACK. A NACK will be reported if no valid signal is detected within 2.5 seconds.
AT+F3	Transmit Tonal ACK	Transmit Space for 600 ms. Send 'OK' prompt to DTE when done.
AT+F4	Transmit Tonal NACK	Transmit Mark for 600 ms. Send 'OK' prompt to DTE when done.
AT+F5	Transmit Tonal ACK with reverse channel command.	Transmit Space for 600 ms, followed by Mark for 180 ms. Then send CONNECT to DTE to indicate modem is ready to accept data.
AT+F6	Abort current Data Block Reception or Transmission.	This command is useful for exception handling, such as timeout. If the FSK transmitter was on, +F6 shuts it off. FSK reception is aborted and modem returns to the AT command mode.

SILICON LABS

Table 143 lists the definitions of result codes typically expected in an SIA session.

Table 143. Definitions of Result Codes Typically Expected in an SIA Session

Result Code	Meaning	Remarks
OK	Ready for next command (or ACK)	When it comes as a response to the +F2 command, "OK" means ACK
CONNECT	Physical handshake is completed.	In SIA FSK mode, CONNECT means that the modem is in the data passing state ready to receive or transmit data. Note: there is an extra space character between the letter T and the carriage return delimiter. In V.32bis mode, CONNECT is followed by the DCE connection speed: e.g., CONNECT 14400
RING	Incoming ring	Modem should answer the incoming call; the host can command this with ATA.
NO CARRIER		Connection is terminated
ERROR	Invalid AT command (or NACK)	As a response to the +F2 command, "ERROR" means NACK; otherwise, it means invalid command.
BUSY		Dialed number is Busy.

8.2. Implementing the Ademco® Contact ID Protocol

Contact ID is a communications protocol for security applications. It is a de facto standard which was developed and is owned by the Ademco Group. The following is a brief overview of the Contact ID protocol. The complete standard is available at the following web site:

http://webstore.ansi.org/RecordDetail.aspx?sku=SIA+DC-05-1999.09

Communication is between an alarm panel and a central station. The part of the alarm panel that handles communication has the following functions:

- Call the central station
- Wait for the central station to indicate that it is ready for data
- Send data
- Wait for the central station to indicate that data was received

The central station also has a block that handles communication. Its functions are:

- Answer calls
- Acknowledge that it is ready to receive data
- Receive data
- Acknowledge that data was received

While performing their security functions, the communication part of the alarm panel always sends data, while the communication part of the central station always receives data. They are called the transmitter and receiver, respectively. (Data could flow the other way, for instance to download new firmware to the alarm panel, but this isn't covered by the Contact ID Protocol.)

A transaction begins with the transmitter calling the receiver. The receiver goes off-hook and acknowledges that it is ready to receive data by producing the handshake tone sequence:

- 1400 Hz tone for 100 ms
- Pause for 100 ms
- 2300 Hz tone for 100 ms

The frequency tolerance on the handshake tones is ±3%. The tolerance on tone and pause times is ±5%. Transmitters have a frequency tolerance of ±5% to account for older receivers.

After the communication channel has been established, the transmitter sends data to the receiver in Message Blocks. Data is transmitted as DTMF codes. The frequency tolerance of the DTMF tones is ±1.5%. Twist is not specified by the Contact ID protocol standard.

After sending the message, the transmitter waits for the receiver to send an acknowledgement (Kissoff) tone. The Kissoff tone is a 1400 Hz tone that lasts for at least 750 ms and at most 1 second. The frequency tolerance of the Kissoff tone is ±3%; transmitters have a frequency tolerance of ±5% for back compatibility with old receivers. The receiver must detect at least 400 ms of the Kissoff tone for it to be considered valid.

The transmitter waits for the Kissoff tone to end, then waits an additional 250 to 300 ms before sending another Message Block. If no Kissoff tone is received after 1.25 s, the transmitter sends the message again. Up to four retries are attempted per Message Block. After the last message block has been acknowledged, the transmitter hangs up.

SILICON LABS

8.2.1. Modem Specific Implementation Details

The DTMF transmitters and receivers are used to send and receive data. Voice mode operation documented in chapter X is used to transmit and receive the tones.

A summary of the necessary tone transmission AT commands is shown in Table 144.

The procedure is as follows:

Modem Initialization: (host sends to modem):

    AT+FCLASS=8   (enters voice mode)

    AT+VLS=15:   (goes off hook and starts tone detection)

Send and receive tones example:

    AT+VTS=[941,1336,10]   Host commands modem to send DTMF digit 0.

    0x10, 0x2F, 0x31, 0x32, 0x7E   Modem responds with 5 characters as it receives two DTMF tones:
                                    1 and 2. There are 2 preamble and 1 postamble characters
                                    in this example.

Table 144. Ademco® Contact ID Protocol Tone Transmission AT Commands

DTMF Digit	Low Tone (Hz)	High Tone (Hz)	Contact ID Digit	Contact ID Digit Value	AT Command
0	941	1336	0	10	AT+VTS=[941.1336. 10]
1	697	1209	1	1	AT+VTS=[697.1209. 10]
2	697	1336	2	2	AT+VTS=[697.1336. 10]
3	697	1477	3	3	AT+VTS=[697.1447. 10]
4	770	1209	4	4	AT+VTS=[770.1209. 10]
5	770	1336	5	5	AT+VTS=[770.1336. 10]
6	770	1477	6	6	AT+VTS=[770.1477. 10]
7	852	1209	7	7	AT+VTS=[852.1209. 10]
8	852	1336	8	8	AT+VTS=[852.1336. 10]
9	852	1477	9	9	AT+VTS=[852.1477. 10]
*	941	1209	B	11	AT+VTS=[941.1209. 10]
#	941	1477	C	12	AT+VTS=[941.1477. 10]
A	697	1633	D	13	AT+VTS=[697.1633. 10]
B	770	1633	E	14	AT+VTS=[770.1633. 10]
C	852	1633	F	15	AT+VTS=[852.1633. 10]
D	941	1633	not used	N/A	N/A
	1400	----		KISSOFF	AT+VTS=[1400,0,85]

8.2.1.1. Handshake Tone Detection

Two tone detectors are reconfigured for detection of the 1400Hz and 2300Hz tones. When a valid tone burst is detected the modem reports it to the host DTE in the V.253 event format as follows.

Event	Modem-to-DTE indication	Remarks
1400 Hz tone burst detected	0x10, 0x63	Character pair <DLE><c> is sent to DTE at the end of the valid tone burst.
2300 Hz tone burst detected	0x10, 0x65	Character pair <DLE><e> is sent to DTE at the end of the valid tone burst.

8.2.1.2. Session Example

Table 145. Ademco® Mode of Operation

Step	DTE-to-Modem Command	Modem-to-DTE Indication	Remarks
1	AT*y254:w8686,1AA,CCDF,C73B,C001,0 AT*y254:w868B,1AA,D3D1,C39A,3FFF,DDD AT*y254:w8690,1AA,C34B,C35F,3FFF,54A0 AT*y254:w8695,C,400 AT*y254:w8697,7BE,E050,CC04,3FFF,345F AT*y254:w869C,7BE,BF39,CA8D,3FFF,37B5 AT*y254:w86A1,C,300,C00,CCD	OK OK OK OK OK OK OK	Initialize 2300 Hz tone detector. Note: This step must be done after a reset or ATZ. But it is not needed for every call.
2	AT*y254:w86A5,100,2A44,C480,C001,0 AT*y254:w86AA,167,25BC,C22F,3FFF,EC95 AT*y254:w86AF,167,303D,C21E,3FFF,BEF2 AT*y254:w86B4,C,400 AT*y254:w86B6,812,1E2F,C772,3FFF,D55F AT*y254:w86BB,939,3394,C6FC,3FFF,D345 AT*y254:w86C0,1000,0,0,0,0 AT*y254:w86C5,C,140,8c0,CCD	OK OK OK OK OK OK OK OK	Initialize 1400 Hz tone detector. This step must be done after a reset or ATZ. But it is not needed for every call.
3	ATE0:UAD|40 AT:UAD&FF7F	OK OK	Set UAD.6 to enable Ademco mode tone detections. Clear UAD.7 to disable SIA mode.
5	AT:R48	0064	DTE reads and records what is the normal "tone off" duration for DTMF dialing. This parameter is country dependent. This parameter will be modified for Data Tones transmission later.
6	AT+FCLASS=8	OK	Put modem into V.253 voice mode.

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Table 145. Ademco® Mode of Operation (Continued)

Step	DTE-to-Modem Command	Modem-to-DTE Indication	Remarks
7	AT:U181,78,0,0,1C	OK	Set up 1400 Hz detector to detect 100 ms Handshake tone burst.
8	ATDnnnnnnn	OK	Call RECEIVER station.
9	AT+VTD=5;:U48,32	OK	Change DTMF on off time to prepare for Data Tones transmission.
10	**Wait for RECEIVER to answer with handshake tones**		
11		<DLE><c> i.e. 0x10, 0x63	1400 Hz tone burst detected Note: First part of Handshake Tones detected.
12		<DLE><e> i.e. 0x10, 0x65	2300 Hz tone burst detected Notes: Second part of Handshake Tones detected. Since there is a 100 ms silence between the 1400 Hz and 2300 Hz tones, the <DLE><e> message should come nominally 200msec after the previous <DLE><c> message. It is the responsibility of the host DTE driver to measure and validate this time period.
13	AT:U181,334,0,0,12C	OK	Change 1400 Hz detector to detect 800 ±300 ms tone burst, i.e. Kissoff tone.
14	**Delay 250 ms before transmitting Data Tones message.**		Host DTE should adjust this delay so that the following +VTS DTMF transmission will start between 250 to 300 ms after the reception of <DLE><e> above.

Table 145. Ademco® Mode of Operation (Continued)

Step	DTE-to-Modem Command	Modem-to-DTE Indication	Remarks
15	AT+VTS=9,9,9,9,1,8,1,*,#,A,0,0,0,0,0,3	OK	First Data Block is transmitted. Note: Data octets are placed after the "=" and separated by commas. Note: Host DTE driver must perform these substitutions, Octet B as * Octet C as # Octet D as A Octet E as B Octet F as C Note: OK is sent at end of transmission.
16	**Wait for Kissoff tone**		
17			1.25 s has elapsed. But modem still has not reported <DLE><c> to DTE
18	AT*Y254:Q83FB	01AF	Check to see if start of a Kissoff Tone has been detected? A non zero response (i.e. not 0000) from modem denotes start of tone is detected. Modem will send <DLE><c> to DTE after it has verified that the Kissoff Tone burst duration is valid.
19		<DLE><c>	Acknowledgement from RECEIVER detected. Note: <DLE><c> is sent at end of tone burst.
20	Delay 250 ms before sending next Data Tone Message. Repeat from Step 15 for sending more Data Codes		
	ATH	OK	Hang up at end of session.

Table 145. Ademco® Mode of Operation (Continued)

Step	DTE-to-Modem Command	Modem-to-DTE Indication	Remarks
	AT:U48,64	OK	Restore DTMF parameters to comply with normal dialing requirements.
	Repeat from Step 6 for next call		

9. Chinese ePOS SMS

9.1. Introduction

An ePOS transaction normally begins with the ePOS terminal calling the server and transmitting data first. In this instance the terminal initiates the call, so it is known as the Originate modem, while the server is the Answer modem. After the modems connect, go through handshake and complete the first data transmission, the two modems alternate being the transmitter and receiver until the completion of the call.

The Si24xx ISOmodems support SMS (Short Message Service) in an ePOS (electronic point of sale) connection. An SMS message is delivered in frames, using the format shown in Figure 37.

Channel Seizure Protocol 1: 0 bits Protocol 2: 300 bits	Mark Signal Protocol 1: 80 bits +/-25 Protocol 2: 80 bits +/- 25	Data Frame				Mark Signal
		Type	Length	Payload	Checksum	
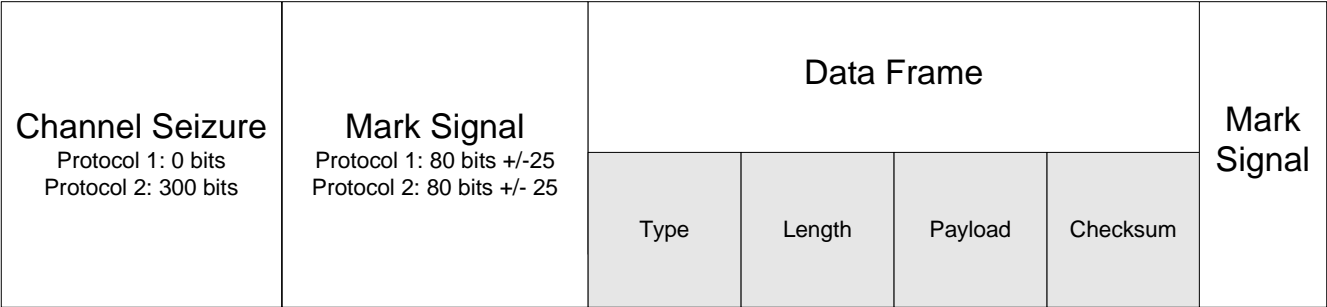
Figure 37. SMS Message Format

As shown in the figure, an SMS frame follows one of two protocols, Protocol 1 or Protocol 2. Protocol 1 frames begin with the Mark signal, while Protocol 2 frames start with the Channel Seizure (CS) signal. Otherwise the two protocols are identical. The Originate modem is configured to transmit in one of the two protocols at the beginning of a call. The Answer modem recognizes which protocol is being sent and processes the incoming message accordingly.

The modem strips off the Channel Seizure and Marks at the beginning and end of the data and provides the Data Frame to the host processor. It does not provide frame content verification of any kind.

9.2. SMS AT Command Set

Table 146 shows the AT commands that the host (DTE) uses to control the transmission or reception of SMS messages.

Table 146. AT Commands for SMS

AT Command	ISOmodem Response	Description
&D1	OK	ESC (pin 22) escapes to command mode from data mode if also enabled by HES (Enable Hardware Escape Pin): U70, bit 15.
&D2	OK	ESC (pin 22) assertion during a modem connection causes the modem to go on-hook and return to command mode. The escape pin must be enabled by setting bit HES: U70, bit 15.
+FCLASS=256	OK	Enables SMS mode
DTXXXX;	OK	Originate modem dials XXXX, then goes back into command mode.
DT;	OK	Answer modem picks up the line and goes back into command mode.
+FRM=200	CONNECT 1 or CONNECT 2	Receive modem goes into data mode and waits for FSK data from Transmit modem; response is determined by whether a Protocol 1 or 2 message was received.
+FTM=201	CONNECT	Transmit modem goes into data mode and waits for data from the DTE. Sends marks when first data byte is received, followed by data.
+FTM=202	CONNECT	Transmit modem goes into data mode and waits for data from the DTE. When first data byte is received, modem sends Channel Seizure and marks followed by data.

9.2.1. SMS User Registers

User registers that set up SMS operations are shown in Table 147. The default settings are shown in bold.

Table 147. User Registers for SMS Operations

Register	Bits	Name	Description	Default (Hex)
U70	15	HES	Enables ESC (pin 22) **0 = Disabled** 1 = Enabled	0
UAA	2	RUDE	**0 = Disables rude disconnect** 1 = Enables rude disconnect	0
UCA	0	SMSMOD	Modulation for SMS data **0: Bell202** 1: V.23	0
UCB	15:0	TXCS	Number of channel seizure bits 0 = no Channel Seizure 1 to 65535 = number of continuous alternating spaces and marks in Channel Seizure.	2580
UCC	7:0	TXMK	Number of mark bits in message header	2580
UCD	0	CASRPT	Respond to CAS, don't report to the host (Auto) or do report to the host (Manual) **0 = Auto Mode** 1 = Manual Mode	0
UD1	11:0	TXDEL	Time the Originate modem waits before transmitting a frame, in 10 ms units. Timed from the termination of the previous signal.	0000
UD2	11:0	RXTO	Time that the Answer modem waits for the received signal after it receives the +FRM command; in 10 ms units	0000
UD3	15:0		V.29FC Answer Tone Detector Threshold (in ms). Range = 50–180 ms	0000
UD4	14:0	CTDT	CAS Tone Detector Threshold	0000
UD7	15:0		SMS Mark Length Threshold	0578

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9.2.2. Procedure

To enable the SMS features on the Si24xx, the host sends "AT+FCLASS=256" to the modem prior to an SMS call. To enable the hardware escape pin functions, the host would set HES with the command "AT:U70|8000".

After setting the other U-registers according to the configurations of the Originate and Answer modems, the host can dial an SMS call using the command "ATDTxxxx;" (where xxxx is the number to be dialed) or answer an SMS call with "ATDT;". The semi-colon at the end of the command places the modem into command mode after dialing. The modem responds to the host with "OK". The host then puts the modem into transmit or receive SMS data mode.

Many SMS POS protocols perform handshaking using CAS and CAS ACK. CAS is a two-tone signal (2130 Hz / 2750 Hz); CAS ACK is a DTMF 'D'. The terminal modem connects to the server, which sends CAS tones until it times out or the terminal modem replies to the server with CAS ACK. The threshold for the modem's CAS tone energy detector is set by CTDT, which has a default value of 500h. The CAS tone must have a minimum duration of 30 ms to guarantee detection.

CAS detection is enabled by setting the detector threshold UD4 to a value other than 7FFFh. When the CAS detector is enabled, FSK CS/MARK detection will run after CAS is detected. The modem will time out if CAS is not detected. (When implementing SMS POS protocols that don't use CAS and CAS ACK, the CAS tone detector must be disabled with the command AT:UD4,7FFF.)

Once CAS is detected, the modem responds with CAS ACK. The duration of CAS ACK is 60 ms.

CASRPT selects Auto or Manual mode for transmitting CAS ACK.

Auto mode (CASRPT = 0): Auto mode reduces the delay between CAS and CAS ACK. After an AT+FRM=200 command, the modem detects the CAS tones and sends CAS ACK without reporting CAS detection to the host.

Manual mode (CASRPT = 1): Manual mode allows the host processor to have more control. A modem reports to its host with the string "CAS" when it detects CAS tones. The modem waits for the host to reply with the ASCII character 'D', then it responds to the other modem with CAS ACK. If the host sends any character other than 'D', the modem returns to the command mode immediately without sending CAS ACK and replies to the host with <DLE><ETX>. This allows the host to send any DTMF digit. The host can then send an AT+FTM command or an AT+FRM command. If the host doesn't send any characters or commands, the modem will time out (as set by UD2) and go back on-hook without sending CAS ACK.

9.2.2.1. Example

The host could use this sequence to set up the modem for Protocol 1 SMS:

AT:UCA,1,0,4E	This sets up the modem for V.23 modulation, Protocol 1, 78 Mark bits in the message header.
AT+FTM=201	Transmit a Protocol 1 SMS frame
<CR><LF>CONNECT <CR><LF>	Modem response to the host

To set up the modem for Protocol 2 SMS:

AT:UCA,0,12C,4E	This sets up the modem for Bell 103 modulation, Protocol 2, 300 bit Channel Seizure, 78 Mark bits in the message header.
AT+FTM=202	Transmit a Protocol 2 SMS frame
<CR><LF>CONNECT <CR><LF>	Modem response to the host

In either protocol, the host must wait for the "CONNECT" response before it sends data. Transmission of data before this message can result in loss of information.

After the host receives "CONNECT ", it sends the frame data followed by <DLE><ETX>. A frame includes type, length, payload and checksum. The frame data can contain anything, including <DLE><ETX>. No DLE shielding is needed. <DLE><ETX> with no data for about 8ms is treated as the end of frame.

After a frame has been sent, the modem response will be: <CR><LF>OK<CR><LF>

On the answer modem side, the command AT+FRM=200 causes the receiver to look for at least 32 bits of CS and for at least 60 bits of marks. The answer modem detects the protocol of the transaction by whether CS comes before the marks.

AT+FRM=200	Receive an SMS frame
AT:UD2,<RxTimeout>	Set RxTimeout:

There can be several responses to AT+FRM=200, depending on the received data.

9.2.2.2. Response 1

If the frame had not been received within the time specified in RxTimeout, the modem response to the host would be:

<DLE><ETX><CR><LF>NO CARRIER<CR><LF>

9.2.2.3. Response 2

If the frame had been received with a mark segment at beginning of frame, the modem would respond to the host with:

CONNECT 1<CR><LF>

<Frame Data Received><DLE><ETX>

<CR><LF>OK <CR><LF>

No frame checking would be done by the modem; all of that would be left to the host. As shown above, <DLE><ETX> marks the end of frame. After sending OK to the host, the modem goes back into command mode.

9.2.2.4. Response 3

If the frame had been received with channel seizure and mark segment detected at beginning of frame, the modem would send one of the responses below to the host:

CONNECT 2<CR><LF>

 <Frame Data Received><DLE><ETX>

<CR><LF>OK <CR><LF>

The Host does all upper level frame validations, since the modem does not do any frame checking. As shown above, <DLE><ETX> signifies the end of frame. After the modem sends OK, it goes back to command mode.

9.3. Example Session

The example below shows a typical session. The user determines the values of the U-registers.

```
transmit "AT+FCLASS=256<CR>"  ;Enable SMS POS mode
waitfor "OK"


transmit "AT:UCA,0,12C,4E<CR>" ;Set SMS POS parameters
waitfor "OK"


transmit "ATD<phone number here>;<CR>"    ;dial out
waitfor "OK`x0d`x0a"
```

The ';' at the end of the dial string returns the modem to command mode after dialing. The modem will issue an OK after dialing.

```
transmit "AT:UD1,3C<CR>"   ; Set TxDelay = 600ms
waitfor "OK"


transmit "AT:UD2,3E8<CR>"  ; Wait 10 s for an answer.
waitfor "OK"


transmit "AT+FRM=200<CR>"  ; Go into data mode and wait for Originate modem
```

The length of the timeout is dependent on the host called. Once the connection is made, the answer modem's host expects to receive a frame such as:

```
0x81 0x00 0x05 0x13 0xcd 0xaa 0xa4 0x00 0x4c
```

Followed by:

```
<DLE><ETX><CR><LF>OK<CR><LF>
```

Once a frame has been received, the receive modem becomes the transmit modem. The server returns a frame of data to the terminal.

```
transmit "AT+FTM=202<CR>"; Use Protocol 2
waitfor "CONNECT `x0d`x0a"
```

Transmit a frame such as:

```
0x82 0x00 0x05 0x6c 0xea 0x50 0x6b 0x00 0x68
transmit "`x10`x03"             ; Send <DLE><ETX> at the end of frame
waitfor "OK`x0d`x0a"
```
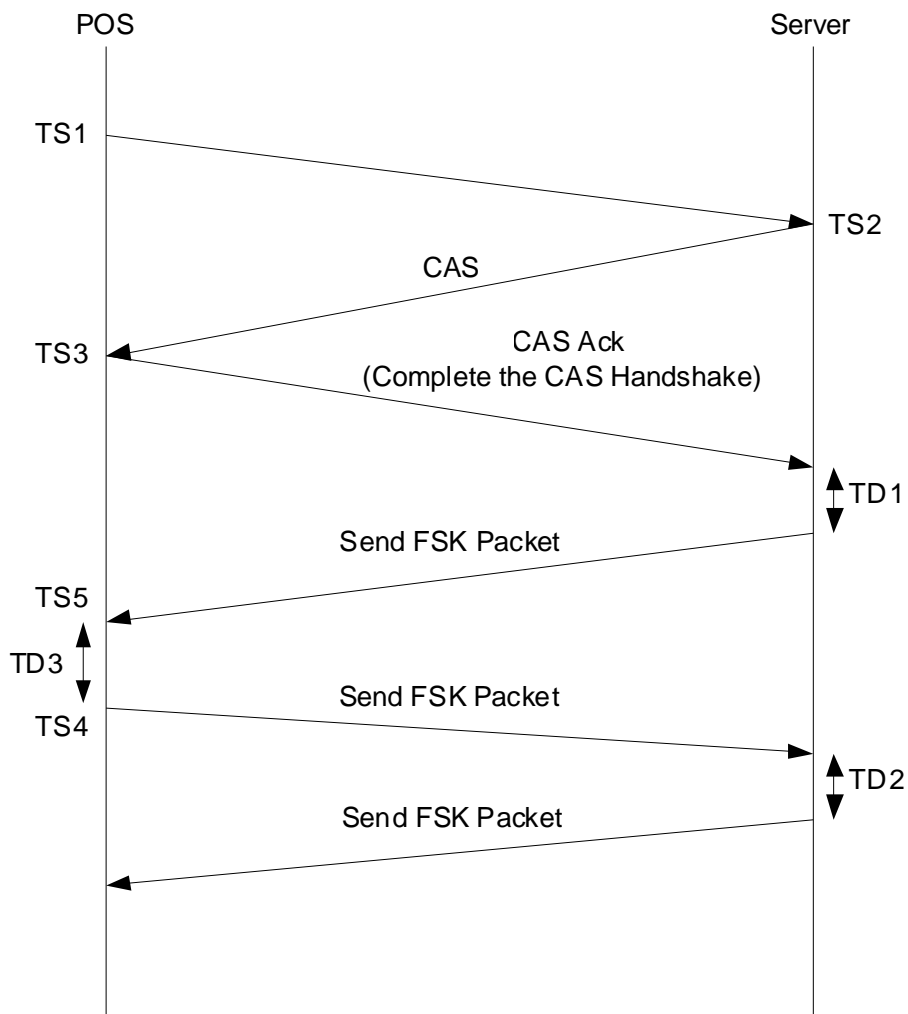
Figure 38. Diagram of Handshake (Using CAS/CAS ACK) and Message Packet Exchange

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For Figure 39, assume that the originating modem transmits first and that the two modems alternate transmitting and receiving. For simplicity, this figure does not show the provisions for timeout cases.
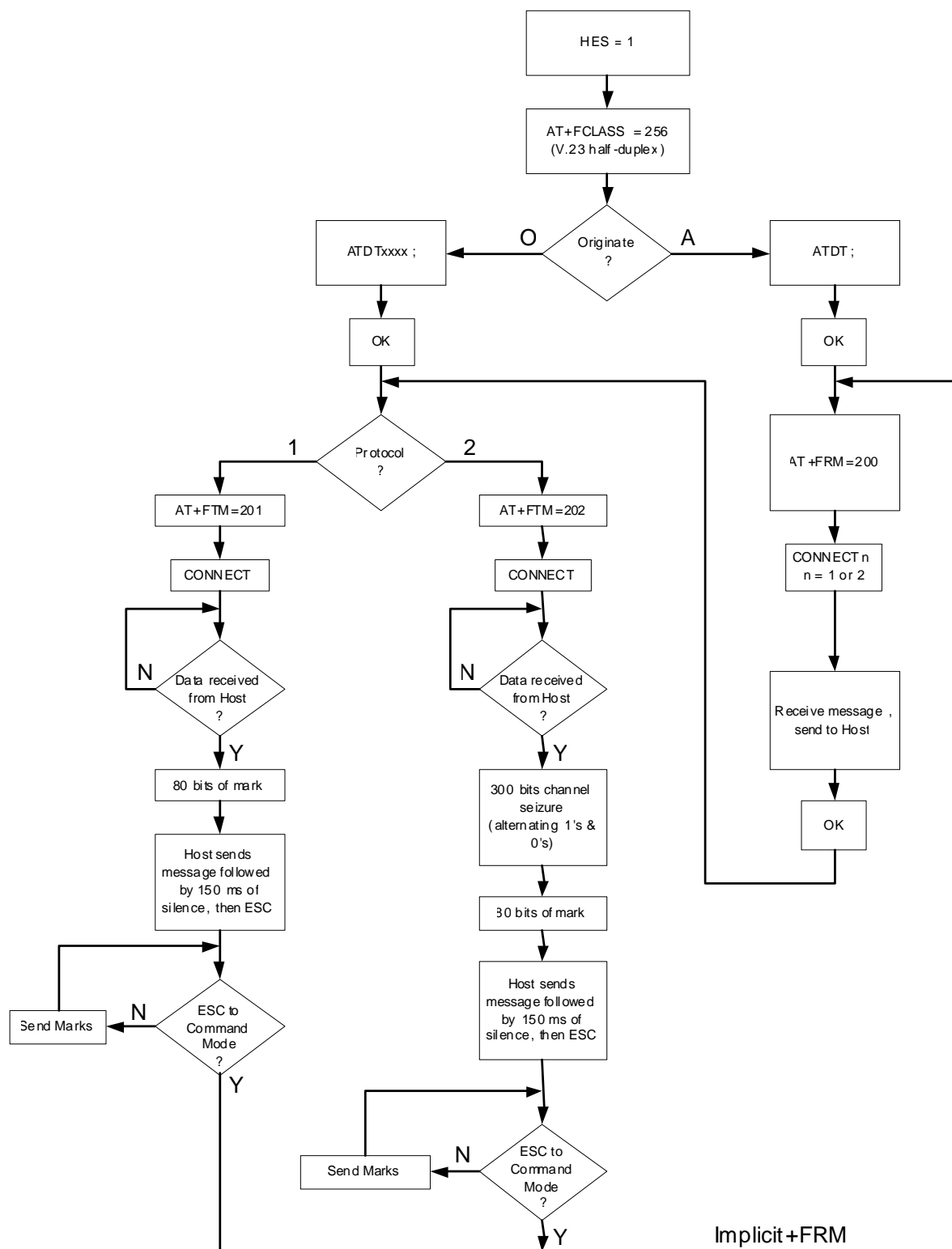
Figure 39. SMS Process in Host and Modem

10. Testing and Diagnostics

10.1. Prototype Bring-Up (Si3018/10)

10.1.1. Introduction

This section provides tips for the debugging of initial prototypes. Although most ISOmodem prototype designs function as expected, there is the potential for layout errors, omitted or incorrect components used in the initial assembly run, and host software problems. If the prototype modem does not function correctly, the techniques outlined in this guide will help quickly isolate the problem and get the prototype functioning correctly. A functional ISOModem evaluation board and data sheet and a computer with HyperTerminal are required for some of the troubleshooting steps. It is assumed that the designer has read the data sheet, implemented the reference design using the recommended bill of materials, and carefully followed the layout guidelines presented in "4.4. Layout Guidelines" on page 49. Troubleshooting begins with system-level checks and then proceeds all the way down to the component level. In this chapter, all system-side pin numbers refer to the 24-pin TSSOP package and all line-side pin numbers refer to the 16-pin version.

10.1.2. Visual Inspection

Before troubleshooting, be certain that the circuit boards and components are clean. Carefully wash the boards to remove all solder flux and solder flakes. Inspect the modem circuitry to ensure all components are installed, and inspect all solder joints for incomplete connections, cold solder joints, and solder bridges. Check all polarized components, such as diodes and capacitors, for correct orientation. Thoroughly clean the circuit board after replacing a component or soldering any connection.

Reset the Modem

Make sure the modem is reset after the power and clocks are applied and stable.

10.1.3. Basic Troubleshooting Steps

- **Check the Power**
  With power off, use an ohmmeter to verify that the system ground is connected to ISOmodem pin 6. Turn on system power and measure the voltage between pin 5 and pin 6 and between pin 21 and pin 6 on the ISOmodem. In both cases, the voltage should be 3.3 V. If this is not the case, check the power routing. If power is present, go to the next step.

- **Check the Phone Line**
  Check the phone line with a manual telephone to be sure that there is a dial tone and that dialing is possible. The dc voltage across Tip and Ring should read approximately 40–52 V with the phone on-hook.

- **Reset the Modem**
  Do a manual reset on the modem. Hold ISOmodem pin 12 ($\overline{\text{RESET}}$) low for at least 5 ms, return to V_{DD} (3.3 V), and wait for at least 300 ms before executing the first AT command.

- **Check the DTE Setup (UART Mode)**
  Be sure the DTE (host) serial port is configured the same as the modem. The default condition is eight data bits, no parity-bit, one stop-bit, and a DTE rate of 19.2 kbps.

- **Check the DTE Connection (UART Mode)**
  Check the DTE interface connection. Be sure the $\overline{\text{RTS}}$ (ISOmodem pin 8) and $\overline{\text{CTS}}$ (ISOmodem pin 11) signals are low.

- **Check the Pulldown Configuration Resistors**

- **Check the Modem Configuration**

Read back the modem register settings and correct any inconsistencies. The ATS$ command lists the contents of all S registers, and the AT:R command lists the contents of all U registers.

If the problem was not located with these basic troubleshooting steps, it is time to narrow the problem down to the host system (hardware and software), the ISOmodem chip and associated components, or the Si3018/10 and associated components.

- **AT OK?**
  The modem responds with an OK to the command AT<CR>. This indicates that the host processor/software is communicating with the modem controller, and problems are in one of the following areas:

- **Inappropriate Commands**
  Verify that all AT commands used are supported by the ISOmodem and comply with the proper format. Be sure each command and argument is correct. Do not mix upper- and lower-case alpha characters in an AT command. An AT command string must contain 48 or fewer characters followed by a carriage return. Command strings greater than 48 characters are ignored.

- **Command Timing**
  The execution time for an AT command is approximately 200 ms. Execution is complete when OK is received. Subsequent AT commands should wait for the OK message, which appears within 200 ms after the carriage return. The reset recovery time (the time between the rising edge of a hardware reset or the carriage return of an ATZ command and the time the next AT command can be executed) is approximately 300 ms. When a data connection is being established, do not try to escape to the command mode until after the protocol message.

- **Register Configurations**
  The ATS$ command lists the contents of all S registers, and the AT:R command lists the contents of all U registers.

- **Si3018/10 and/or Associated Components**
  If the modem goes off-hook and draws loop current as a result of giving the ATH1 command, go to "10.1.6. Si3018/10 Troubleshooting".
  If the modem does not go off-hook and draw loop current as a result of giving the ATH1 command and receiving an OK message, begin troubleshooting with the isolation capacitor at the ISOmodem. First, check all solder joints on the isolation capacitors, Si3018/10, and associated external components. If no problems are found, proceed to "10.1.5. Isolation Capacitor Troubleshooting" to verify whether the problem is on the ISOmodem or the Si3018/10 side of the isolation capacitor. If the problem is found to be on the ISOmodem side, check C50, C51, C53, the corresponding PCB traces, and the ISOmodem pins. Correct any problem found. If no problems are found with the external components, replace the ISOmodem. If the problem is found to be on the Si3018/10 side of the isolation capacitor, go to "Si3018/10 Troubleshooting".
  If the modem does *not* respond with an OK to the command AT<CR>, this indicates that the host processor/software is not communicating with the modem controller, and the problem can be isolated as follows:

- **ISOmodem Clock is Oscillating**
  First, be sure the ISOmodem is properly reset and $\overline{\text{RESET}}$, pin 12, is at 3.3 V. Next, check the DTE connection with the host system. If this does not isolate the problem, go to "10.1.4. Host Interface Troubleshooting".

- **ISOmodem Clock is Not Oscillating**
  Check the voltage on the ISOmodem, pins 5 and 21, to be sure the chip is powered. Also, check that pins 6 and 20 are grounded. Next, check the solder joints and connections (PCB traces) on C40, C41, Y1, and the ISOmodem Pin 1 and Pin 2. Measure C26 and C27 (or replace them with known good parts) to ensure that they are the correct value. If these steps do not isolate the problem, replace the ISOmodem.

10.1.4. Host Interface Troubleshooting

The methods described in this section are useful as a starting point for debugging a prototype system or as a continuation of the troubleshooting process described previously. The procedures presented in this section require a known good ISOModem evaluation board and data sheet. This section describes how to substitute the evaluation board for the entire modem circuitry in the prototype system. Substituting a known operational modem can help isolate problems quickly. The first step is to substitute the evaluation board for the complete modem solution in the prototype system. This immediately demonstrates whether any modem functionality problems are in the prototype modem circuitry or in the host processor, interface, or software.

- **Verify ISOModem Evaluation Board Functionality**
  Connect the evaluation board to a PC and a phone line or telephone line simulator. Using a program, such as HyperTerminal, make a data connection between the evaluation board and a remote modem. Remove power and the RS232 cable from the evaluation board and proceed to the next step.

■ **Connect Evaluation Board to Prototype System**

Completely disconnect the embedded modem from the host interface in the prototype system. Connect the ISOModem evaluation board to the host interface using JP3 as described in the ISOModem evaluation board data sheet section titled Direct Access Interface. This connection is illustrated in Figure 40. Be sure to connect the evaluation board ground to the prototype system ground. Power up and manually reset the evaluation board, then power up the prototype system and send AT<CR>. If an OK response is received, make a connection to the remote modem as in the previous step. If no OK response is received, debug host interface and/or software. If a connection is successful, go to the next step to isolate the problem in the prototype modem.

An alternative approach is to connect the prototype modem to the ISOModem EVB motherboard in place of the daughter card and use a PC and HyperTerminal to test the prototype modem. See Figure 41 for details.

10.1.5. Isolation Capacitor Troubleshooting

Connect the evaluation board isolation capacitor to Prototype Modem Si3018/10. Remove C1 on the evaluation board and on the prototype system. Solder one end of the evaluation board, C1, to the ISOmodem-side pad leaving the other end of C1 unconnected. Next, solder a short jumper wire from the unconnected side of C1 on the evaluation board to the Si3018/10-side C1 pad on the prototype system. This connection is illustrated in Figure 42. Connect the phone line to the prototype system RJ-11 jack.

Power up and manually reset the evaluation board, then power up the prototype system. Attempt to make a connection using the host processor and software, the evaluation board ISOmodem, and the prototype system Si3018/10 and associated external components. If this connection is successful, the problem lies with the PCB layout, the external components associated with the ISOmodem or the ISOmodem device itself.

If the connection attempt is not successful, the problem lies with the Si3018/10 and/or associated components. Proceed to "Si3018/10 Troubleshooting".

This diagnosis can be validated by connecting the Host ISOcap capacitors to the Si3018/10 on the evaluation board as shown in Figure 43.

10.1.6. Si3018/10 Troubleshooting

Start by measuring the on-hook and off-hook voltages at the Si3018/10 pins with respect to IGND (pin 15). Compare these voltages to those in Figure 44. This may indicate an area of circuitry to investigate further using the Component Troubleshooting techniques in the following section. The voltages measured should be reasonably close to those in the figure.

If any of the on-hook or off-hook Si3018/10 pin voltages are significantly different than those in Figure 44 and nothing seems wrong with the external circuitry after using the Component Troubleshooting techniques, replace the Si3018/10.

10.1.7. Component Troubleshooting

A digital multimeter is a valuable tool for verifying resistances across components, diode directions, transistor polarities and node voltages. During this phase of troubleshooting, it is very useful to have a known, good ISOModem evaluation board to compare against measurements taken from the prototype system. The resistance values and voltages listed in Tables 148, 149, and 150 will generally be enough to troubleshoot all but the most unusual problems.

Start with power off and the phone line disconnected. Measure the resistance of all Si3018/10 pins with the Ohmmeter's black lead on pin 15 (IGND). Compare these measurements with the values in Table 148. Next, measure the resistance across the components listed in Table 149 and compare the readings to the values listed in the table. Finally, using the diode checker function on the multimeter, check the polarities of the transistors and diodes as described in Table 150. The combination of these measurements should indicate the faulty component or connection. If none of the measurements appears unusual and the prototype modem is not working, replace the Si3018/10.

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Prototype System

Host
Controller

Host
UART

Si24xx

Si3018

Discretes

RS232
Transceiver

Si24xx

Si3018

Discretes

To
Phone
Line

EVB
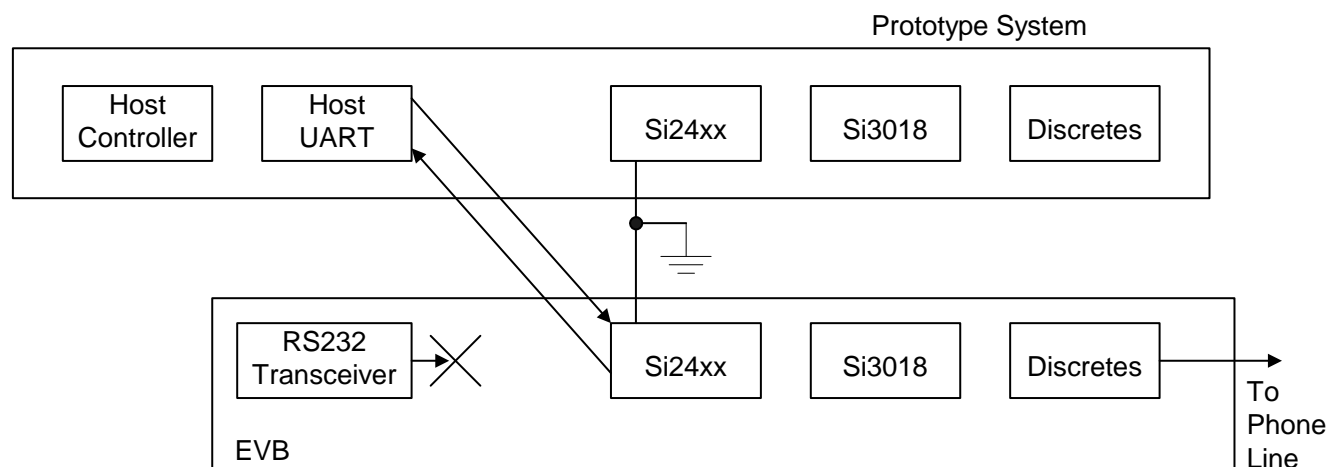
- Connect prototype system ground to EVB ground
- Disable RS232 transceiver outputs (check evaluation board data sheet)
- Disconnect prototype modem interface
- Connect the evaluation board to the target system

Figure 40. Test the Host Interface

Prototype System

Host
Controller

Host
UART

Si24xx

Si3018

Discretes

To
Phone
Line

PC

RS232
Transceiver

Si24xx

Si3018

Discretes

EVB
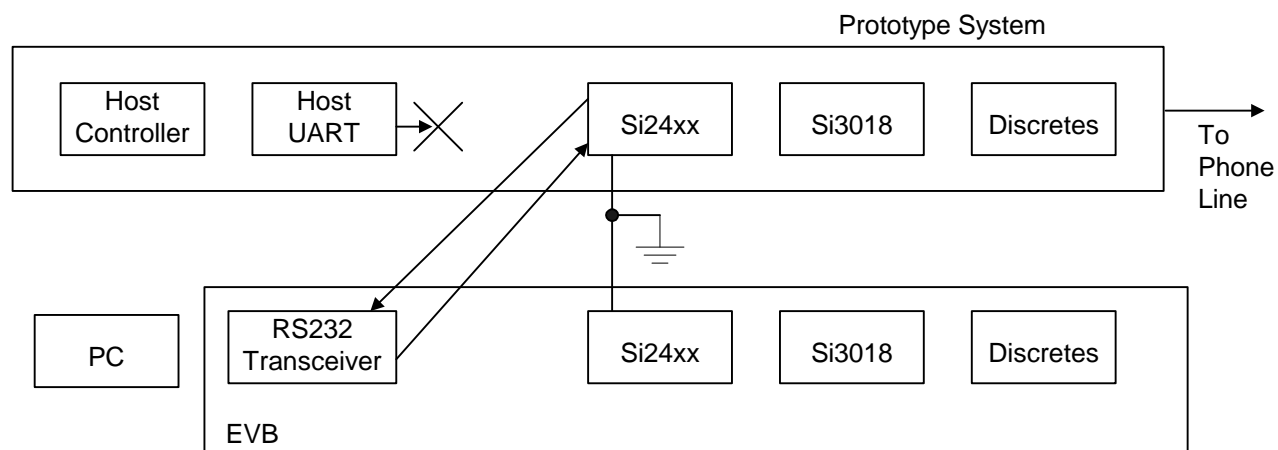
- Connect prototype system ground to EVB ground
- Remove modem module from EVB
- Disconnect host outputs from prototype modem
- Connect EVB RS232 transceivers to prototype modem
- Use PC with HyperTerminal to test prototype modem

Figure 41. Test the Prototype Modem

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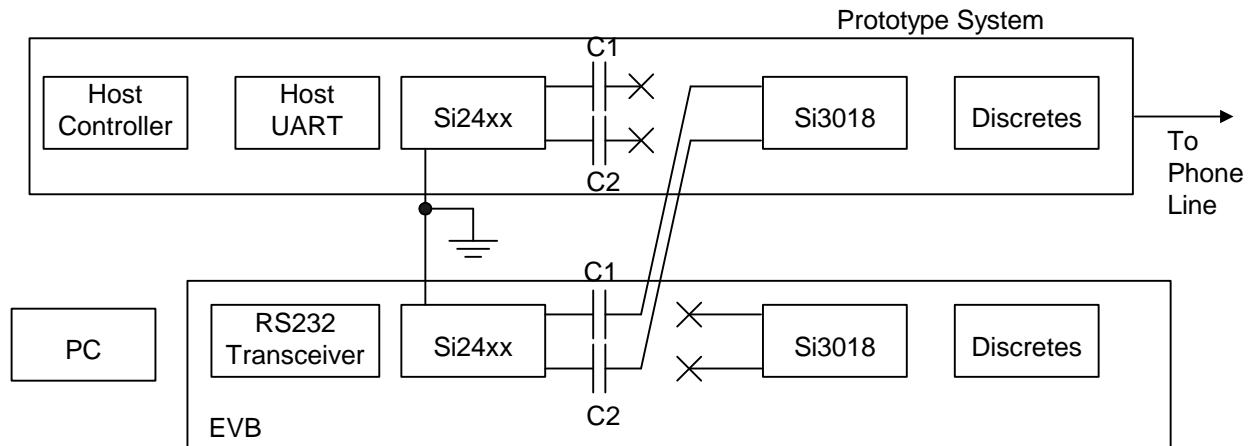
- Connect the prototype ground to the EVB ground.
- Lift prototype C1 and C2 and EVB C1 and C2 so the Si3018 is disconnected from the Si24xx on both modems.
- Connect EVB C1 and C2 to the Si3018 pad of prototype system C1 and C2.
- Connect the phone line to the RJ11 jack on the prototype system.
- Use PC and HyperTerm and attempt to establish a modem connection.

Figure 42. Test the Prototype Si3018/10 Circuitry
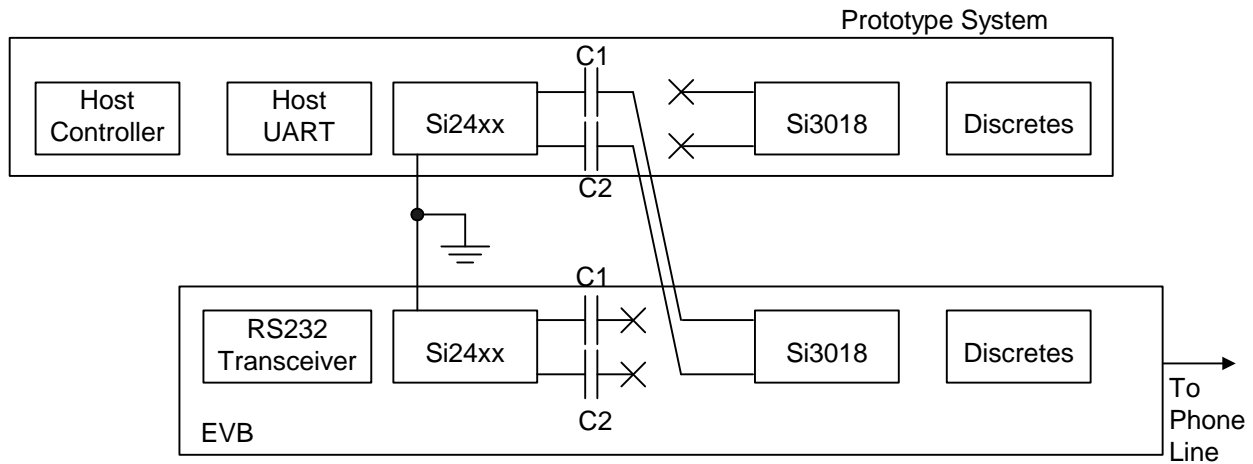
- Connect the prototype ground to the EVB ground
- Lift prototype and EVB C1 and C2 to decouple the line side from the DSP side. Do same on evaluation board.
- Connect prototype system C1 and C2 to the Si3018 pad of EVB C1 and C2
- Connect the phone line to the RJ11 jack on the EVB
- Run the prototype system software to attempt a modem connection

Figure 43. Verify Prototype Si3018/10 Failure

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On-Hook

```
0 V ── QE        DCT2 ── 0 V
0 V ── DCT       IGND ──
0 V ── RX        DCT3 ── 0 V
0 V ── IB          QB ── 0 V
0.5 V ── C1B      QE2 ── 0 V
0.9 V ── C2B       S2 ── 0 V
~2.3 V ── VREG   VREG2 ── 0 V
~1.0 V ── RNG1   RNG2 ── ~1.0 V
```

Off-Hook

```
1.6 V ── QE        DCT2 ── 2.2 V
3.4 V ── DCT       IGND ── 0 V
2.5 V ── RX        DCT3 ── 1.6 V
0 V ── FB            QB ── 2.8 V
0.5 V ── CIB        QE2 ── 2.1 V
0.9 V ── C2B         SC ── 0 V
2.3 V ── VREG     VREG2 ── 1.8 V
1.0 V ── RNG1     RNG2 ── 0.9 V
```

Voltages measured with respect to IGND (Si3018 pin 15)

Figure 44. Si3018/10 Typical Voltages

Table 148. Resistance to Si3018/10 Pin 15

Si3018/10	Resistance
Pin 1	> 6 MΩ
Pin 2	> 5 MΩ
Pin 3	> 2 MΩ
Pin 4	1 MΩ
Pin 5	> 5 MΩ
Pin 6	> 5 MΩ
Pin 7	> 1 MΩ
Pin 8	> 2 MΩ
Pin 9	> 2 MΩ
Pin 10	> 1 MΩ
Pin 11	0 Ω
Pin 12	> 2 MΩ
Pin 13	> 5 MΩ
Pin 14	> 14 MΩ
Pin 16	> 5 MΩ

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Table 149. Resistance across Components

Si3018/10	Resistance
FB1	< 1 Ω
FB2	< 1 Ω
RV1	> 20 MΩ
R1	1.07 kΩ
R2	150 Ω
R3	3.65 kΩ
R4	2.49 kΩ
R5	100 kΩ
R6	100 kΩ
R7	4.5 or 16 MΩ
R8	4.5 or 16 MΩ
R9	> 800 kΩ
R10	536 Ω
R11	73 Ω
R12	< 1 Ω
R13	< 1 Ω
R15	< 1 Ω
R16	< 1 Ω
C1	> 20 MΩ
C2	> 20 MΩ
C3	> 3 MΩ
C4	3.5 MΩ or 9.7 MΩ
C7	2 MΩ or 5 MΩ
C8	> 20 MΩ
C9	> 20 MΩ

Note: If two values are given, the resistance measured is dependent on polarity.

Table 150. Voltages across Components with Diode Checker

Component	Voltage
Q1, Q3, Q4, Q5: Base (red lead) to Emitter (black lead) Base (red lead) to Collector (black lead) (Verifies transistors are NPN)	0.6 V 0.6 V
Q2: Emitter (red lead) to Base (black lead) Collector (red lead) to Base (black lead) (Verifies transistor is PNP)	0.6 V 0.6 V
Collector of Q2 (red lead) to pin 1 of Si3018/10 (black lead) If test fails, Z1 is reversed.	> 1 V

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10.2. Self Test

The Si24xx ISOmodem's advanced design provides the system manufacturer with an enhanced ability to determine system functionality during production tests and to support end-user diagnostics. In addition to local echo, a loopback mode allows increased test coverage of system components. For the loopback test mode, a line-side power source is required. While a standard phone line can be used, the test circuit shown in Figure 45 is adequate.
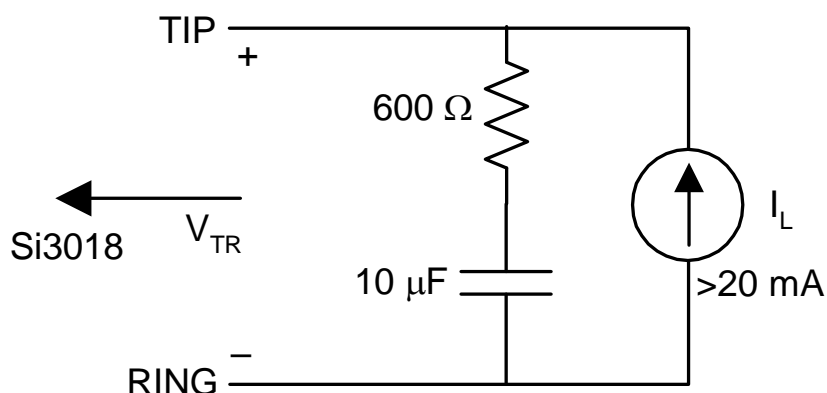
Figure 45. Loop Test Circuit

The AT&Tn command, in conjunction with the AT&Hn command, performs a loopback self test of the modem. AT&Hn determines the modulation used for the test (V.22bis, V.32bis, etc). If an AT&Hn command is not issued just prior to the start of the test, the default or previously-selected modulation is used. The modulation options and defaults are listed in Table 40 on page 77. The test is started with an AT&T2 or AT&T3 command. During the test, the modem is in data mode. To end the test, escape data mode using one of the "Escape" methods, such as +++, and end the test with ATH.

The AT&T2 command initiates a test loop from the DSP through the DAA interface circuit of the ISOmodem. Transmit data are returned to the DSP through the receive channel. In the parallel or SPI mode, the transmit data are passed to the receiver via Hardware Interface Register 0. AT&T2 tests only the Si24xx chip, not the Si3018/10.

The AT&T3 command initiates a test loop from the DSP through the DAA interface, the ISOcap interface, the Si3018/10, and the hybrid circuit. This test exercises the Si24xx, the Si3018/10, and many external components. A phone line termination with loop current and no dial tone is required for this test since it involves the line-side chip (Si3018/10) and the hybrid. The modem is off-hook during this test. The AT&T3 mode is useful during emitted and conducted radiation testing. To test the ISOcap link only, set U62 (DL) [1] = 1 and issue the AT&T3 command.

The AT\U command is also useful as a production test. This command places a 25 ms low pulse on the $\overline{RI}$ and $\overline{DCD}$ pins. It also makes $\overline{INT}$ the inverse of ESC and $\overline{RTS}$ the inverse of $\overline{CTS}$. Sending the AT\U command can be used to verify the connection of these pins to the circuit board. This command is terminated by resetting the ISOmodem.

10.3. Board Test

The modem and DAA chips come from Silicon Laboratories 100% functionally tested on automatic test equipment to guarantee compliance with the published chip specifications. The functionality of a finished product containing an ISOmodem chipset depends not only on the functionality of the modem chipset after assembly but also on discrete components and product-related software. Finished product test requirements and procedures depend on the manufacturer and on the product. Consequently, no universal final test procedure can be defined.

Testing the modem in a finished product is done for several reasons. First, it is important to be sure the modem chipset and peripheral components were installed correctly during assembly and were not damaged. Second, it is necessary to be sure the correct component values were installed and that there are no manufacturing problems, such as solder bridges, cold solder joints, or missing components.

Functional testing can be used to test special features, such as intrusion detection, Caller ID, and overcurrent detection. An intrusion can be simulated by placing a 1 kΩ resistor across Tip and Ring through a relay. Caller ID testing requires special test equipment, such as the Rochelle 3500 or Advent AI-150.

Many manufacturers choose to use built-in self-test features, such as the &T3 Loopback test described above. Others do a complete functional test of the modem by originating and answering a call and successfully passing a data file in each direction. This process tests the modem and line-side chip functionality, the associated external components, and the software controlling the modem. This test can be done with a modem under test (MUT) and a known-good reference modem, or between two modems under test. Testing two modems under test at once reduces test and setup times. Modem operational testing is time consuming and adds to product cost. It is up to the manufacturer to determine whether operational testing is warranted.

Analog modems (Bell 103 through V.34) can be tested by connecting the modems through a telephone line simulator, such as Teltone TLS-3. A call can be placed or received in either direction at the speed set in the modems. A test script must be written for a computer to control the dialing, monitor the call progress, send a file, and compare the received and sent file. Figure 46 illustrates this test configuration.
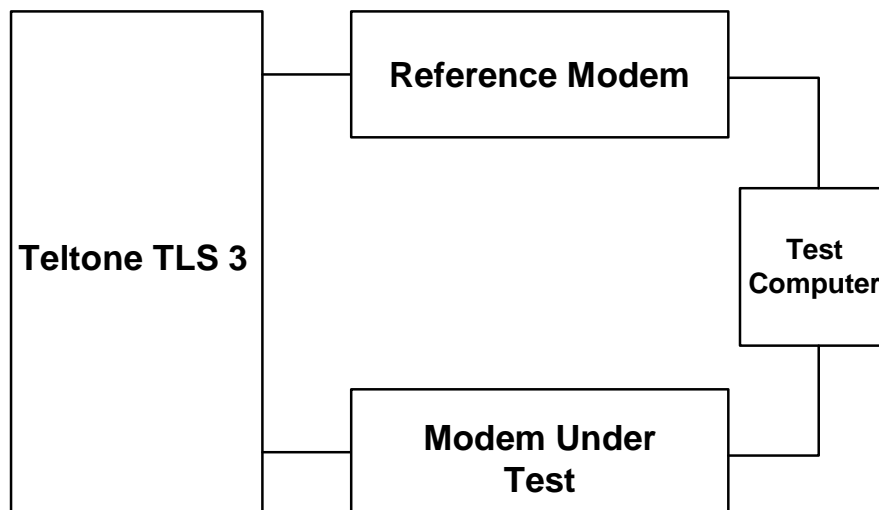
Figure 46. Bell 103–V.34 Modem Functional Test Connection

V.90 modems must be tested with a digital modem, such as the USR Courier I. If a digital modem isn't used as illustrated in Figure 47, the highest connection speed a V.90 modem will support is 33.6 kbps. A call can be placed or received in either direction at the speed set in the modems. A test script must be written for a computer to control the dialing, monitor the call progress, send a file, and compare the received and sent files. Figure 47 illustrates this test configuration.
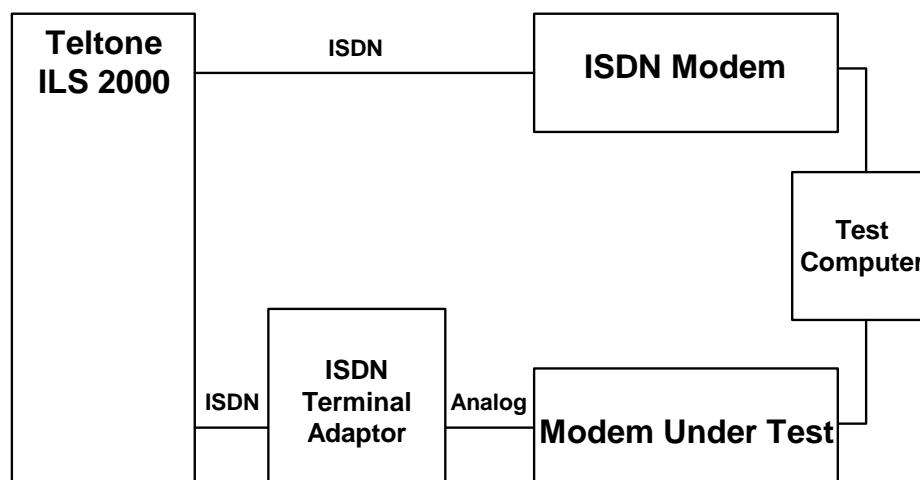
Figure 47. V.90 Modem Functional Test Connection

Table 151 compares the coverage of &T2, &T3, and full bidirectional functional testing.

Table 151. Test Coverage

Circuit or Function	&T2	&T3	Functional Test
Si24xx chip	Yes	Yes	Yes
ISOcap Operation	Yes	Yes	Yes
Si3018/10 Operation		Yes	Yes
Hookswitch		Yes	Yes
dc Termination		Yes	Yes
Bridge		Yes	Yes
AC Termination		Yes	Yes
Line Voltage Monitor			Yes
Ringer Network			Yes
Intrusion Detection			Yes
Caller ID			Yes
Overcurrent Detection			Yes

10.4. Compliance Testing

Regulatory compliance testing requires the modem to be configured in specific ways and controlled to perform specific operations necessary to make required measurements. Compliance testing commands and configuration information are provided.

Some helpful commands for conducting compliance testing on the ISOmodem are listed in Table 152. The modem register defaults configure the modem for FCC operation.

Table 152. AT Commands for Compliance Testing

AT Command/Test Method	Desired Response
ATH1	Continuous off-hook
ATH0	Return on-hook
AT&Hn (see command description for n)	Set modulation
AT&T3 (requires load and loop current)	Turn on carrier (originate)
Set S10 = 255 to keep the modem under test from hanging up after the remote modem is unplugged. Connect with another modem (Si24xx in answer mode); then, unplug the other modem.	Turn on carrier (answer)
AT&T4	Initiate transmit as originating modem with automatic data generation
AT&T5	Initiate transmit as answering modem with automatic data generation
ATX0	Blind dial (no dial tone)
AT*Y1D<digit> (example: AT*Y1D1 for DTMF1)	Send continuous DTMF digit
ATM2	Speaker on continuously
ATM0	Turn off speaker
AT:Uhh,xxxx (hh is U register and xxxx is the hex value to be written)	Write a U register
AT:Rhh (hh is U register)	Read a U register
AT:R	Read all U registers
ATA	Send Answer Tone for 3 seconds
AT:U4D,0008 ATX0 ATDT	Send Calling Tone
Connect test modem and remote modem through a telephone line simulator. Configure test modem without protocol. Set test modem S10 = 255. Connect phone in parallel to remote modem. Set remote modem to desired modulation. Dial remote modem and connect. Take parallel phone off-hook. Remove power from remote modem. Test modem transmits indefinitely.	Transmit a specific modulation

Homologation testing requires that the ISOmodem signal output be measured for each modulation and data rate. The AT&T3 command establishes an analog loopback connection to the phone line and places the modem in data mode. The modulation is controlled by the &H command. This command is insufficient for homologation for several reasons:

■ It is not possible to configure the output tone to be as if from the answering or originating modem.

■ It is not possible to configure the data rate used in an analoop connection within a given modulation.

■ Three data patterns need to be sent during output testing: all marks, all spaces, and random data.

Once transmission with automatic data generation is initiated, the modem goes off-hook and begins to transmit the data in the modulation selected by the existing &H command. Transmission continues until the ATH command is sent after escape.

The data sent during &T4 and &T5 transmission tests is controlled by the S40 register. The data rate for &T4 and &T5 commands is controlled by the existing &G command. In V.34 cases, where a data rate may use multiple symbol rates, the symbol rate is controlled by the S41 register. If an invalid combination of data/symbol rate is selected, the modem chooses a valid symbol rate. It is the responsibility of the operator to select valid combinations for testing.

Table 153. Symbol/Data Rate

S41	V.34 Symbol Rate	Allowable Data Rates
0 (default)	2400 symbols/second	2400–21600
1	2743 symbols/second	4800–26400
2	2800 symbols/second	4800–26400
3	3000 symbols/second	4800–28800
4	3200 symbols/second	4800–31200
5	3429 symbols/second	7200–33600

After the &T4 or &T5 command is issued and the modulation output has begun, a result code stating CONNECT followed by the data rate (as if the output were an actual connection) is sent. The 300 bps rate does not give the speed after CONNECT. The &G4 command allows V.34/2400bps operation, and &G3 allows V.22bis/1200 bps operation.

The answer tone output must also be measured during homologation testing. A bit in memory allows a continuous answer tone to be output in the same way as a continuous DTMF tone through the AT*Y1 command. After issuing the commands AT&H10 and AT*Y2A, a constant answer tone is produced, and the modem is returned to command mode. Both AT commands need to be sent for each and every tone to be produced. Each of the two commands need to be on its own command line. The tone continues until a character is received or the S7 timer expires. After the command has been terminated, the modem returns on-hook and sends the NO CARRIER message.

For homologation testing, it may be necessary to output the V.29 modulation with transmit data. The +FTM command includes additional codes given in Table 154 to initiate output with the transmit data specified in S40.

Table 154. V.29 Data Rate

+FTM=	Transmit Modulation	Data Rate
53	V.29	7200
55	V.29	9600

The AT+FCLASS=0 command must be sent before any other analoop test or connection is made. The modem must remain on-hook for a time programmed in S-register 50. Any attempt to go off-hook is delayed by this time in 1 s units. S-50 default is 3 seconds.

There is a double CONNECT message for analoop in B1O3, V.21, and V.23 for all options except \V0.

10.4.1. EMI

The ISOmodem chipset and recommended DAA schematic are fully compliant with and pass all international electromagnetic emissions and conducted immunity tests (including FCC parts 15 and 68; EN50082–1). Careful attention to the ISOmodem schematic (page 47), bill of materials (page 48), and layout guidelines ensure compliance with these international standards. In designs with difficult layout constraints, the addition of R12 and R13 to the C8 and C9 recommended capacitors may improve modem performance on emissions and conducted immunity. For such designs, a population option for R12 and R13 may allow additional flexibility for optimization after the printed circuit board has been completed. Also, under some layout conditions, C8 and C9 may improve the immunity to telephone-line transients.

10.4.2. Safety

Designs using the ISOmodem pass all overcurrent and overvoltage tests for UL1950 3rd Edition with the addition of a 1.25 A Fuse or PTC, as shown in Figure 48. In a cost-optimized design, compliance to UL1950 does not always require overvoltage tests. In the design cycle, it is important to plan ahead and know which overvoltage tests will apply. System-level elements in the construction, such as fire enclosure or spacing requirements, need to be considered during the design stages. Consult with a testing agency during product design to determine which tests will apply.

1000 Ω @ 100 MHz, 200 mA
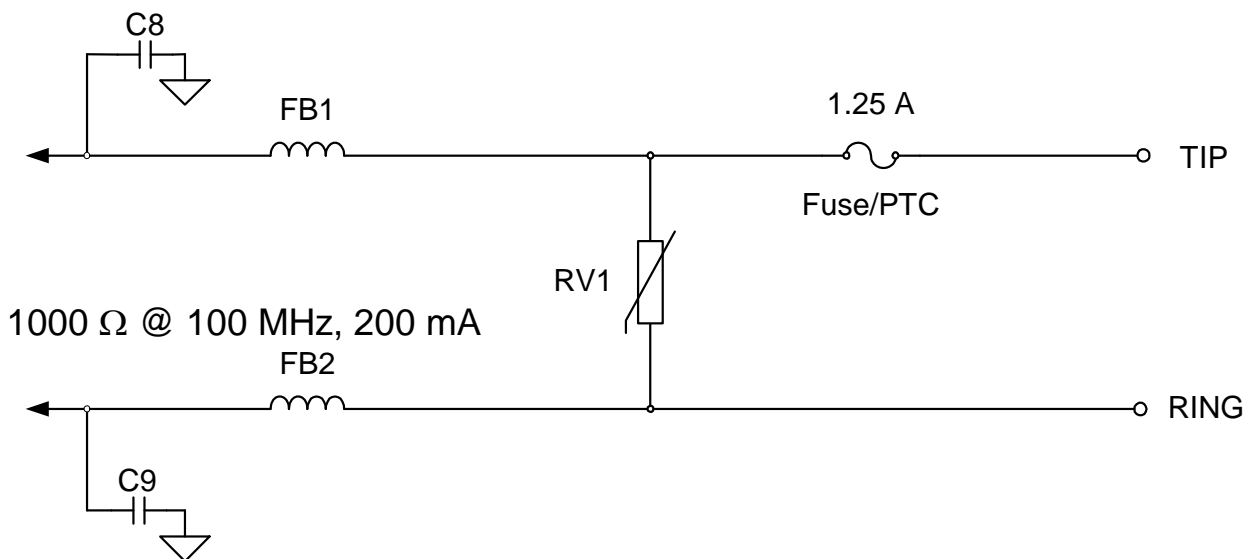
Figure 48. Circuits that Pass All UL1950 Overvoltage Tests

10.4.3. Surges

Use the reference design described in "4. Hardware Design Reference" on page 43 with through-hole Y1 capacitors for C1, C2, C8, and C9. Use spacing between the capacitor leads, between any line-side (high voltage) component or trace and system side (low voltage) component or trace greater than 8 mm. Also, the spacing between any line-side component or trace (or through-hole lead extending through the PCB) and the chassis (or anything connected to the chassis or low voltage circuitry) must be greater than 8 mm or protected with insulating material capable of withstanding a voltage greater than 8 kV. Additionally, slots cut through the PCB are recommended between the leads of C1, C2, C8, and C9 for increased creepage. The PCB and components should be clean and free of contamination, such as solder flux or other residue. The design engineer must verify the spacing indicated above meets or exceeds any specifications with which they wish to comply. The ISOmodem, used with the components and techniques described above, offers the highest reliability and lowest cost of any available solution. The use of supplemental surge-suppression components is not recommended.

10.5. AM-Band Interference

In certain areas, AM-band interference causes poor connectivity rates and error rates. A good EMI common-mode filter may be necessary in some situations. An example of an off-the-shelf unit designed to plug directly into the phone line is the Coilcraft TRF-RJ11, which can be used for debugging or fixing problem locations.

Eliminating common mode EMI from telephone lines, handset cords, and LANs can be done quickly and easily with these plug-in filter modules.

One, two, and four line (two, four and eight wire) versions are available with RJ11, RJ14, or RJ45 standard terminations. They're designed to help meet FCC Part 15 and 68 as well as European CCITT and CISPR-22 requirements.

Part number	Lines	A max	B max	C min	C max
TRF-RJ11	1	0.68/17,2	0.84/21,3	4.54/115,3	5.54/140,7
TRF-RJ14	2	0.68/17,2	0.84/21,3	4.54/115,3	5.54/140,7
TRF-RJ45-8	4	0.89/22,6	0.83/21,1	4.26/108,2	5.26/133,6

Typical Attenuation[1]
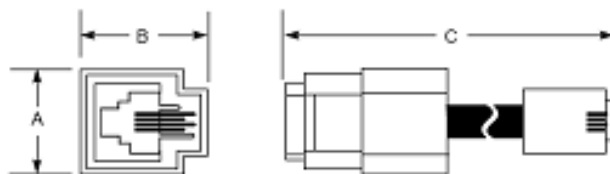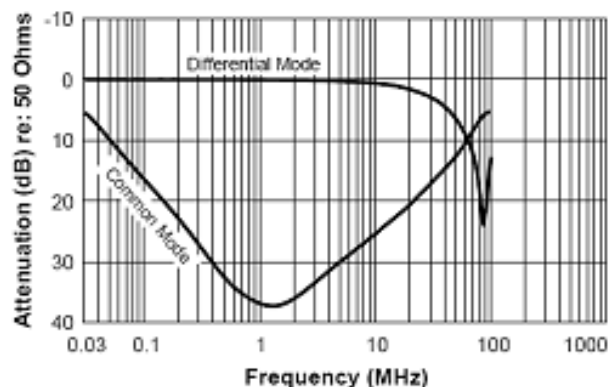
Figure 49. Published Coilcraft TRF-RJ11 Filter Performance

10.6. Debugging the DTE interface

A hardware-based serial RS232 monitoring product, such as the Parascope Plus, is an invaluable tool for debugging the DTE/DCE Interface. It captures and records details of DTE - DCE interaction. Hexadecimal and bit-shifted views are possible, and it timestamps every character exchanged with much greater precision than a software-based monitor. It is sold by FETEST at http://www.fetest.com.

Feline WinXL serial transaction log.

Silabs IsoModem eval. board

Timestamp of highlighted char.
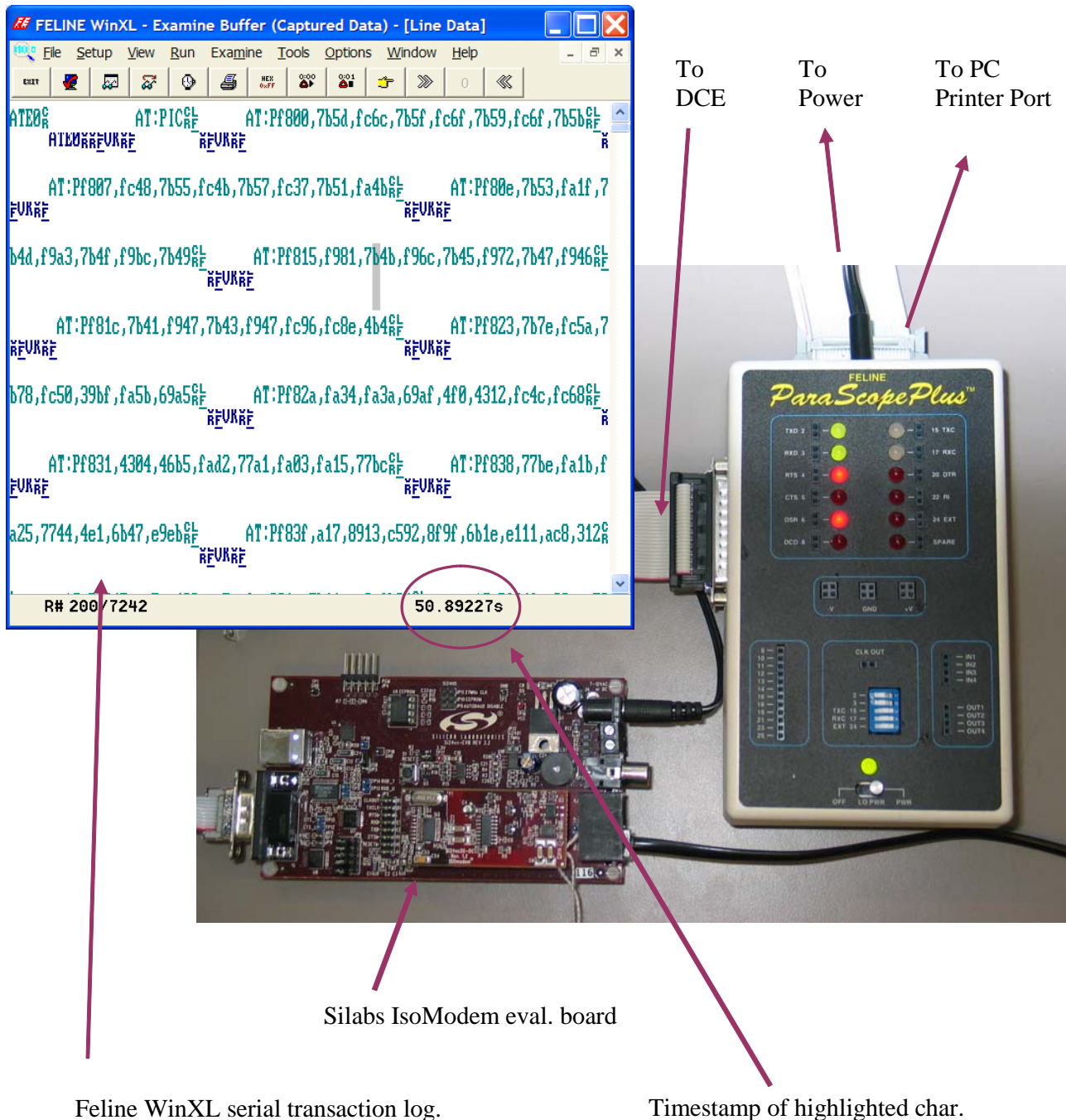
Figure 50. Debugging the DTE Interface

APPENDIX A—EPOS APPLICATIONS

EPOS applications generally require nearly flawless call connection reliability and a very short overall transaction time. The message length of a typical EPOS terminal is between 120 to 260 bytes of information. Due to the relatively small message length, the need for reliable connections under all line conditions, and short connection times, the preferred modulations have traditionally been variations of V.22 (1200 bps) or Bell 212 (1200 bps). EPOS servers do not strictly follow ITU standards. Despite the informal use of the term "V.22 fast connect", there is no ITU "fast connect" standard. De-facto standards with modifications of ITU standards, such as V.22 Fast Connect, have been adopted to reduce the transaction time. Some server manufacturers make changes to the modem with the intent of making it difficult for competing terminals to connect. Many EPOS servers have out-of-specification clocks and use reduced handshake timing. V.22bis (2400 bps) is occasionally used in EPOS terminals as well. The primary method by which V.22bis terminals achieve a shorter connection time has been through the use of a shorter answer tone. V.29 FastPOS is a Hypercom proprietary protocol based on the V.29 Fax standard. For these reasons, EPOS applications often require some amount of reverse engineering and fine tuning of the ISOmodem performance, typically with a patch.

Recently, improvements to the overall user experience have necessitated the storage of transaction information within the EPOS terminal based on some predefined criteria. These stored transactions are typically sent as part of a larger transaction at a later time. This effectively increases the message length to over 2 kB, necessitating the use of higher-speed modulations, such as V.29 FastPOS or V.32bis.

The choice of either V.29 FastPOS versus V.32bis is a tradeoff between transaction message length and connection times. It is common for a terminal to support both of these modulations.

Modulation	Typical Connect Time (Sec)*
V.90	25
V.34	10.7
V.32b	7.8
V.22b	5.0
V.22	3.0
V.22 FastConnect	0.6
V.29 FastPOS	0.5

*Note: Does not include dial delay.

VISA II (7E1)

Terminal		Host
Dials host	⟶	
	⟵	ENQ (0x05)
STX <data>ETX, LRC	⟶	
	⟵	ACK (0x06)
	⟵	STX <data>ETX, LRC
ACK (0x06)	⟶	
	⟵	EOT (0x04)
Disconnects	⟶	
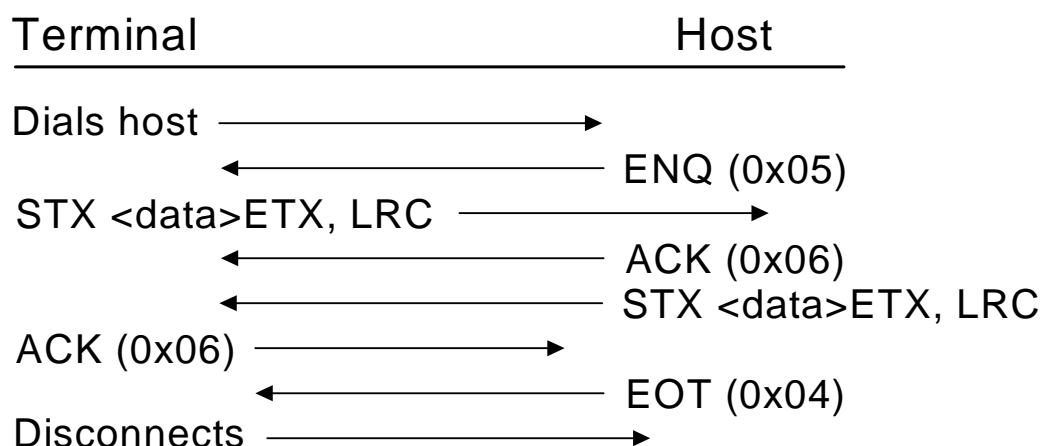
Another consideration for EPOS applications is the method of error detection and error correction. Early EPOS terminals adopted the Zilog 85C30 Serial Communications Controller (SCC) in conjunction with a synchronous modem to implement an HDLC/SDLC-based data link layer. The complexities of the HDLC handling is done by the SCC, while the modem performs strict data pump function. However, given the broad availability of UARTs, HDLC handling can be performed by the modem also. To facilitate this system partitioning, the V.80 protocol is used. V.80 allows the multiplexing of data, control, and status information so that the host processor can specifically control what frames are sent to, or received from, the modem across the asynchronous UART (DTE) interface. The host performs much of the other layers of the protocol stack beyond this Data Link Layer. A discussion of host software is beyond the scope of this appendix.

Recommendation V.80

The goal of V.80 is the concept of "abstracting hardware circuits". This is achieved by the addition of a control and status channel alongside the main data channel. The main data channel is effectively the information transfer across the UART TX and RX lines. The control/status channel that runs alongside the main data channel is signaled by the use of *EM shielding*. This means a "special character" is chosen to signify the beginning of the control/status channel. In its simplest form, this "special character," in conjunction with the "next" character, is taken together as a single nugget of information denoting a special control message or a special status.

V.80 uses <0x19> as a special control character. The next question becomes how to send the character 0x19 as data? This is accommodated by the concept of *transparency*, in which the host is required to send a special sequence to signify its desire to send 0x19 as data rather than a control character.

The concept could have been very simple, but there are additional complications:

- The desire to support 7-bit data and 1-bit parity asynchronous protocols
- The desire to support XON and XOFF handshaking
- The desire to limit bandwidth usage

The desire to support 7 data bits and 1 parity bit creates the possibility that the host would be sending <0x99> when the intention is to be sending the <0x19> special character. The <EM> character is really a shortcut for saying <0x19> or <0x99>.

The XON and XOFF characters are <0x11> and <0x13>, respectively. These characters are treated in a special way by many UARTs, and, therefore, V.80 must ensure that *neither* <0x11> or <0x13> occur in the data stream so that a lower protocol layer will not need to be rewritten. Hence, the final "special character set" for V.80 includes <0x19>, <0x99>, <0x11>, and <0x13>.

What happens if the data file being sent is a constant stream of <0x19> bytes? By the single-transparency rules, one would then argue that the number of bytes sent across the DTE would effectively be doubled. In order to ensure that the throughput does not become bloated by the EM Shielding, provisions for all combinations of two special character combinations are created. This adds yet another sixteen EM Shielding cases since there are 4 x 4 matrix of combinations of these special characters.

At this point, the transparency cases for EM Shielding can thus guarantee the ability to send "anything" over the DTE with the special considerations of 7 vs 8 data bits, XON and XOFF characters and throughput considerations. However, once the data channel has been architected, the rest of the unused EM codes can be used for the primary purpose of V.80, which is the concept of *hardware abstraction*.

In EPOS applications, there is little value in abstracting pins such as $\overline{RI}$ or $\overline{RTS}$. The value comes in abstracting the TXCLK and RXCLK of the Synchronous UART. The Synchronous UART is the primary method of connecting to the Zilog 85C30 SCC. V.80 allows the interface between the host and the modem to be a simple asynchronous DTE, while allowing for synchronous operation performed by the modem itself.

The purpose of going through this explanation is to allow the easier reading of the V.80 standard and to provide the proper framing of the use of V.80 in an EPOS application. It is important to note that the *usage* of V.80 for HDLC function does *not* use many of the other aspects of V.80.

For example, the data transferred across the UART is assumed to be 8 bits, even though V.80 also provides the ability to transfer 7-bit ASCII data. Also, it is rare for XON/XOFF handshaking to be used in an EPOS application, but the transparency rules of EM Shielding are burdened with these extra EM codes in any case.

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In the end, the only thing that matters in an EPOS application is the ability to send and receive HDLC frames across the DTE. For this, the ability of the host to tell the modem "end of transmit frame" and the ability for the modem to tell the host "CRC successful" is, in essence, the kernel of V.80 use in an EPOS application.

One final note before showing an example… the V.80 standard refers to a "Transparent Sub-Mode" and a "Framed Sub-Mode". The main idea behind the Transparent Sub-Mode is to allow the host to specifically decide what bits are being sent across the DCE. In the Transparent Sub-Mode, nothing is left out, and the host is responsible for every single bit that is transmitted to and from the modem. In the Framed Sub-mode, the HDLC handling is performed by the modem, and, therefore, there are actions taken by the modem that the host assumes and does not worry about. In EPOS applications, only the "Framed Sub-Mode" is of importance.

Example:sending an HDLC Frame containing the following bytes:

```
0xFF 0x11
```

The host will transmit the following byte stream. Note that the 0x11 is sent as an <EM><t3> or 0x19 0xA0. An <EM><flag> or 0x19 0xB1 denotes the end of frame.

```
0xFF 0x19 0xA0 0x19 0xB1
```

At the UART interface at TXD, the bit-representation is:

```
strt  0xFF    stp stp   0x19    stp strt  0xA0    stp strt   0x19    stp strt   0xB1
 1    0   11111111 1    0   10001001 1    0    00000101 1    0    10001001 1    0    10001101
```

The modem strips off the start and stop bits and reconstructs the original bytes:

```
0xFF 0x19 0xA0 0x19 0xB1
```

The transparency characters are resolved, and, since the <EM><flag> is present, the Frame Check Sequence is calculated. Let us assume that the FCS is 0xC00F:

```
        16-bit FCS
0xFF 0x11 0xC0 0x0F
```

Adding the HDLC flags and zero-stuffing, the bit stream is shown as follows. The bit stream containing the 0xFF and 0x0F bytes have inserted zero bits. The algorithm is fairly simple in that whenever there are five ones in a row, a bit is inserted. The inserted bits are shown in red. This bit stream is then modulated and transmitted out to the DCE.

```
                              16-bit FCS
  Flag      0xFF      0x11      0xC0      0x0F      Flag
01111110 111110111 10001000 00000011 111010000 01111110
```

The receive process reverses the above steps. The receiver hunts for HDLC flags and synchronizes to the HDLC flag stream. It then extracts the frame between the HDLC Flags and performs zero-bit deletion on the payload. The receiver also calculates the CRC and matches with the 16-bit FCS of the frame. Then, the <EM> transparency is added, and finally, the <EM><flag> is sent as an indication that the calculated CRC of the frame matches the FCS.
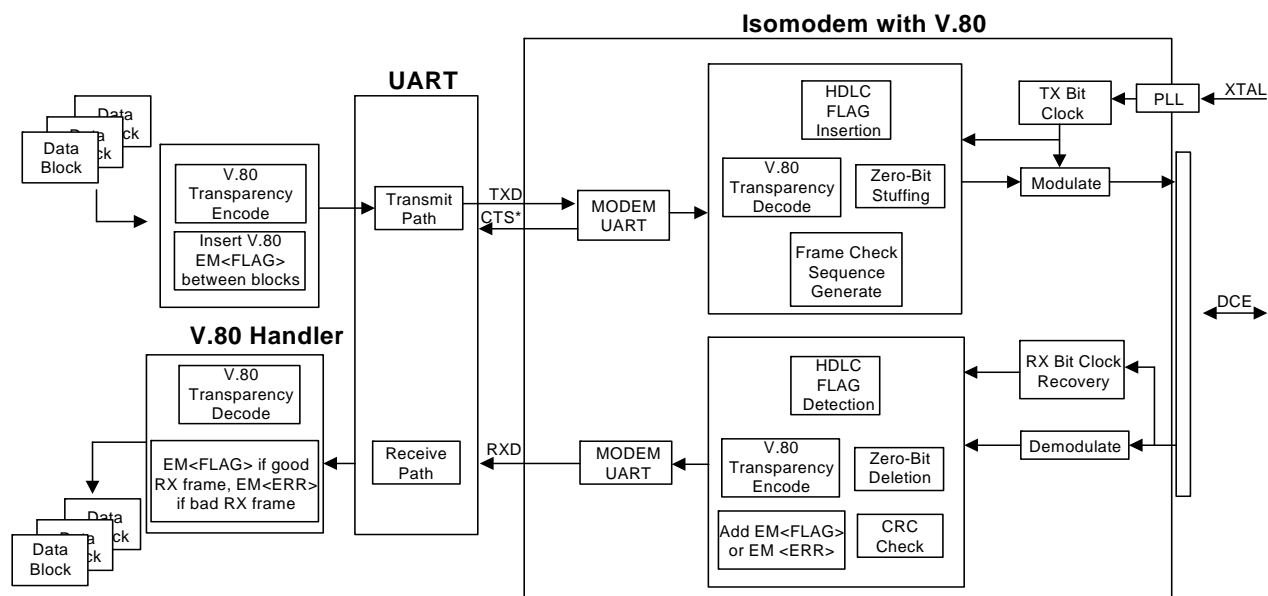
Figure 51. ISOmodem V.80 Protocol HDLC Framing in Framed Sub-Mode

The ISOmodem in EPOS Applications

- The Rev D Si2493/57/34/15/04 and Rev A Si2494/39 include all Rev B and C patches.
- AT:U87 [10] must be set when using Rev B silicon.
- A V.80 interface to V.29 Fast Connect is not supported on Rev B silicon and can be accomplished only as a patch on Rev C. Please contact Silicon Laboratories, Inc. for latest patch. "5.8. Firmware Upgrades" on page 121 outlines how to use this patch.
- When operating as V.22 Fast Connect (+MS=V22, AT:U7A,3), the register U80 can be modified to account for unusual server timings. The value in U80 should reflect the expected answer tone duration of the NAC. The units are in 1/600 s. For example, if the answer tone duration of the server is 500 ms, AT:U80,012C.
- When operating as V.22 Fast Connect (+MS=V22, AT:U7A,3), a short answer tone of at least 300 ms is required for proper operation. This answer tone can be 2100 Hz, 2225 Hz, or a V.22 Unscrambled Binary Ones (USB1). If the server NAC does not have any of these answer tones prior to scrambled data or HDLC flags, it is possible to command the modem to operate without these tones by setting bit 15 of U80. The modem then begins transmitting scrambled data (or HDLC Flags) some time after the end of dialing, based on the value in U80 [14:0]. The units are in 1/600 s. For example, to command the modem to begin transmitting 3 s after the end of dialing, set AT:U80,8708.

A V.29 FastPOS Sample Program

Introduction

In previous versions of the interface to V.29 FastPOS, the HDLC layer was assumed to be implemented by the host software. Another issue was the case where the EPOS Terminal was calling a server that could answer either as V.29 FastPOS or V.22bis; it was not possible for the modem to "train down" to V.22bis.

To address these issues, a new interface has been implemented in the Rev D Si2493/57/34/15 and Rev A Si2494/39 and is available as a patch in the RevC ISOmodem. This interface allows the call to start as a V.29 FastPOS and can train down to V.22bis if the server NAC can answer as either a V.29 FastPOS or V.22bis. Please contact Silicon Laboratories, Inc. for the latest patch.

One of the improved aspects of this interface technique is to use two control lines: ($\overline{\text{RTS}}$ and $\overline{\text{DTR}}$); $\overline{\text{RTS}}$ controls direction of transfer, while the $\overline{\text{DTR}}$ hangs up the line. The tradeoff here is that $\overline{\text{RTS}}$ can no longer be used as a method of stopping the modem from sending data to the host.

This is generally not an issue as long as the DTE rate is greater than the DCE rate and the host can keep up with the receiver without having to resort to the negation of $\overline{\text{RTS}}$.

The data are in V.80 format. Just read and write data while toggling $\overline{\text{RTS}}$ as needed. Assert $\overline{\text{RTS}}$ to transmit and de-assert to receive. This is called a push-to-talk paradigm.

The description here shows how to set up and use the modem for V.29 FastPOS and also provides a sample program along with both a DTE trace and WAV files that capture what is happening at both ends of the modem. The only critical signals that are not recorded below but obviously controlled in the program are the $\overline{\text{RTS}}$ and $\overline{\text{DTR}}$ lines.

The hardware used was the Engineering Eval. Board Rev 3.2 and a 24xx2G-DC Rev 1.2 module containing a 24 pin 2457 Rev C ISOmodem chip plus a 3018 DAA chip. JP6 was strapped {1-2, 4-5, 7-8, 10-11, 13-14}. JP5 was unstrapped.

Setup procedure:

1. Host DTE Rate must be greater than 19200.
2. Host DTE must be configured for 8N1 CTS-only flow control
3. Load Patch "rc_p71_bcd8.txt"

   AT+GCI=xxxxxxx

   AT&D2   Enables escape pin (U70 HES bit needs to be set also.)

   AT+IFC=0,2   Flow control setup

   AT:U87,050A   V.80 Setup

   AT\N0   Wire Mode

   AT+FCLASS=1

   AT:U7A,1

   AT:UAA,8004

   AT+ES=6,,8   Synch access mode

   AT+ESA=0,0,0,,1   Synch access mode control
4. Make Sure $\overline{\text{RTS}}$ is negated (voltage high)
5. Make Sure $\overline{\text{DTR}}$ is asserted (voltage low)
6. Send ATDT###

Notes:
1. Patch is "Originate Only"
2. $\overline{\text{RTS}}$ is used as DIRECTION of transfer. Think "push-to-talk" paradigm. Assert $\overline{\text{RTS}}$ PRIOR to transmission. Negate $\overline{\text{RTS}}$ after frame has been sent. The modem will guarantee that the carrier is turned off after all current frames have been completed.

3. $\overline{\text{DTR}}$ is assumed to be connected to the ESC pin of the modem. It has been programmed to HANG UP when $\overline{\text{DTR}}$ is negated.

4. When the modem is in RECEIVE operation ($\overline{\text{RTS}}$ negated), it is not possible to communicate with the modem. The only control is to hang up using $\overline{\text{DTR}}$.

5. The modem "automatically" takes care of figuring out if it is supposed to be in "V.29 Long Train" vs. "V.29 Short Train". The primary host responsibility is to take care of $\overline{\text{RTS}}$.

6. Data to/from the modem is expected to be in V.80 format.

Example Program in C/C++

This program shows how to establish an SDLC V.29 FastPOS link and keep the loop alive.

How to use the program:

This program is meant to run for only a few minutes for testing. It is run after a reset is done, loads a patch from "patch.txt" and calls using the atdt line it finds in "tel_no.txt". Both files need to terminate in CR LF.

The tel_no.txt file must contain a complete telephone number dialing line followed by a CR, e.g. ATDT8,5551212.

```
// V29_test.cpp : Defines the entry point for the console application.
// Copyright 2005 Silicon Labs Inc. All rights reserved.
// Rev 0.0602


#include "stdafx.h"
#include "windows.h"
#include "stdlib.h"
#include <stdio.h>
#include <time.h>


char    fnamePatch[]=".\\patch.txt";
char    fnameTelno[]=".\\Tel_no.txt";
char            *SendAndWaitFor(char *cpCommand, char *cpInBuffRd,
                                char *cpResponse, int iTimeoutMs);
char            *WaitForResponse(char *cpResponse, char *cpInputBuffer,
                                int iTimeOutInMs);
void            SetupSerPort(void);
void            AssertRTS(bool bAssert);
void            AssertDTR(bool bAssert);
void            Delay(long iMs) ;
bool            GetFileTextLine(char *cpIn);
void            LoadAndSendPatch(void);

char            *cpInBuffer;
char            *cpOutBuffer;
char            *cpInputWr;
char            *cpErrorString;


FILE            *hpPatchFile;
FILE            *hpTelNoFile;


DCB             dcb;
HANDLE          hCom;
char            *pcCommPort = "COM1";
COMMTIMEOUTS    sCOMMTIMEOUTS;
int             iCharCount;
char            *cpInputRd, *cpInputRd_temp, cpInput_test[255];
```

```
char          caUA_PKT_STR[] = {(char)0x30, (char)0x73, (char)0x19, (char)0xb1, (char)0 };
char caRR_PKT_STR[] = {(char)0x30, (char)0x19, (char)0xa0, (char)0x19, (char)0xb1, (char)0 };
char caSNRM_PKT_STR[] = {(char)0x30, (char)0x93, (char)0x19, (char)0xb1, (char)0 };
char caRX_PKT_STR[]    = {(char)0x19, (char)0xb1, (char)0 };


void AlternateCall(void);

int main(int argc, char* argv[])
{
   // Initialize these buffers.
cpInBuffer  = (char *)malloc(100000);
   cpOutBuffer = (char *)malloc(100000);
   cpErrorString = (char *)malloc(100000);

   for (int i= 0; i< 10000; i++)
     {
     cpInBuffer[i]   = 0;
      cpOutBuffer[i]  = 0;
      cpErrorString[i] = 0;
      }

   cpInputRd = cpInBuffer;
   cpInputWr = cpInBuffer;


   unsigned long  ulNoOfbytes;

   SetupSerPort();

   LoadAndSendPatch();
   AssertDTR(true);// Leave DTR asserted for calling

   cpInputRd = SendAndWaitFor("atz\r", cpInputRd, "OK\r\n", 300); // A soft reset Just in case
 Delay(300); //  Important, AN93 implies this delay must be done after an ATZ.
   cpInputRd  = SendAndWaitFor("ATE0\r", cpInputRd, "OK\r\n", 300);
   cpInputRd_temp = SendAndWaitFor("AT&T6\r", cpInputRd, "OK\r\n", 300);// Get the patch CRC
   printf ("%s \n", cpInputRd); cpInputRd=cpInputRd_temp;               // Display the patch CRC

// setup county of operation   ********************MODIFY to your locality******************
//   cpInputRd = SendAndWaitFor("at+gci=B5\r", cpInputRd, "OK\r\n", 300);

   // &D2 enables escape pin,    // X4  enable extended result codes
   // \V2 report connect message only  // %c0 disable data compression
   // %V1 Auto line status detection mode is the fixed method
   // +IFC=0,2  No data flow control, Hardware flow control
   cpInputRd = SendAndWaitFor("AT&D2x4\\V2%c0%V1+IFC=0,2\r", cpInputRd, "OK\r\n", 300);
   // \N0            wire mode,   // +FCLASS=1      HDLC mumbo jumbo
   cpInputRd = SendAndWaitFor("AT\\N0+FCLASS=1\r", cpInputRd, "OK\r\n", 300);
   cpInputRd = SendAndWaitFor("AT:UAA,8004\r", cpInputRd, "OK\r\n", 300);

   // +ES=6,,8    enabled synch access, //  6,, enables synch access on initiating a connect
```

```
    // ,,8        enables synch access on answering a connect
    cpInputRd = SendAndWaitFor("AT+ES=6,,8\r", cpInputRd, "OK\r\n", 300);


    // AT+ESA=0,0,0,,1  synch access mode control
    // 0,,,,   modem transmits SYN if underrun during transparent mode
    // ,0...   modem tx's flags after underrun after flag happens in framed sub mode
    // ,,0,,   modem tx's abort on underrun in frame middle during framed sub mode
    // ,,,,1   enables CRC generation and checking
    cpInputRd = SendAndWaitFor("AT+ESA=0,0,0,,1\r", cpInputRd, "OK\r\n", 300);


    // "AT:U87,010A  Synch access mode config
    // 0x0400 bit 10    Minimal transparency <EM><T1 thru T4> during Rx
    // 0x0100 bit 8     Upon connection immediately enter framed sub mode
    // 0x000A bits 3:0  Wait for 10 bytes before starting xmission.
    cpInputRd = SendAndWaitFor("AT:U87,050A\r", cpInputRd, "OK\r\n", 300);


    // :U7A,1  Fast connect
    cpInputRd = SendAndWaitFor("AT:U7A,1\r", cpInputRd, "OK\r\n", 300);


    AssertRTS(false);

  if ((hpTelNoFile = fopen(fnameTelno, "rb")) == NULL)
    {
      fprintf(stderr, "The Tel. Number File is missing.\n");
      exit(1);
      }


    char caOutGoing[256];
    bool bValidLine = GetFileTextLine(caOutGoing);

    printf("Phone Number: %s\n",caOutGoing);

    if(bValidLine)
       cpInputRd  = SendAndWaitFor(caOutGoing, cpInputRd, "CONNECT\r\n", 120000);

    else
       {
       fprintf(stderr, "The Tel. Number File is incorrect.\n");
       exit(1);
       }

    int iLength;
    iCharCount = 0;   //reset the total chars to 0 for data mode.

//  Skip waiting for the speed packet.
//  cpInputRd = WaitForResponse("\0x19\0xbe\0x24\0x24\0x19\0xb1", cpInputRd, 6000);  // ???

    // Long training happens now!

    cpInputRd = WaitForResponse(caSNRM_PKT_STR, cpInputRd, 6000);
    Delay(50);                              //Delay to allow the line to turn around
```

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```
    AssertRTS(true); //RTS=1 for transmitting
    Delay(300); //Delay to allow the line to turn around
                                                  //  Alternatively use USE CTS
    iLength = strlen(caUA_PKT_STR);
    WriteFile(hCom, caUA_PKT_STR, iLength, &ulNoOfbytes, 0);  // Tx UA messge
    Delay(100);

    while(1)   // Short training happens now!
       {
       AssertRTS(false);  printf("RTS=0 Rx ");                 //RTS=0 for receiving
        cpInputRd=WaitForResponse(caRX_PKT_STR,cpInputRd,3000);//Rx RR message
       iLength = strlen(cpInput_test);
       for (int i=0; i<iLength; i++)
          printf("%02x ", (unsigned char)cpInput_test[i]);printf("**%d  ", *cpInputRd);
       //Alternatively use CTS
       Delay(150);

       do{  // flush out the bytes for last RX packets.
         BOOL bError = !ReadFile(hCom,  cpInputWr, 1, &ulNoOfbytes, 0); //ulNoOfbytes=1
         printf("%02x ", (unsigned char)cpInputWr[0]);
       }while (ulNoOfbytes); printf("\n");

       AssertRTS(true); printf("RTS=1 Tx ");                   //RTS=1 for transmitting
       Delay(50); // morrie 01/20/06
       iLength = strlen(caRR_PKT_STR);
       for (i=0; i<iLength; i++)printf("%02x ", (unsigned char)caRR_PKT_STR[i]); printf("\n");
       WriteFile(hCom, caRR_PKT_STR, iLength, &ulNoOfbytes,0); //Tx RR message
       Delay(100); //Delay x ms to complete TX sending before set RTS=0 for RX
       }
    return;

}

// -------------------------------------------------------------------------------------

// Use this call to check CTS status
// DWORD iEVentMAsk;        // wait for EV_CTS
// BOOL WaitCommEvent(HANDLE hFile, &iEVentMAsk, LPOVERLAPPED lpOverlapped);

// -----------------------------------------------------------------

void SetupSerPort()
{
    BOOL     bSuccess;
    hCom = CreateFile(pcCommPort,  GENERIC_READ | GENERIC_WRITE, 0,
                   NULL, OPEN_EXISTING, 0, NULL);
    if (hCom == INVALID_HANDLE_VALUE)
       {                             // Handle the error.
        printf ("CreateFile failed with error %d.\n", GetLastError());
        exit(1);
```

```
        }

    // Build on the current configuration, and skip setting the size
    // of the input and output buffers with SetupComm.

    bSuccess = GetCommState(hCom, &dcb);
    if (!bSuccess)
        {
        // Handle the error.
        printf ("GetCommState failed with error %d.\n", GetLastError());
        exit(1);
        }
    // Fill in DCB: 57,600 bps, 8 data bits, no parity, and 1 stop bit.
dcb.fBinary          = TRUE;                     // Binary mode; no EOF check
dcb.fOutxCtsFlow     = FALSE;                    // No CTS output flow control
dcb.fOutxDsrFlow     = FALSE;                    // No DSR output flow control
dcb.fDtrControl      = DTR_CONTROL_ENABLE;       // DTR flow control type
dcb.fDsrSensitivity  = FALSE;                    // DSR sensitivity
dcb.fTXContinueOnXoff= TRUE;                     // XOFF continues Tx
dcb.fOutX            = FALSE;                    // No XON/XOFF out flow control
dcb.fInX             = FALSE;                    // No XON/XOFF in flow control
dcb.fErrorChar       = FALSE;                    // Disable error replacement
dcb.fNull            = FALSE;                    // Disable null stripping
dcb.fRtsControl      = RTS_CONTROL_ENABLE;       // assert RTS
dcb.fAbortOnError    = FALSE;                    // Do not abort rds/wr on error
  dcb.BaudRate  = CBR_115200;                      // set the baud rate
  dcb.ByteSize  = 8;                               // data size, xmit, and rcv
  dcb.Parity    = NOPARITY;                        // no parity bit
  dcb.StopBits  = ONESTOPBIT;                      // one stop bit

  bSuccess = SetCommState(hCom, &dcb);
  if (!bSuccess)
      {                       // Handle the error.
      printf ("SetCommState failed with error %d.\n", GetLastError());
      exit(1);
      }
  printf ("Serial port %s successfully initialized.\n", pcCommPort);
  return;
 }


// ------------------------------------------------------------------------------

char *SendAndWaitFor(char *cpCommand, char *cpInBuffRd,
                            char *cpResponse, int iTimeoutMs)
{
   unsigned long ulNoOfbytes;
   strcpy(cpOutBuffer, cpCommand);
   WriteFile(hCom, (long *)cpOutBuffer, strlen((char *)cpOutBuffer),
                            &ulNoOfbytes, 0);
   if(iTimeoutMs)
```

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```
        cpInBuffRd = WaitForResponse(cpResponse, cpInBuffRd, iTimeoutMs);
    if(!cpInBuffRd)
        exit(0);
    return cpInBuffRd;
}


// Check for a specific response in the input buffer, and return ptr to what
// follows. If this times out or ERRORs before the response is found then a
// NULL is returned; It keeps reading the ser channel while waiting

char *WaitForResponse(char *cpResponse, char *cpInputBuffer, int iTimeOutInMs)
{
    unsigned long ulNoOfbytes;
    clock_t        sStartTime   = clock();
    clock_t        sCurrentTime;
    // covert wait time in ms's to clock_t by mutiplying by CLOCKS_PER_SEC/1000
    clock_t        sWaitTime = (clock_t)(iTimeOutInMs*CLOCKS_PER_SEC)/1000;
    int iPasses  = 0;
    int iCharCnt =0;          // set to 0
    while(1)
       {
        char cTemp = *cpInputWr;
       *cpInputWr = 0;
       char *cpFound = strstr(cpInputBuffer, cpResponse);
       *cpInputWr = cTemp;
       if(cpFound)
{//copy the received bytes for late display
           strncpy(cpInput_test, cpInputBuffer, iCharCnt);cpInput_test[iCharCnt]='\0';
           return cpFound + strlen(cpResponse);
       }

       // Setup a 50 ms timeout for reads
       sCOMMTIMEOUTS.ReadIntervalTimeout         = 0;
       sCOMMTIMEOUTS.ReadTotalTimeoutMultiplier  = 0;
       sCOMMTIMEOUTS.ReadTotalTimeoutConstant    = 50;
       sCOMMTIMEOUTS.WriteTotalTimeoutMultiplier = 0;
       sCOMMTIMEOUTS.WriteTotalTimeoutConstant   = 0;
       SetCommTimeouts(hCom,   &sCOMMTIMEOUTS);

       // Read the serial port
//cpInputWr has char from the port
       BOOL bError = !ReadFile(hCom,  cpInputWr, 1, &ulNoOfbytes, 0);
       iCharCount += ulNoOfbytes;   iCharCnt+=ulNoOfbytes;

       if(bError)
          {
          strcat(cpErrorString, "Read Error\r\n");
          exit(10); // implement a write to file before exit(0)
          }
       cpInputWr += ulNoOfbytes;
       // check for a timeout
```

```
        sCurrentTime = clock();
        iPasses++;

        if( sCurrentTime > (sStartTime + sWaitTime) )
            {
            strcat(cpErrorString, "Timeout of ");  strcat(cpErrorString, cpResponse);
            printf ("\n%s\n", cpErrorString);
            strncpy(cpInput_test, cpInputBuffer, iCharCnt);
            cpInput_test[iCharCnt]='\0'; //copy the received bytes for late display
            return cpInputBuffer;    // we exit with the same input string we came in with
                                     // because we time out.


            }


        }
};

// ----------------------------------------------------------------------

void AssertRTS(bool bAssert)
{
    BOOL     bSuccess;
    if(bAssert)
        dcb.fRtsControl      = RTS_CONTROL_ENABLE;      // assert RTS
    else
        dcb.fRtsControl      = RTS_CONTROL_DISABLE;      // dis-assert RTS
    bSuccess = SetCommState(hCom, &dcb);
    if (!bSuccess)
        {       // Handle the error.
        printf ("SetCommState failed with error %d.\n", GetLastError());
        exit(1);
        }
    else
        return;
}



void AssertDTR(bool bAssert)
{
    BOOL     bSuccess;
    if(bAssert)
        dcb.fDtrControl      = RTS_CONTROL_ENABLE;      // assert RTS
    else
        dcb.fDtrControl      = RTS_CONTROL_DISABLE;      // dis-assert RTS
    bSuccess = SetCommState(hCom, &dcb);
    if (!bSuccess)
        {       // Handle the error.
        printf ("SetCommState failed with error %d.\n", GetLastError());
        exit(1);
        }
```

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```
    return;
}


void Delay(long iMs)
{
    clock_t wait;
    // covert ms's to clock_t by mutiplying by CLOCKS_PER_SEC/1000
    wait = (clock_t)(iMs*CLOCKS_PER_SEC)/1000;
    clock_t goal;
    goal = wait + clock();
    while( goal > clock() )
        ;
}




void LoadAndSendPatch(void)
{
    char  caOutGoing[256];
    cpInputRd_temp = SendAndWaitFor("AT&T7\r", cpInputRd, "OK\r\n", 300); // Reset the modem
    printf ("Current %s \n", cpInputRd); cpInputRd=cpInputRd_temp;
    printf ("Loading patch:%s...\n", fnamePatch);
    if ((hpPatchFile = fopen(fnamePatch, "rb")) == NULL)
        {
        fprintf(stderr, "The Patch File is missing.\n");
        exit(1);
        }
    AssertRTS(true );
    cpInputRd=SendAndWaitFor("ATE1\r", cpInputRd, "OK\r\n", 300);
    bool bValidLine = true;
    while(bValidLine)
        {
        bValidLine = GetFileTextLine(caOutGoing);
        if(bValidLine)
            cpInputRd      = SendAndWaitFor(caOutGoing, cpInputRd, "OK\r\n", 3000);

        }
    cpInputRd  = SendAndWaitFor("ATE1\r", cpInputRd, "OK\r\n", 300);
    cpInputRd_temp = SendAndWaitFor("AT&T6\r", cpInputRd, "OK\r\n", 300);
    printf ("Finish Loading, %s \n", cpInputRd); cpInputRd=cpInputRd_temp;
    fclose(hpPatchFile);
}

// Returns FALSE when at end of file
// Stops after first LF.

bool GetFileTextLine(char *cpIn)
{
    *cpIn = 0;   char cpInChar[8]; cpInChar[1] = 0;
    while(!feof(hpPatchFile))
```

```
    {
    cpInChar[0] =  fgetc(hpPatchFile);
    strcat(cpIn, cpInChar);
    if(*cpInChar == '\n')
        return TRUE;
    }
  return FALSE;
}
```

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V.29 FastPOS Detailed Wave Files

The following is a wave file that shows a V.29 FastPOS SDLC transaction. It was captured with the program listed above with a keep-alive loop. See "Appendix B—Line Audio Recording" on page 273 for details on how to capture wave files.

RTS (not $\overline{RTS}$) signal

V.29 Calling Tone

Answer Tone
(2225 Hz)

Calling modem is receiving
and sends to the DTE:
"Connect Packet" :
<EM><0xBE><0x24><0x24><EM><B1>
Then the SNRM Packet:
<0x30><0x93><EM><0xB1>

DTE sends the calling
modem a UA packet
to transmit:
<0x30>(0x73><EM><0xB1>

Calling modem is receiving.
Sends a Tx abort to DTE:
<EM><0xB2>
Then the received RR packet:
<30><EM><0xA0><EM><B1>

DTE sends the calling modem
an RR packet to transmit:
<30><EM><0xA0><EM><B1>

Repeat

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V.29 FastPOS DTE Trace

This is recorded while the program listed above is running. The patch load is left out for brevity.

```
DCE        CR LF CR LF O   K   CR LF                    a   t   z   CR CR LF O   K   CR LF
DTE                                      a   t   z   CR                                      A   T

DCE                  A   T   E   0   CR CR LF O   K   CR LF                    CR LF C   :
DTE        E   0   CR                                a   t   &   T   6   CR

DCE        b   c   d   8   CR LF CR LF O   K   CR LF                    CR LF O   K   CR LF
DTE                                      A   T   *   y   0   CR

DCE                                      CR LF O   K   CR LF
DTE        a   t   +   g   c   i   =   B   5   CR                    A   T   &   D   2   x   4   \

DCE                                                CR LF O   K   CR LF
DTE        V   2   %   c   0   %   V   1   +   I   F   C   =   0   ,   2   CR                    A

DCE                                                CR LF O   K   CR LF
DTE        T   \   N   0   +   F   C   L   A   S   S   =   1   CR                    A   T   :   U

DCE                                      CR LF O   K   CR LF
DTE        A   A   ,   8   0   0   4   CR                    A   T   +   E   S   =   6   ,   ,   8

DCE          CR LF O   K   CR LF                                                CR
DTE        CR                    A   T   +   E   S   A   =   0   ,   0   ,   0   ,   ,   1   CR

DCE        LF O   K   CR LF                                CR LF O   K   CR LF
DTE                    A   T   :   U   8   7   ,   0   5   0   A   CR                    A

DCE                                      CR LF O   K   CR LF
DTE        T   :   U   7   A   ,   1   CR                    A   T   D   T   8   ,   0   1   1   5

DCE                                                CR LF C   O   N   N   E   C   T   CR LF
DTE        5   1   1   5   8   5   3   2   5   0   7   CR LF

DCE        EM BE $   $   EM B1 0   93 EM B1                EM B2 0   EM A0 EM B1
DTE                                      0   s   EM B1                          0   EM A0

DCE          EM B2 0   EM A0 EM B1                EM B2 0   EM A0 EM B1
DTE        EM B1                          0   EM A0 EM B1                          0   EM A0
```

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APPENDIX B—LINE AUDIO RECORDING

Recording and examining the audio signals on the phone line is one of the best debugging techniques for PSTN modems. Virtually all the relevant signals are in the audio spectrum and are easy to acquire using a standard PC sound card and accessory hardware and software that is especially designed for music creation and analysis.

The required hardware is a Radio Shack Catalog No. 43-228A "Recorder Control". It can be used with any computer equipped with a 3.5 mm audio-input jack.

The resulting wave can usually be recorded in the field using the computer's operating-system resources, but for analysis, a software package capable of showing the spectral contents as they change over time is recommended. The two most widely used ones are Adobe Audition, a commercial product, and WaveSurfer, which is a free open-source product that runs on Windows, Linux, OS X and Unix. This audio-recording technique does not replace sophisticated test equipment, but it is quite useful in showing up some faults in the line and in the modem's (DUT) negotiation with the device on the other side of the phone line.

When to Use Audio Recording

This technique is best used when the modem appears to connect normally against some servers but does not connect well when calling a specific server or modem. This implies the hardware is functional and the issues most likely involve the negotiations between the modems during connect and retrain. One way to rule out the possibility of a hardware problem is to call the server or modem where the connect issue is found using the Silicon Labs EVB module.

Times When Audio Recording May Not Help

Some signals are exceptions and cannot be monitored in this way due to the limits of the bandwidth examined. Examples are the dc voltage and currents that exist during both on- and off-hook conditions, precise details of the pulse dialing waveforms, and most EMI signals. EMI signals, which are not visible during the recordings, may produce in-band demodulated and cross-product signals in the modem.

Some in-band signals cannot easily be monitored this way because they are common-mode signals. While they may be less visible to the recording apparatus, they can be received by the modems in some cases. An example of this is a strong common-mode 50 or 60 Hz hum with its harmonics (a 50 or 60 Hz buzz).

Hardware Setup

The Radio Shack Recorder Control contains a transformer that bridges the phone line with a dc-blocking capacitor, plus a voice-operated switch output that starts and stops a recording device. We only use one of the output connectors since we are not interested in the VOX mechanism. Connect the audio output connector (a 3.5 mm O.D. connector) to the microphone input socket at the back of the computer. The RJ11 connector from the Recorder Control should be connected to the Tip and Ring of the phone line being monitored.
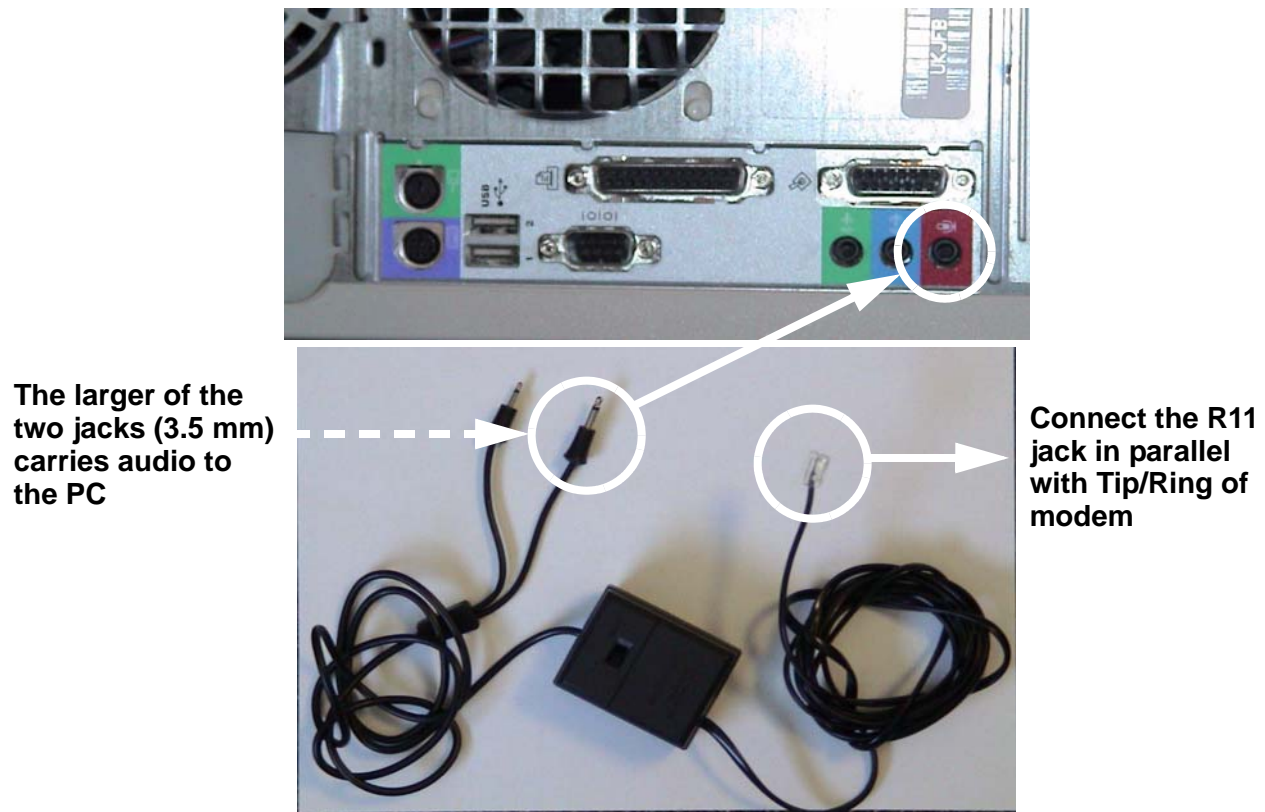
Figure 52. Hardware Setup

The larger of the two jacks (3.5 mm) carries audio to the PC

Connect the R11 jack in parallel with Tip/Ring of modem

Setting PC Microphone Input for Recording (Windows NT)

Use the following procedure:

1. Click Start->Settings->Control Panel->Sounds and Multimedia to open the "Sounds and Multimedia Properties" window.

2. Click Audio Tab; click Volume to open the "Recording Control" window.

3. Select Microphone as input; adjust balance and volume.

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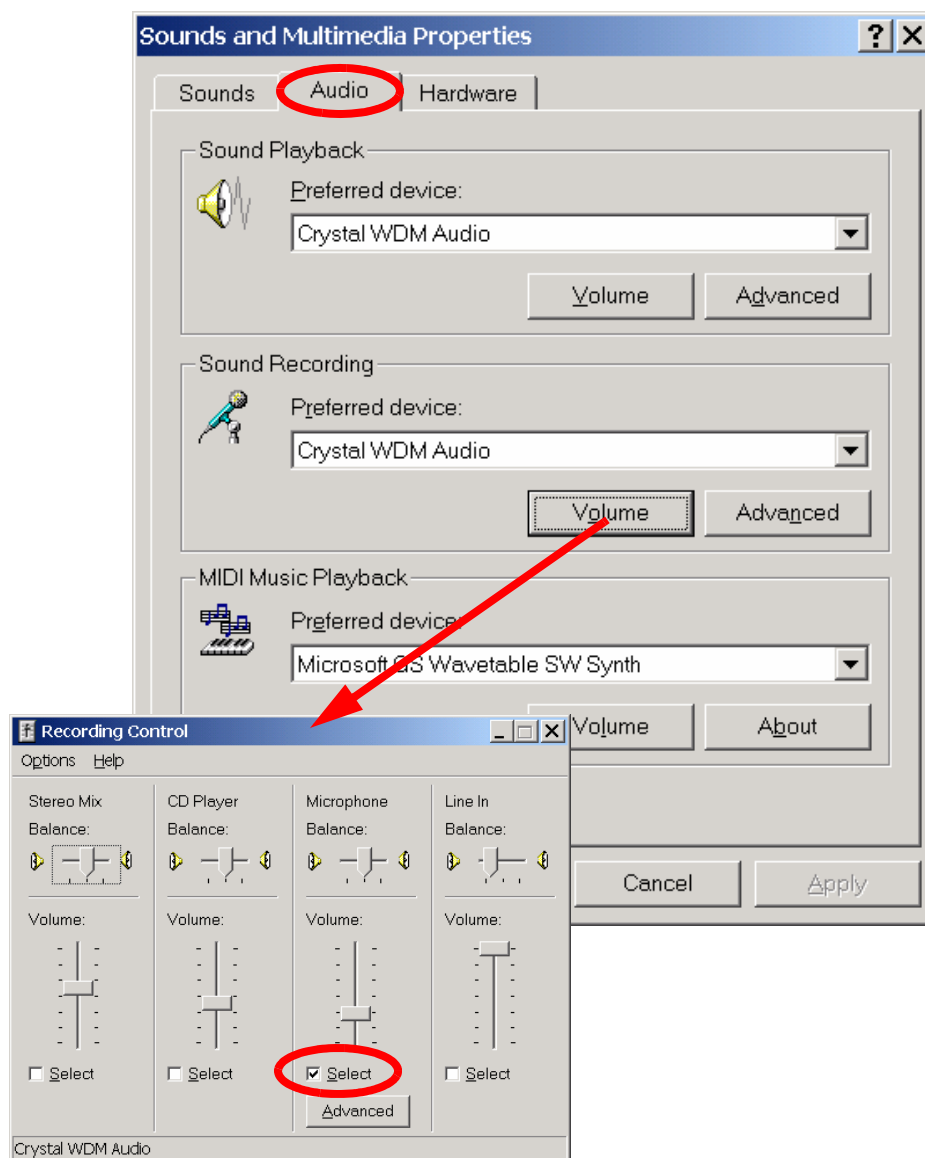
Figure 53. Sounds and Multimedia Properties

Setting PC Microphone Input for Recording (Windows 98)

Use the following procedure:

1. Select Start->Settings->Control Panel->Multimedia Properties to open the Multimedia Properties window.
2. Select the "Audio" tab and then the "Recording" icon to open the Recording Control window.
3. Select Microphone as input, and adjust the balance and volume.
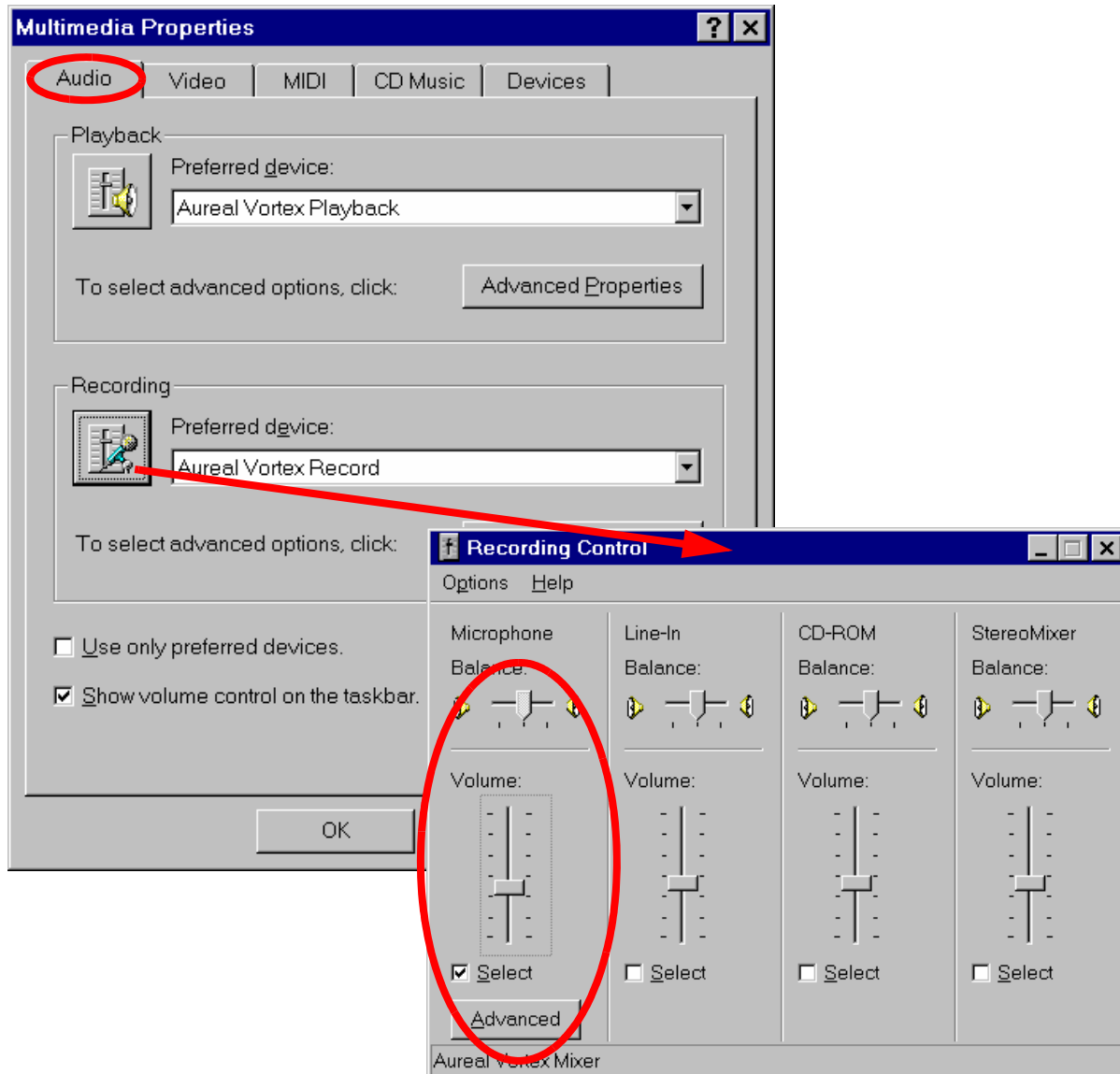
Figure 54. Multimedia Properties

Setting PC Microphone Input for Recording (Windows XP)

Use the following procedure:

1. Select Start->Control Panel->Multimedia Properties to open the Sounds and Audio Devices Properties window.

2. Select the Audio tab and then the Sound Recording volume button to open the Recording Control window.

3. Select Microphone as input, and adjust balance and volume.

4. Select Advanced to open the Advanced Controls for Microphone screen.

5. Deselect the "1 Mic Boost" radio button (Mic. Boost is essentially an AGC mechanism that can spoil the audio recordings.)

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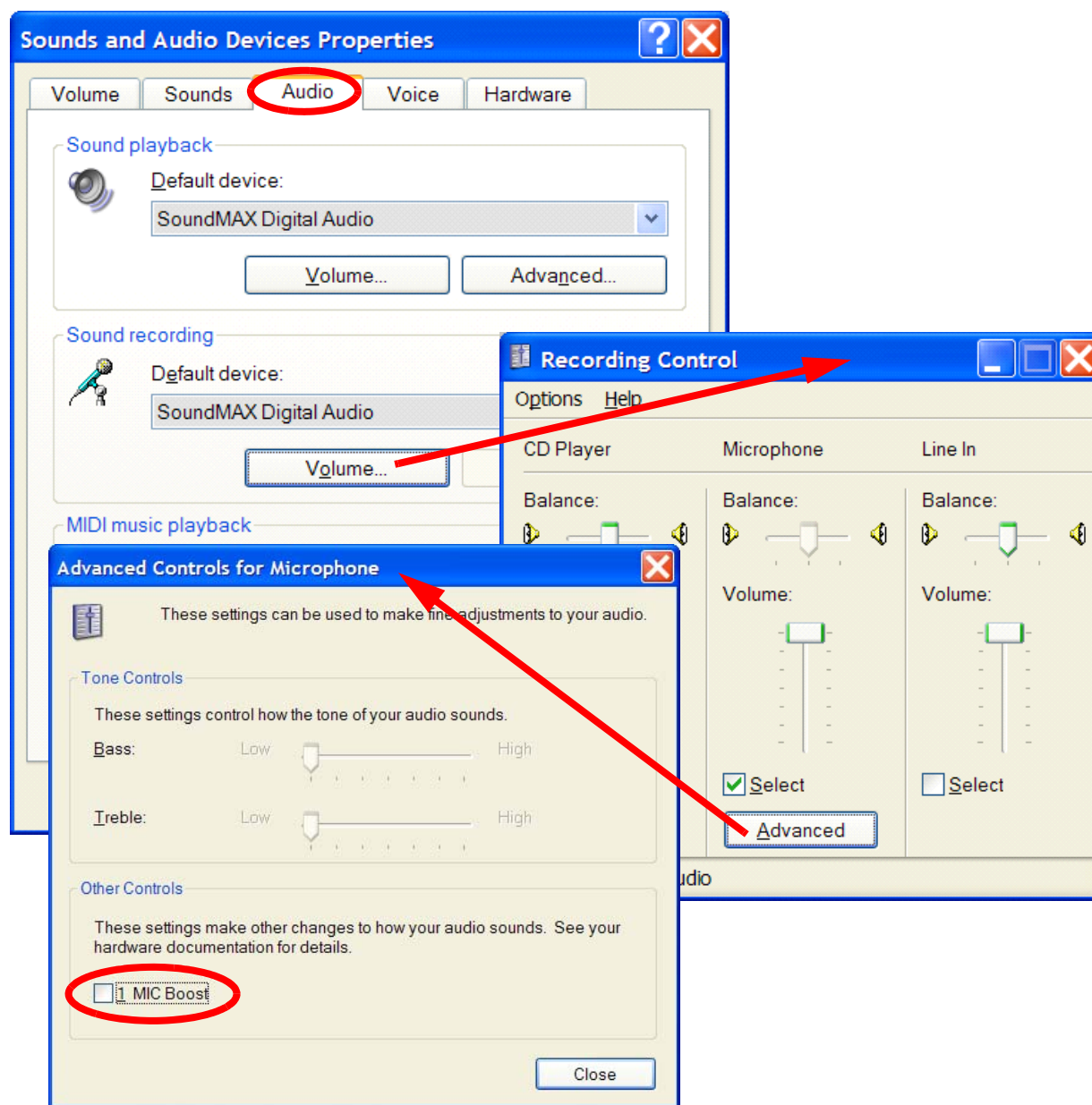
Figure 55. Sounds and Audio Devices Properties

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Making the Recording with Windows Sound Recorder (Windows XP, NT or Windows 98)

Use the following procedure:

1. Click Start->Programs->Accessories->Entertainment->Sound Recorder to open "Sound Recorder" window
2. Select the red record button to start recording, then File->Save when done.

Figure 56. Sound Recorder

Making the Recording with Adobe Audition or WaveSurfer

These applications provide more recording options than the Window Sound Recorder application. They should be set up for monophonic recordings at a sample rate of about 11,000 samples per second in order to save recording space while still retaining reasonable fidelity. The number of bits per word should be 16 bits to allow the full dynamic range available in the sound card. The larger resolution size of 32 bits floating point would be a waste of space and computing power.
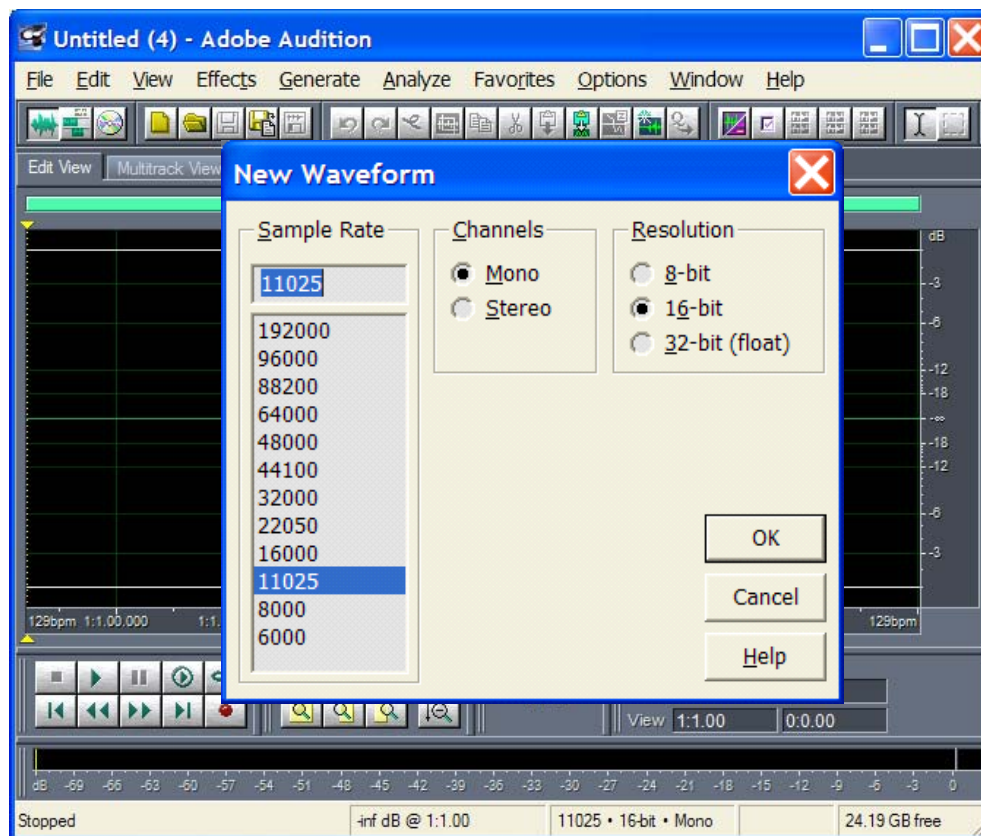
Figure 57. Adobe Audition Example

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Audio Playback and Analysis

Below are two displays showing the results of recording a good V.22 transaction using Adobe Audition. We need to examine the signal both in the time domain and the frequency domain, with the frequency domain being a much more useful view. The graphs below show time on the horizontal axis and either wave energy in dB or Frequency in Hz on the vertical scale. In the frequency display, the color of the wave indicates the energy at that combination of elapsed time and frequency. The color scheme is programmable. It is typical in the temporal view to see a dc offset until one applies a high-pass filter, a step that is rarely necessary.
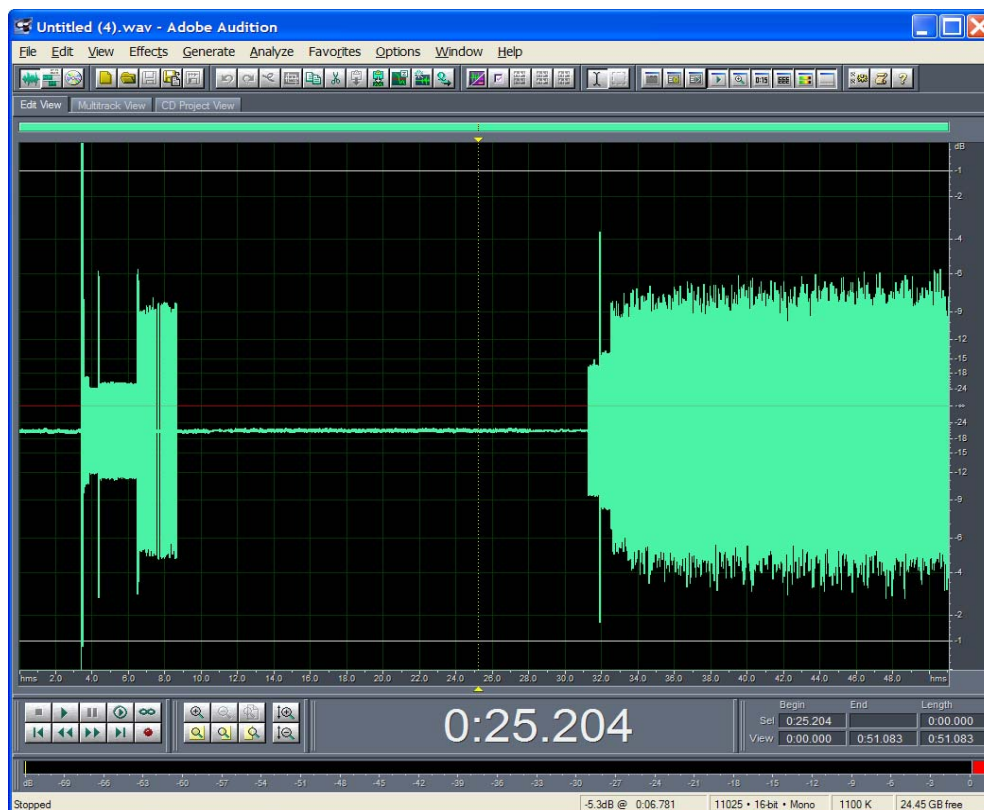
Figure 58. Adobe Audition Temporal View of a Good V.22 Transaction
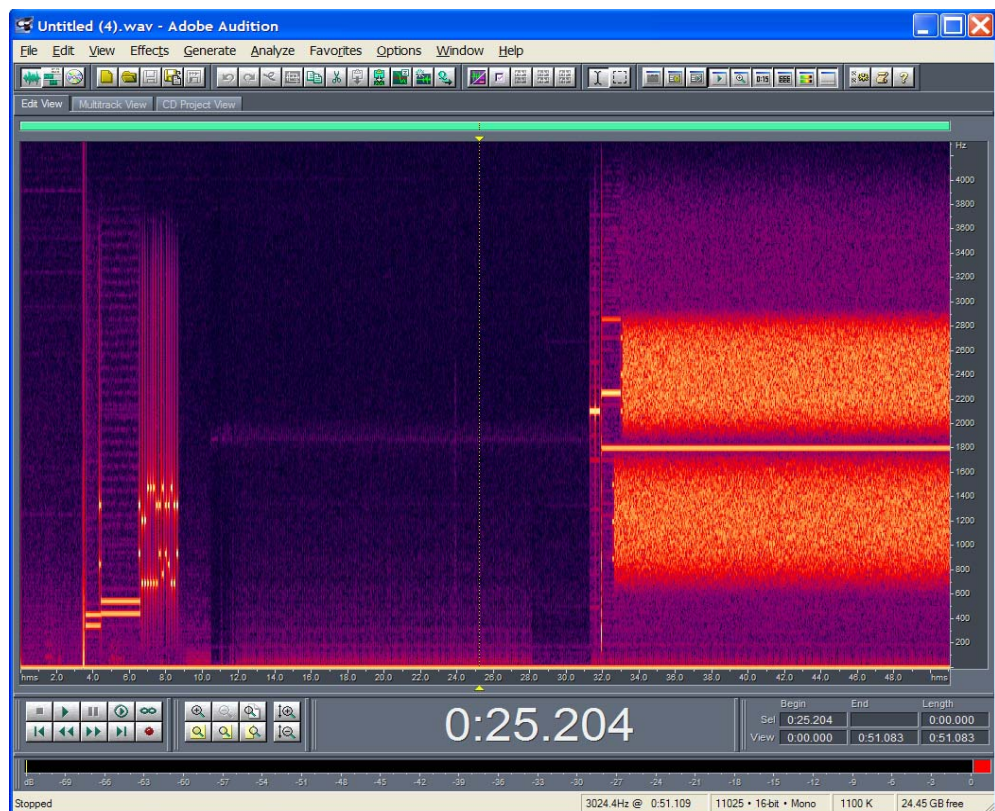
Figure 59. Adobe Audition Spectral View of a Good V.22 Transaction

An important parameter that is not obvious at first glance is the resolution in "bands" of the spectral display. There is a tradeoff that must always be considered. This is set up in the Options->Settings Display tab in the Adobe Audition product. This parameter allows for finer and coarser vertical (frequency) resolution at the cost of time-domain uncertainty. Figures 60 and 61 depict the same wave files but with 256 bands versus 2048 bands. One can see better timing details in one graph compared with the other. The 256-band spectral display shown in Figure 60 shows the fine timing details of the protocol, but with poor frequency resolution. The 2048-band spectral display shown in Figure 61 allows more precise frequency measurements and signal separation, but at the cost of obtaining a coarser time resolution.
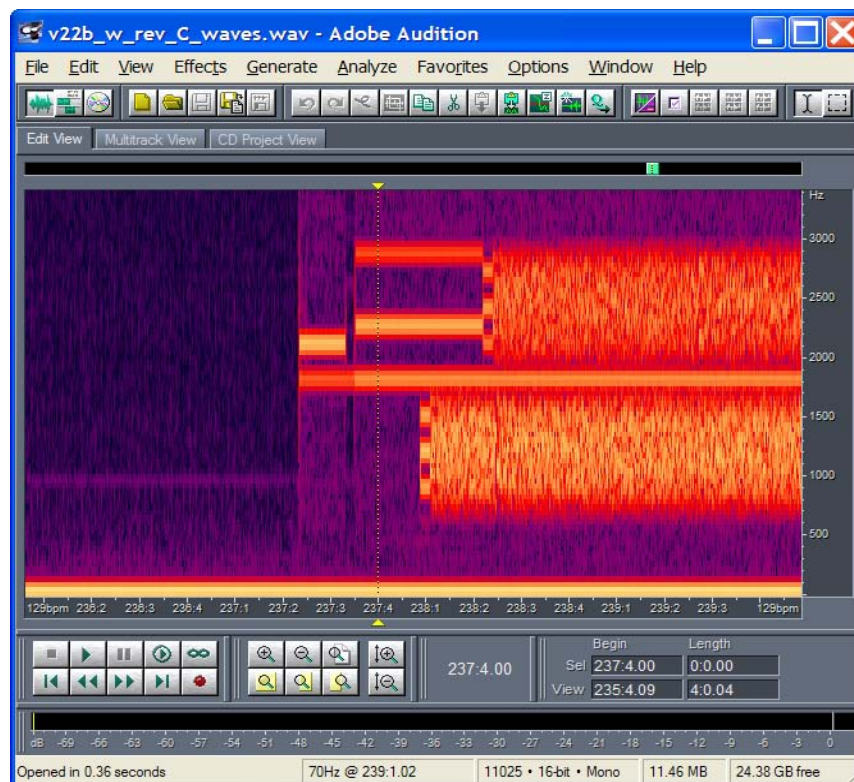
Figure 60. 256 Band Spectral Display
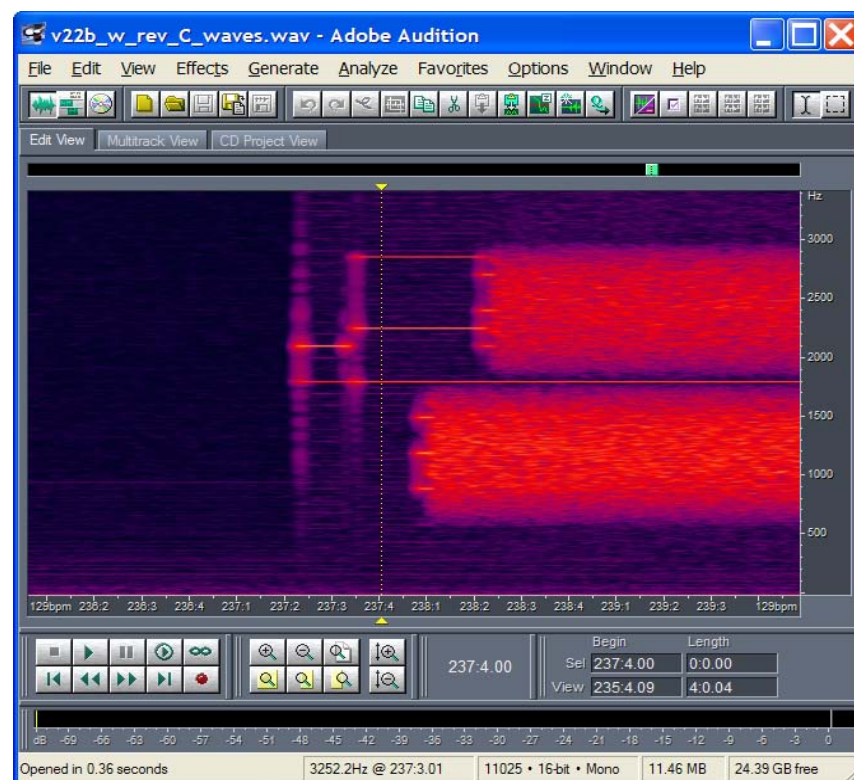
Figure 61. 2048 Band Spectral Display

Audio-Recording Pitfalls

To facilitate communications protocol debugging, it is imperative that audio recordings be made properly. The two most common conditions that degrade the quality of audio recordings are:

- "Waveform clipping due to excessive recording level
- "Time-varying levels due to use of AGC (automatic gain control)
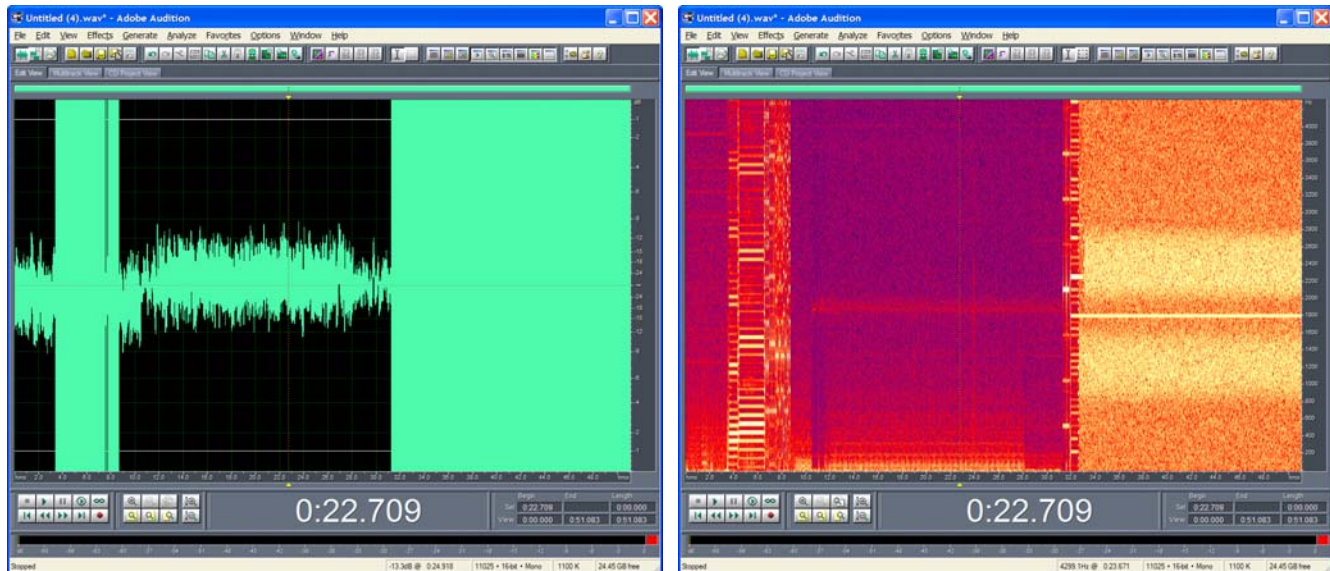
Figure 62. Recording Made at Excessive Level

The above recording was made at an excessively high level. One can see clipping in the time domain and numerous distortion products in the frequency domain.
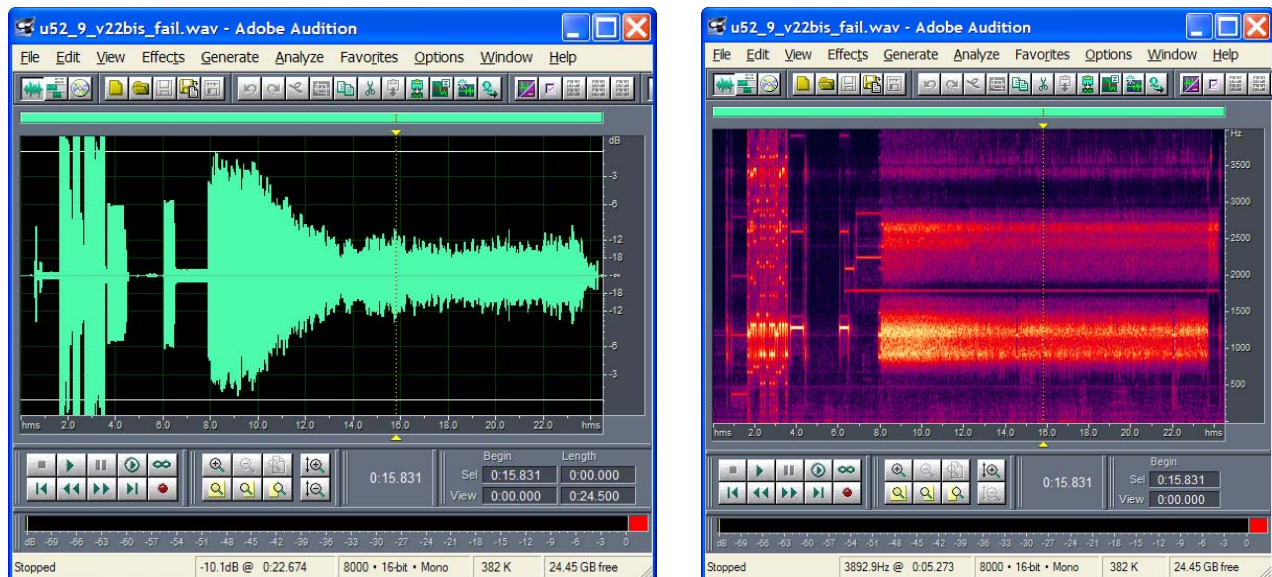
Figure 63. Recording Made with AGC Noise Reduction

The above recording was made with AGC "Noise Reduction" still enabled, as can be seen from the gradual level drop in the time domain graph at the start of V.22 negotiations. It also shows evidence of a microphone being used instead of the Radio Shack adapter. This is visible in the frequency-domain graph as horizontal striations (an undulating frequency response) during the scrambled portion of the V.22 communication. One can also see third-harmonic distortion.

Details of Some Low-Speed Protocols

The following annotated recordings give basic ideas of what to expect the EPOS modem transactions will look like. There are many possible variations of these examples, both in and out of compliance with published standards, in common use. There are also very unusual variations that Silicon Labs has made efforts to support in order to allow customers to connect to non-standard and essentially broken modems. Some of these are described in a later section.
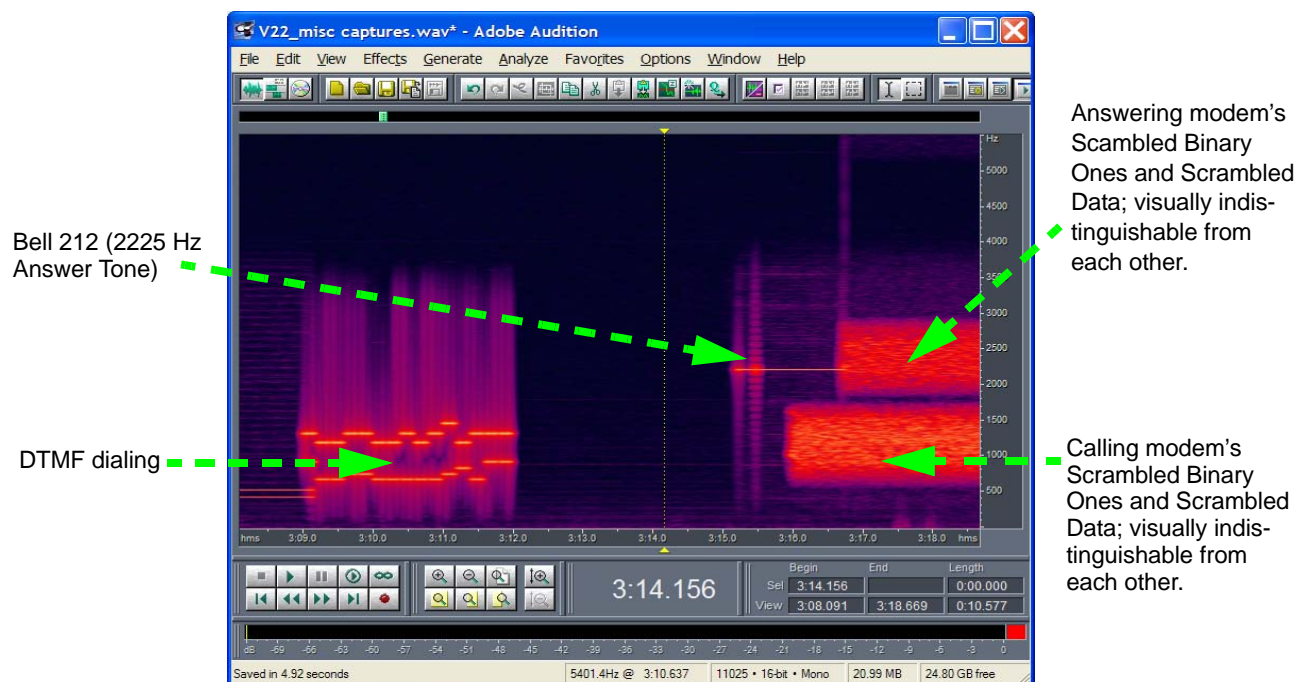
Figure 64. Appearance of Bell 212 Protocol

Figure 65. Appearance of V.22 Protocol
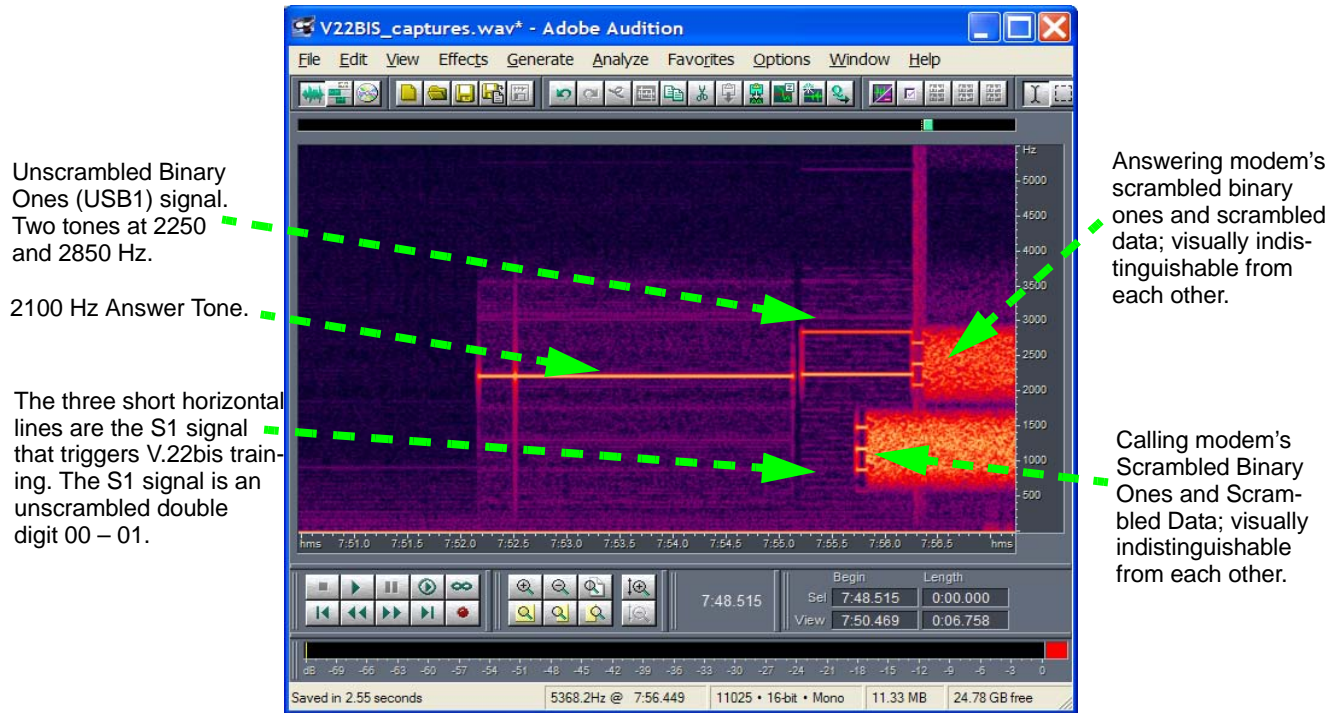
Figure 66. Appearance of V.22 bis Protocol

This looks the same as the V.22 bis protocol above except for S1 signal used for signaling V.22 bis(ness) and for start of retrains.
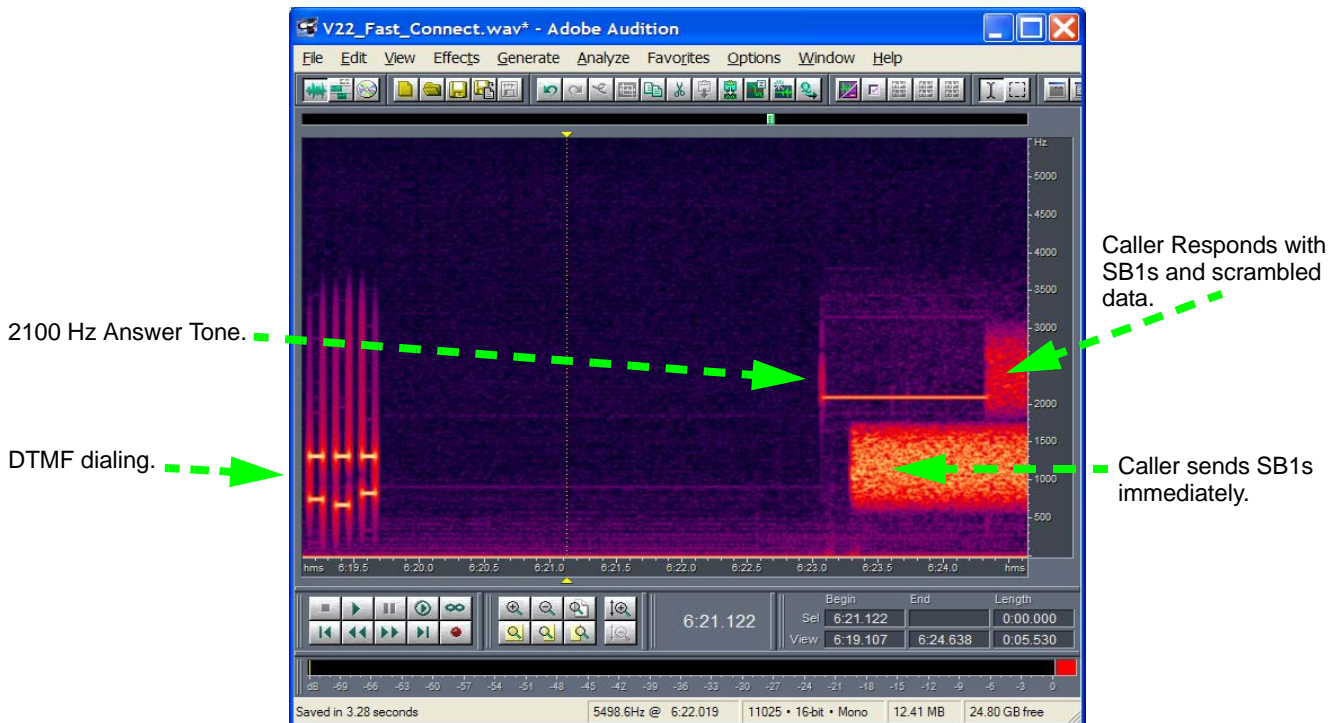
Figure 67. Appearance of V.22 Fast Connect Protocols

AN93

As shown in Figure 68, the V.29 FastPOS protocol looks different than the older, slower V.22-like protocols. It is also half-duplex, and each participating modem uses the entire spectral space available on the telephone line.

A receiving modem recognizes that the calling modem is V.29-capable by detecting the V.29 calling tone at 980 Hz. Another example with some more SDLC-oriented data is provided later in this document.
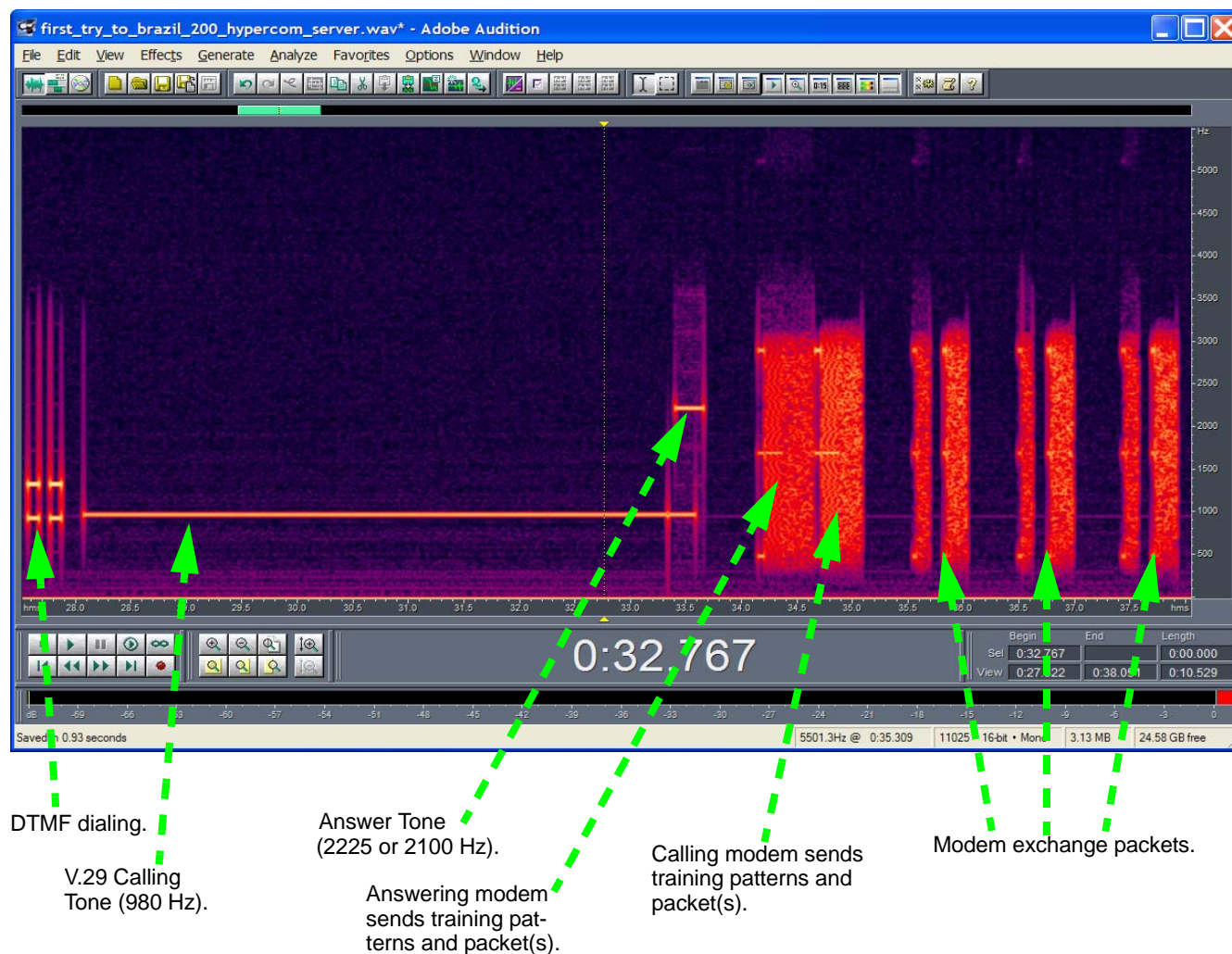
Figure 68. Appearance of V.29 FastPOS Protocol

A V.22 bis server with unpredictable and undesirable gaps during the USB1 signal.
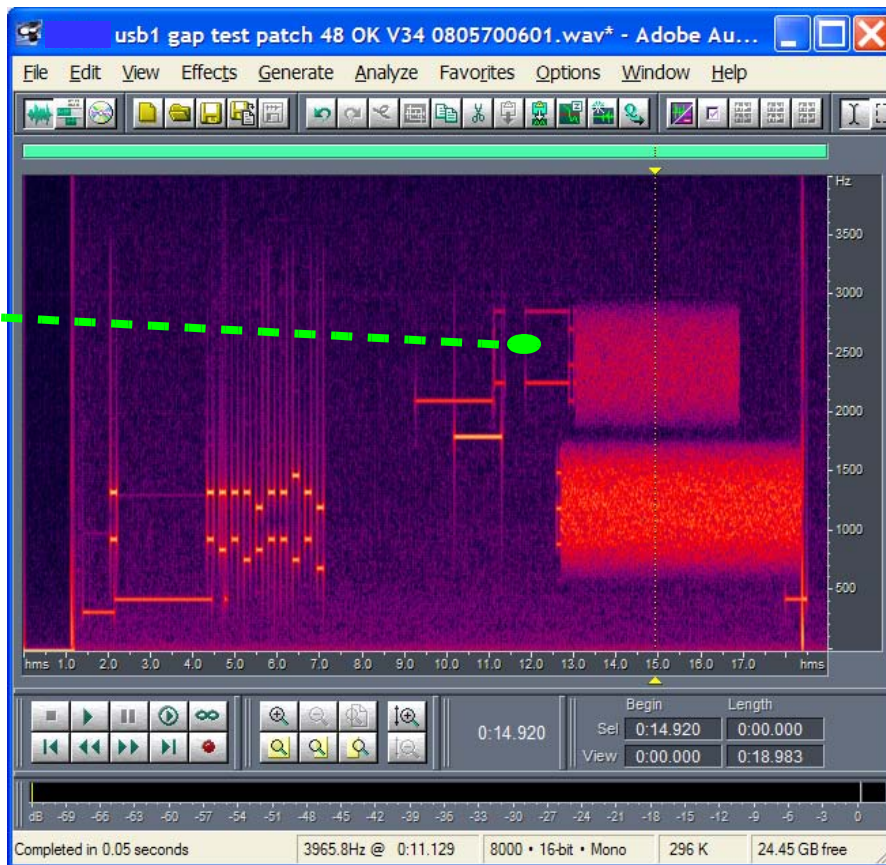
A V.22 bis server with a 2225 answer tone instead of 2100 Hz.
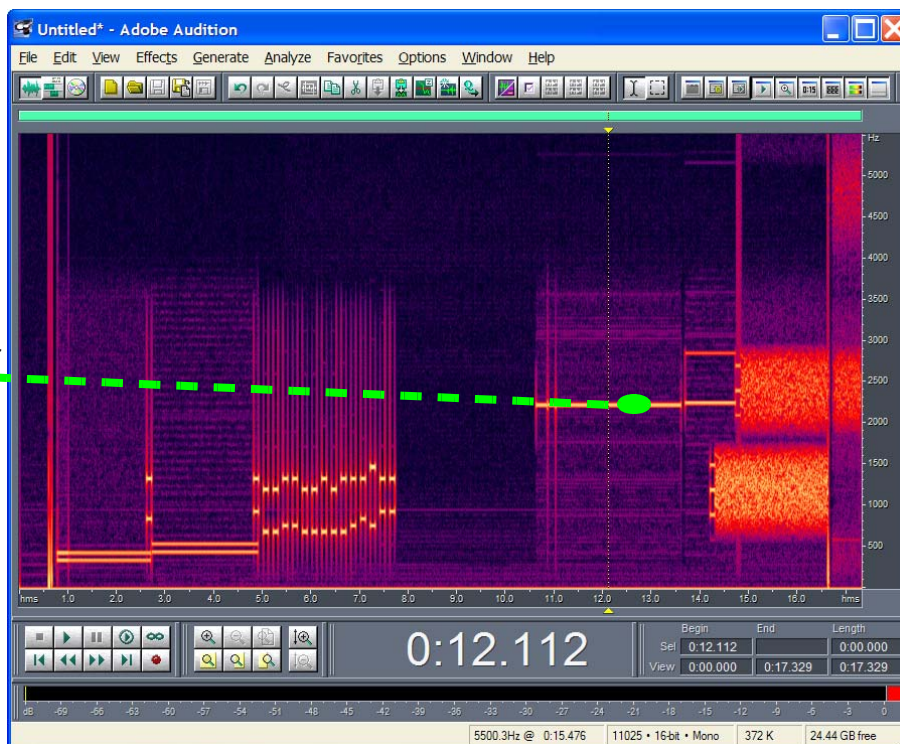
Figure 69. Examples of EPOS Server Misbehavior
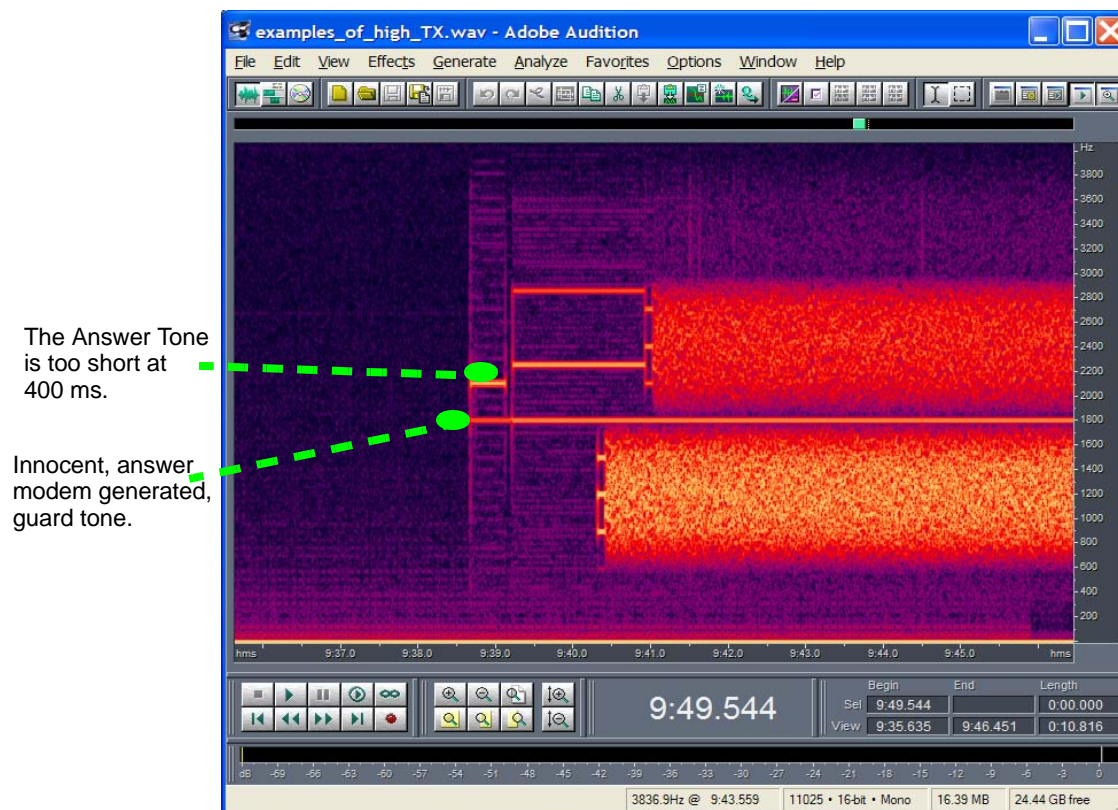
Figure 70. Example of EPOS Server Misbehavior

Examples of Line Impairments

DTMF Distorted by Low Line Level
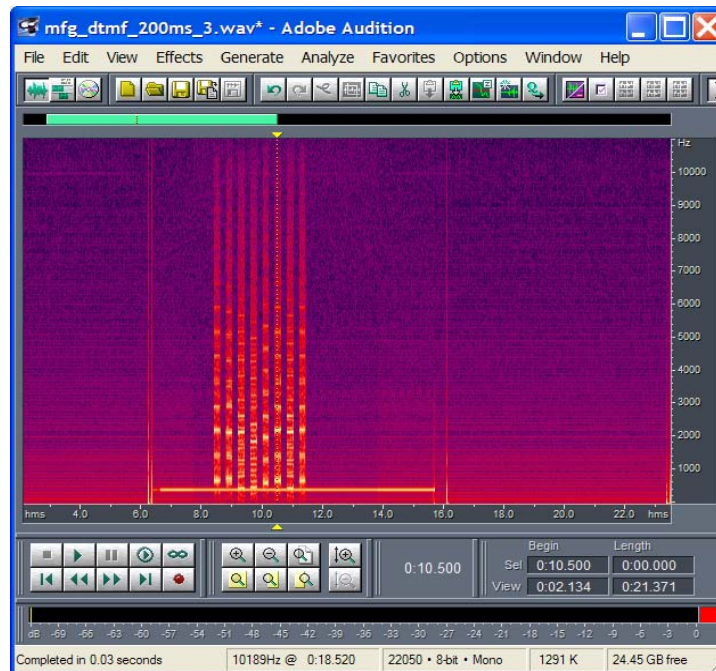
Figure 71. Defective DTMF
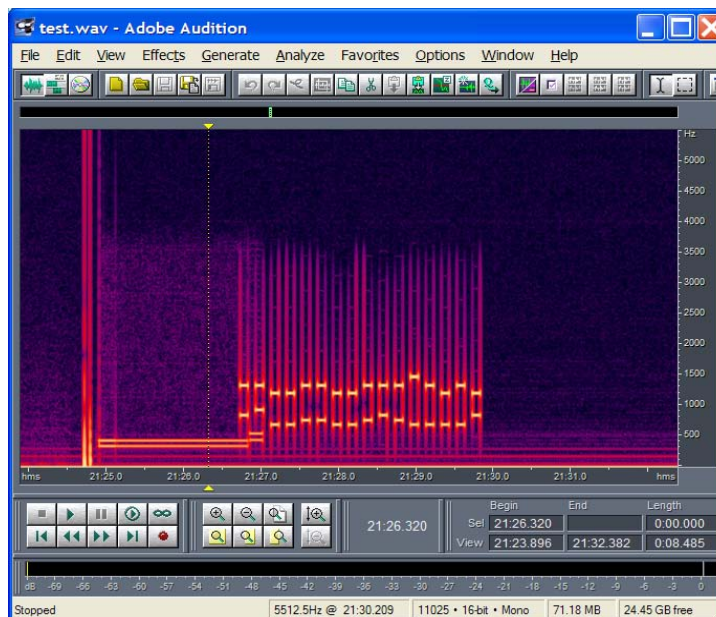
Figure 72. Normal DTMF

Solutions:

- Fix the telephone line.
- Lower the DTMF level with AT:U46, 0BD0 or AT:U46, 0CF0
- Check the loop-current level with AT:R79 and AT:R6C.

Power Line Related Noise
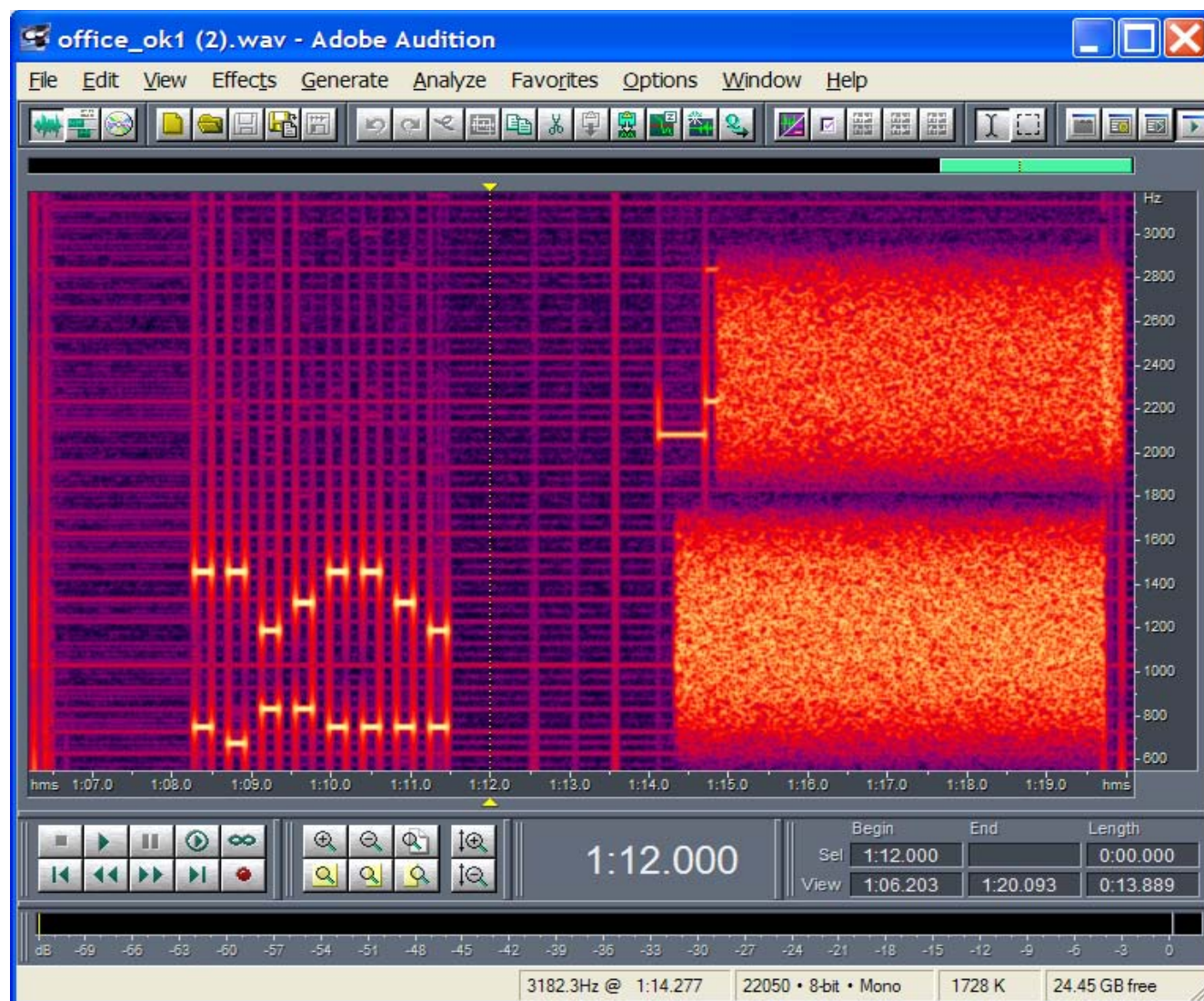
Figure 73. Odd Harmonics of 50 Hz Manifest as Horizontal Lines Spaced at 100 Hz

Causes:

- Unbalanced phone line
- High ac leakage supply
- Poor CMR in modem

Solutions:

- Fix the telephone line.
- Ground the system to earth or float completely using a battery.
- Use an analog supply with lower ac Leakage

APPENDIX C—PARALLEL/SPI INTERFACE SOFTWARE IMPLEMENTATION

This appendix describes the software interface requirements for communication with the ISOmodem in parallel or SPI mode. Sample code was developed to run on the Silicon Labs C8051F12xx platform to allow basic communication between the modem and a PC using the parallel or SPI interface. Figure 74 shows a typical connection between a PC and the modem using the MCU C8051F12xx demo board as interface:
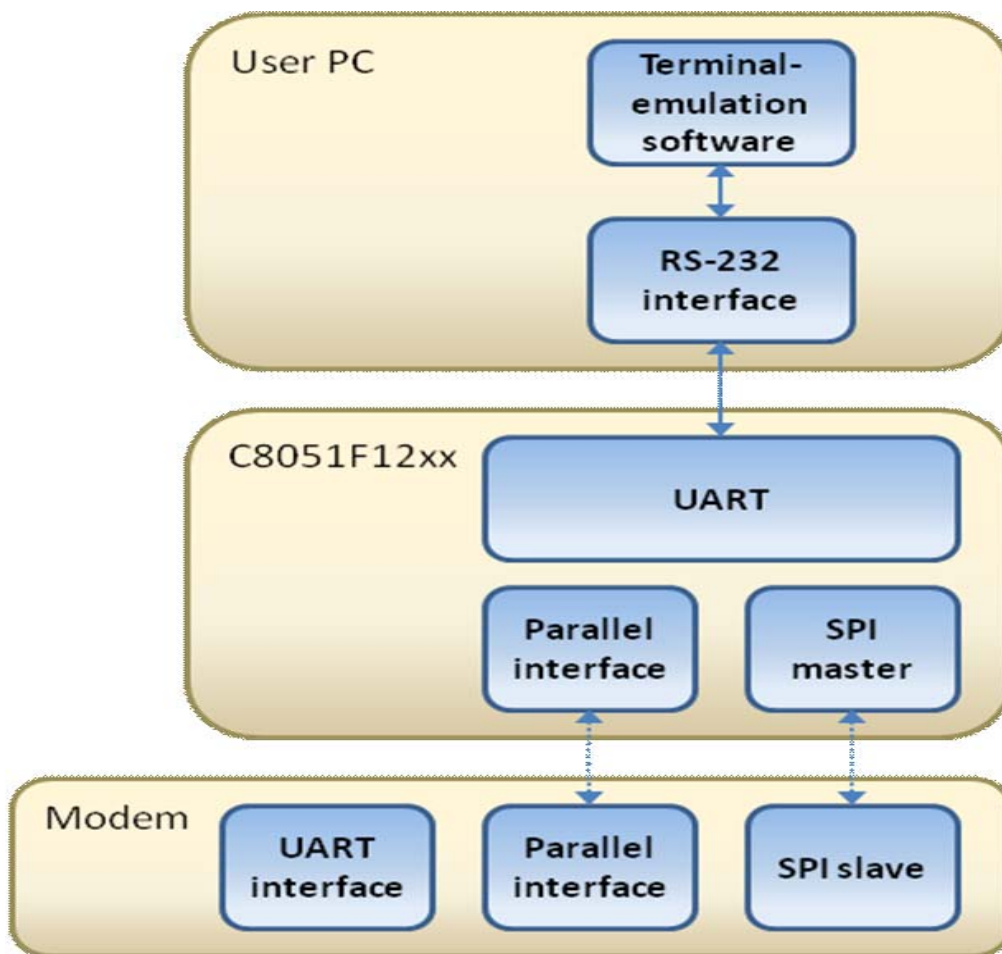
Figure 74. PC to Modem Connection through a C8051F12xx Demo Board

A typical application is structured in four software layers:

1. Hardware access: where the MCU performs all the basic I/O accesses to and from the modem

2. Interrupt service or polling: depending on the mode of access (polling or interrupt), this layer contains the algorithms that determine when the host and the modem exchange data.

3. Data buffer management, status and control: this portion of the code contains the circular buffers that relay data between the UART and the modem in both directions. Access functions are provided for the application to set the software interrupt mask and the escape bit, and to query the status of software interrupts.

4. The application layer: this code depends on the application. An example application `main()` block is provided in this document. An optional diagnostic console-level command set is also available to run on the application layer. This command set is enabled using compiler options in the MCU development environment. Refer to "Compiler Option: Dot Commands" on page 299 for details.

Figure 75 illustrates the MCU software architecture, and the MCU and modem hardware connections.
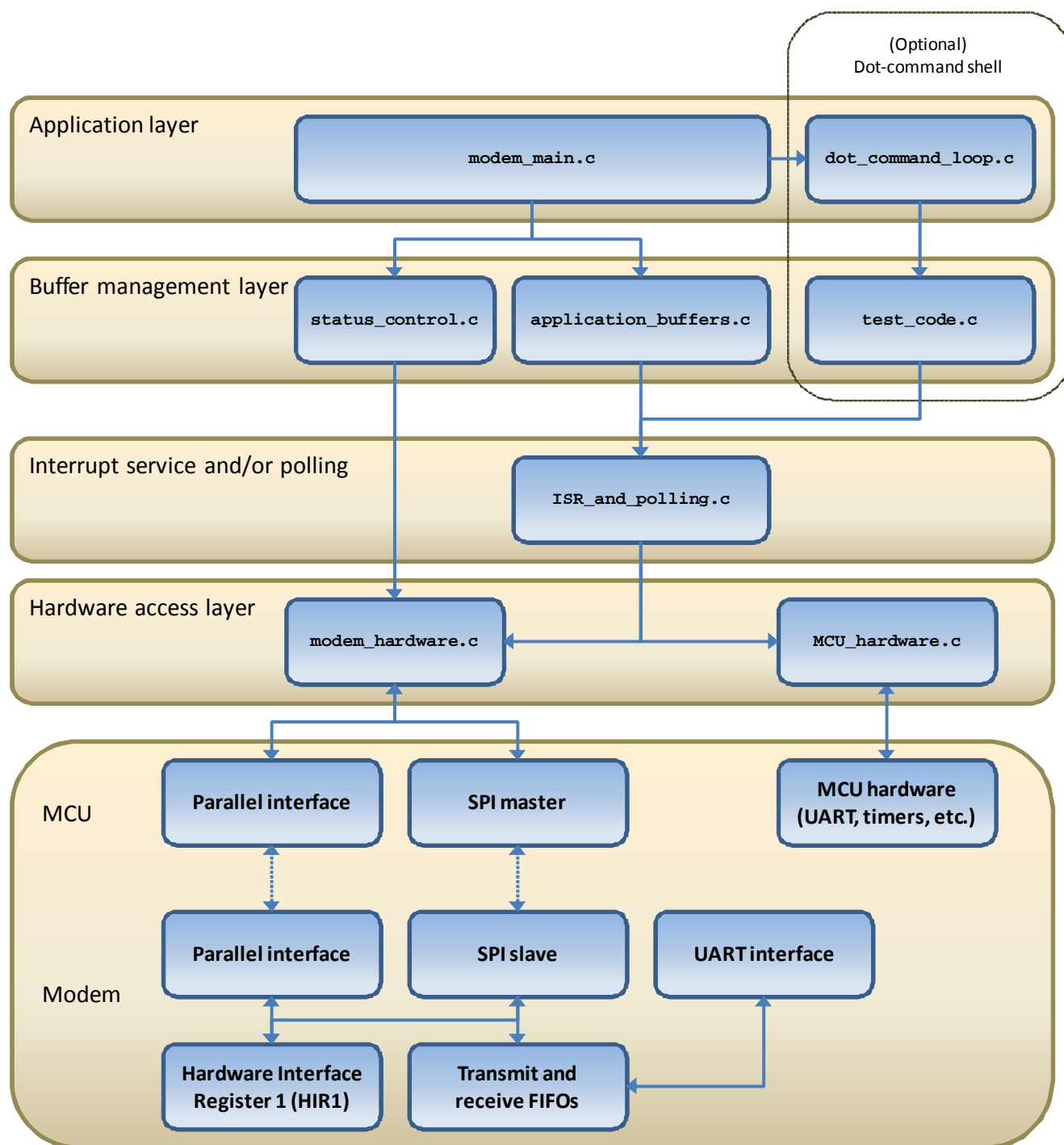

Figure 75. MCU Software and Modem Interface

Software Description

Hardware Access Layer

This layer contains all the routines to access the MCU and modem hardware at the most basic level. The application layer typically does not need to access these functions directly. It consists of two source files:

■ **MCU_hardware.c**

■ **modem_hardware.c**

MCU_hardware.c

This sample code will work only on the Silicon Labs MCU C8051F12xx platform used for this example. This file contains code specific to the MCU hardware configuration such as port configuration, oscillator configuration, timers, UART, GPIOs, etc.

modem_hardware.c

This code can be ported to other applications with minimal changes needed to compile on a given host platform. This file contains code to read from or write to the modem. The two functions below provide basic access to the modem's Hardware Interface Registers:

`char readModem( tHIRREG eHIR )`: This is the main access point for unconditionally reading the modem's data and status registers in parallel or SPI mode. The function reads the HIR0 when `eHIR` is `HIR0` (0) and the HIR1 when `eHIR` is `HIR1` (1).

`void writeModem( tHIRREG eHIR, char val, char mask )`: This is the main access point for unconditionally writing the modem's data and control registers in parallel or SPI mode. The parameter `eHIR` can be `HIR0` (0) or `HIR1` (1). When writing to the HIR1, an optional mask value allows first reading the HIR1 from the modem by calling readModem(), and then setting or clearing only those bits that are high in mask. Defined values for mask are:

```
#define SiCTSb 0x01 // Clear to send (active low)
#define SiRTSb 0x02 // Request to send (active low)
#define SiESC  0x04 // Escape to command mode
#define SiINT  0x08 // Software interrupt
#define SiINTM 0x10 // Enable software interrupt
#define SiREM  0x20 // Receive FIFO empty
#define SiTXE  0x40 // Transmit FIFO almost empty interrupt
#define SiRXF  0x80 // Receive FIFO almost full interrupt
```

Boolean-OR combinations of the above are possible. This allows setting and/or clearing several bits simultaneously. Thus a mask value of 0xFF results in all bits of `val` being written to the HIR1, and a mask value of zero reads the HIR1 and simply rewrites the value just read, ignoring `val`. The mask parameter is ignored when writing to the HIR0.

Interrupt Service and Polling Layer

Sample code for this layer can be found in the **ISR_and_Polling.c** file. This code can be ported to other applications with minimal changes needed to compile on the host platform. This block contains the interrupt service routines for both modem access and MCU to PC UART access. Except for `modemCommunicationUpdate()`, the application layer typically does not need to access these functions directly. The access mode is interrupt driven by default. In order to select polling mode, the system must set the global variable `pollingNotInterruptMode` to a nonzero value. The software is designed to allow switching back and forth between polling and interrupt modes. If only one mode is ever used, the code can be simplified accordingly. The next two sections detail out the functioning of the polling and interrupt modes.

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Polling HIR1 Method

Transmitting and receiving data to and from the modem is accomplished by polling HIR1 status bits TXE and REM. Polling is implemented by the following code fragment, excerpted from `modemCommunicationUpdate()`, which must run in an infinite loop:

```
static char bytesToSend == 12;      // Declared in modemCommunicationUpdate()


if ( ( readModem( HIR1 ) & SiREM ) == 0  && rxBufferSize < MODULUS_MASK )
{
    readModemByte;
}
if ( gUARTToModemBufferSize > 0 )  // If there are data to be sent
{
    if ( bytesToSend == 12 )        // Check TXE only every twelve bytes sent
    {
        status = readModem( HIR1 ) & SiTXE;
        if ( status )               // If transmit FIFO empty
        {
            writeModem( HIR0, pullByteForModem(), 0xFF );
            bytesToSend--;
        }
    }
    else    // No need to check TXE because transmit FIFO is twelve deep
    {
        writeModem( HIR0, pullByteForModem(), 0xFF );
        bytesToSend--;
        // If the bytes to send count = 0, reset the count
        if ( bytesToSend == 0 )
        {
            bytesToSend = 12;
        }
    }
}
```

Interrupt Service Routine (ISR) Method

Transmitting and receiving data to and from the modem is accomplished by servicing the interrupts generated by the modem. The interrupt sources are described below. Whenever new communication is initiated after a period of idling with respect to the TXE interrupt, the interrupt must be "jump-started" by calling the interrupt service routine manually.

RXF Interrupt: Receive FIFO Almost Full

The RXF bit indicates the status of the receive FIFO. If this bit is set, the FIFO is either full (contains 12 bytes) or almost full (contains 10 or 11 bytes). There are two ways to clear this interrupt: the RXF bit in HIR1 can be cleared by the host, or enough bytes can be read from the receive FIFO to leave 9 bytes or less, thus removing the condition for the interrupt. If the host clears the RXF bit, the interrupt is disabled. The interrupt can be rearmed only when the receive FIFO drops below the ten-byte threshold. The interrupt can then trigger again when the receive FIFO fills up to ten bytes or more.

TXE Interrupt: Transmit FIFO Almost Empty

This interrupt occurs when only two bytes or fewer remain in the modem's transmit FIFO. The interrupt can be cleared by writing more data to the FIFO to clear the interrupt condition, or by clearing the TXE bit in the HIR1. However, if the FIFO is emptied by the modem faster than it is being filled, the TXE interrupt will either persist or trigger again. If the TXE bit is cleared, the interrupt is disabled and can be rearmed only when three bytes have been placed into the transmit FIFO. The TXE interrupt may then trigger again when the transmit FIFO drops below the three-byte threshold. If the transmit FIFO is empty and new data need to be transmitted after the TXE interrupt has been cleared, the TXE interrupt needs to be jump-started by calling `modemCommunicationUpdate()`.

Timer Interrupt: Receive FIFO Not Empty

This interrupt occurs whenever some data remained in the modem's receive FIFO without the FIFO being read for a period of time set in register U6F. This happens typically at the end of a data burst, when there aren't enough bytes in the receive FIFO to cause an RXF interrupt, and no more data are received. A timer interrupt can also occur when the receive FIFO is full if the RXF interrupt was disabled by clearing the RXF bit. The timer is also reset when new received data are added to the receive FIFO.

The reset value of U6F is 1 ms. The timer interrupt can only be cleared by reading at least one byte from the receive FIFO. If there remain bytes in the receive FIFO after servicing a timer interrupt, the timer will trigger another interrupt after the same amount of time specified in the U6F register.

U70 Interrupt

This interrupt is analogous to the interrupt pin when operating in UART mode. It is the result of a condition set in the U70 register being met, e.g. a parallel phone detection if bit PPDM was set in U70.

The U70 interrupt, indicated by the INT bit in HIR1, can be enabled and disabled using the INTM bit in the same register. The only way to clear this interrupt is by sending the AT:I command to the modem. Typically, this requires the application layer to send an ESC control word to place the modem in command mode before sending AT:I. The response from the AT:I reports the cause of the interrupt. Refer the programmer's guide for more information.

Figure 76 shows the ISR implementation for modem-originated interrupts. The interrupt service routine keeps running in a loop until all interrupt conditions are cleared. The `modemInterrupt()` sample code on page 300 shows the full ISR implementation. Refer to the `#define` statements to see how the different interrupt conditions are inferred.
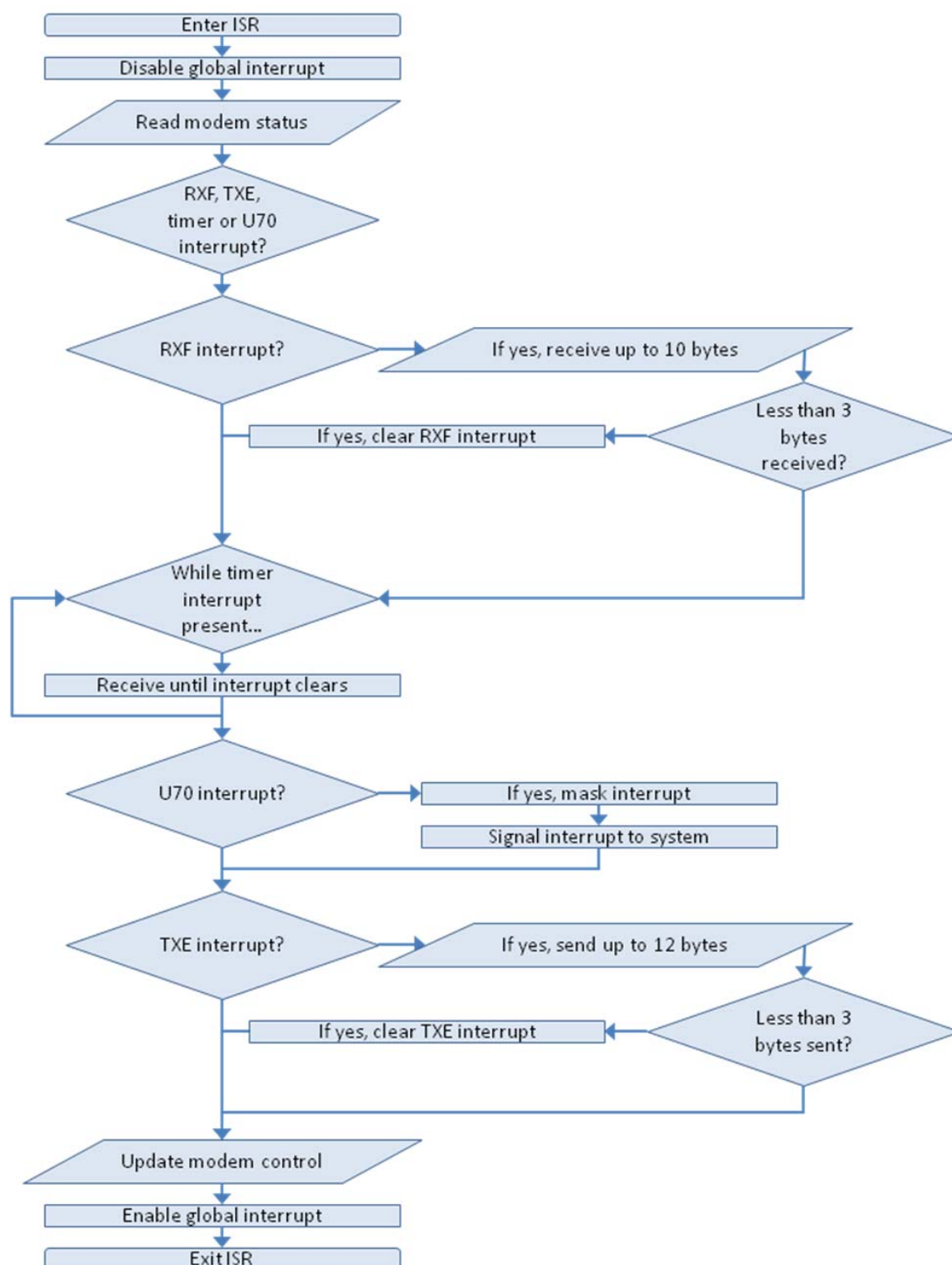
Figure 76. Parallel- or SPI-Port Interrupt-Service Flowchart

Buffer Management, Status and Control Layer

Buffer Management

Sample code for this layer can be found in the **application_buffers.c** file. This code can be ported to other applications with minimal changes needed to compile on the host platform. This block contains the buffer-management routines for both modem and UART access. The buffer structure consists of two circular buffers implemented as the following array variables:

```
char gModemToUARTBuffer[ BUFFERSIZE ];
```

The above buffer is typically filled by `modemInterrupt()` and emptied by `UART0Interrupt()`. Once the buffer is empty, subsequent TI0 (UART) interrupts have no effect. If the buffer is filled again after all TI0 interrupts have been serviced, the TI0 interrupt needs jump starting. This is accomplished by calling `UARTCommunicationUpdate()` after filling the buffer.

```
char gUARTToModemBuffer[ BUFFERSIZE ];
```

The above buffer is typically filled by `UART0Interrupt()` and emptied by `modemInterrupt()`. Once the buffer is empty, subsequent TXE (modem) interrupts have no effect. If the buffer is filled again after all TXE interrupts have been serviced, the TXE interrupt needs jump starting. This is accomplished by calling `modemCommunicationUpdate()` after filling the buffer.

The two arrays above must be sized by choosing a power of two for the value of `BUFFERSIZE`, defined in **modem_80C51.h**. This is because keeping track of the circular-buffer indexes requires modulus operations. Instead of costly integer divisions with remainder, the modulus operation is achieved by bit masking using the all-one bit pattern equal to `BUFFERSIZE` minus one. For example, if `BUFFERSIZE` is 1024 (2^{10}), the bit mask (`MODULUS_MASK`) used for updating buffer pointers modulo `BUFFERSIZE` must be 1023 (0011 1111 1111). When a buffer index reaches the value 1024 (0100 0000 0000), a bitwise-AND operation with `MODULUS_MASK` will reset the index value to zero. If the value of `BUFFERSIZE` is changed in the header file, then the value of `MODULUS_MASK` must be set to the same value minus one. The following global variables track the state of the buffers. A value of zero indicates an empty buffer.

```
int gModemToUARTBufferSize;
```
```
int gUARTToModemBufferSize;
```

Read and write addresses to the above buffers are tracked by the following pointers:

```
int gLastFromUART;  // The last byte that was added to gUARTToModemBuffer[]
int gNextToModem;   // The first byte that will be taken out of gUARTToModemBuffer[]
int gLastFromModem; // The last byte that was added to gModemToUARTBuffer[]
int gNextToUART;    // The first byte that will be taken out of gModemToUARTBuffer[]
```

The flow of data between the modem and the UART is managed by the following functions:

```
char pullByteForModem( void );          // Remove a byte from gUARTToModemBuffer[]
char pullByteForUART( void );           // Remove a byte from gModemToUARTBuffer[]
void pushByteToModem( char byteToSend ); // Add a byte to gUARTToModemBuffer[]
void pushByteToUART( char byteToSend );  // Add a byte to gModemToUARTBuffer[]
```

Figure 77 summarizes the interactions between the function calls, pointers and buffers described above.
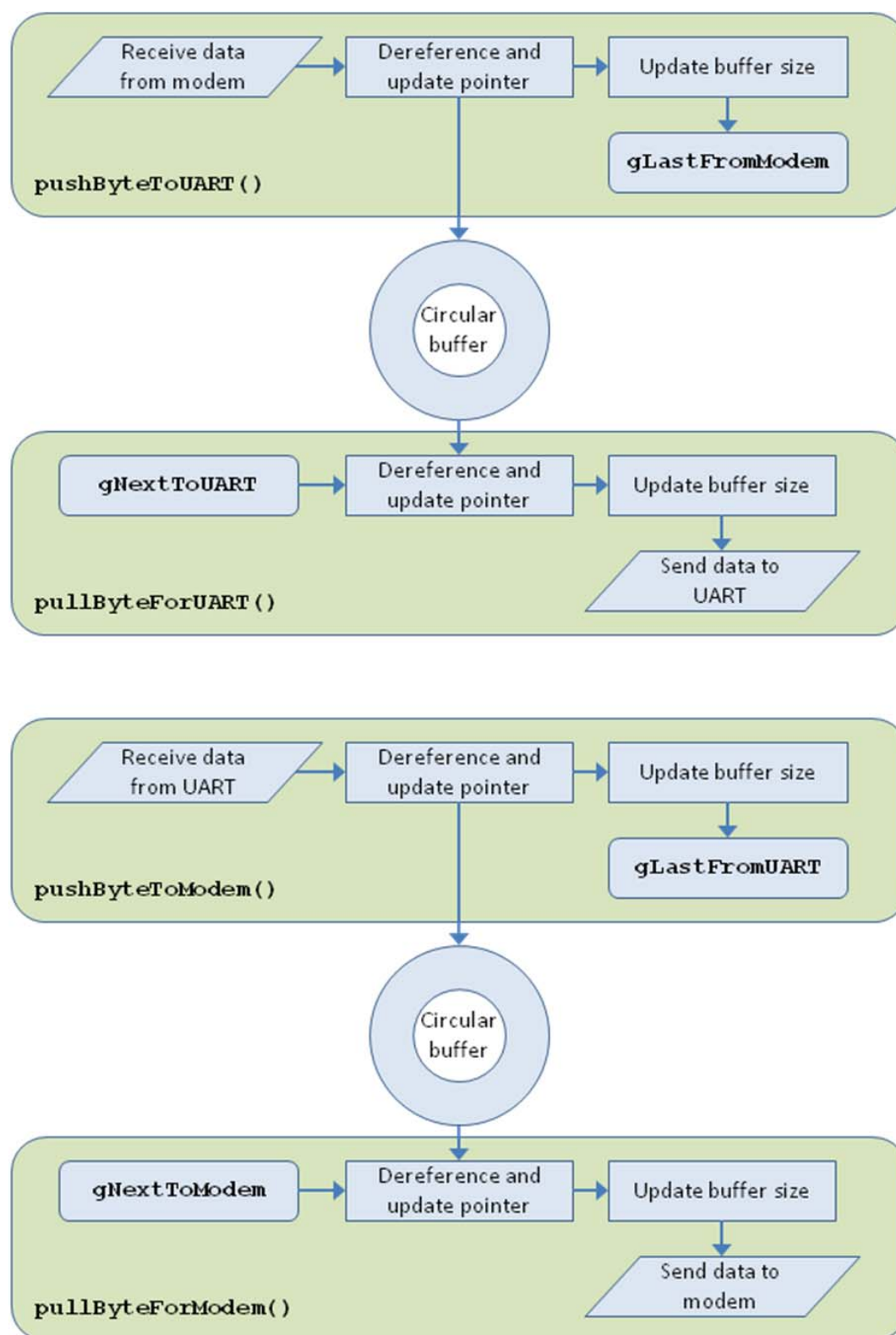
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Figure 77. Circular-Buffer Flowchart

Status and Control

Sample code for this layer can be found in status_control.c file. This code can be ported to other applications with minimal changes needed to compile on the host platform. The modem status may be queried, and modem control flags may be set using the two functions below:

`void setControl( char controlCode, char action, char condition )`: Set modem control. Possible control codes are:

`SiESC`: Set or clear escape flag.

`SiINTM`: Enable or disable U70 interrupt.

The action may be `ENABLE` or `DISABLE`. Control takes effect upon one of two conditions:

`NOW`: Unconditionally upon entering the function call.

`WHEN_TX_BUF_EMPTY`: The `setControl()` function loops until the `gUARTToModemBuffer[]` is empty. This enables, for instance, setting the escape code after a given data set has been transmitted, prior to sending AT commands. It is up to the application to ensure the buffer empties within a reasonable amount of time.

`char queryU70IntStatus( void )`: Returns the INT flag from the ISOmodem at the same bit position as in the HIR1 register.

The Application Layer: Sample Application

Sample code for an application can be found in the **modem_main.c** and **modem_80C51.h** files. This code is application and host platform specific. By default, the program simply passes data back and forth between the modem and the UART using the buffers and function calls described above. The minimal application is shown below:

```
char gPollingNotInterruptMode = 0;  // Interrupt mode by default


void main( void )
{
    EA = 0;                         // Disable global interrupt
    EA = 0;                         // Dummy, as per MCU data sheet
    initApplicationBuffers();
    initHardware();
    setControl( SiESC, DISABLE, NOW );
    IT1 = 1;                        // External interrupt 1 is edge triggered
    EX1 = 1;                        // Enable external interrupt 1
    PS = 1;                         // High interrupt priority for UART0
    PX1 = 0;                        // Low interrupt priority for modem side
    EA = 1;                         // Enable global interrupt
    while ( 1 )
    {
        modemCommunicationUpdate();
        UARTCommunicationUpdate();
    }
}
```

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The infinite loop has two functions depending on the use of interrupts or polling for modem communication:

1. In interrupt mode, the TXE (modem) and TI0 (UART) interrupts are always jump-started by making periodic calls to `modemCommunicationUpdate()` and to `UARTCommunicationUpdate()`, respectively. The calls are necessary only to jump-start the modem and UART transmit interrupts. A system that is aware of the transmit activity for both the modem and the UART can reduce the number of calls, thereby freeing MCU bandwidth for other tasks.

2. In polling mode, only TI0 (UART) interrupts need jump-starting using periodic calls to `UARTCommunicationUpdate()`, and repeated calls to `modemCommunicationUpdate()` are necessary to poll the modem's HIR1 and determine the status of the transmit and receive FIFOs. An obvious limitation of the polling method is the need to constantly poll the modem for a change of FIFO state, which uses up MCU bandwidth.

Compiler Option: Dot Commands

To include diagnostic (dot command) functions, define `DIAGNOSTICS` by removing the comment slashes (`//`) at the appropriate line in the **modem_80C51.h** header file, and include the files **dot_command_loop.c** and **test_code.c** in the project build. Contact Silicon Labs for more details on diagnostic commands.

Modem Operation

Initialization

After reset, the ISOmodem does not by default have all the required features enabled. When using the parallel or SPI mode, Silicon Labs recommends the following initialization steps:

1. Push the command AT:U70,8F00 followed by carriage return into the transmit buffer. The setting of U70 can vary, but it is recommended that bit 15 (HES) be set to enable escape.

2. Monitor the receive buffer for OK, indicating that the command was successful.

3. If a firmware upgrade needs to be programmed into the part, push the upgrade into the transmit buffer one line at a time. The OK prompt must be received after each line.

4. Once the patch is written to the ISOmodem, other commands can be pushed into the transmit buffer.

5. If software interrupts are required, enable them by calling:

`setControl( SiINTM, ENABLE, NOW ).`

Silicon Labs also recommends the use of any firmware upgrade (provided by Silicon Labs) if called for in the errata for that revision. Firmware upgrades address known problems with a given revision.

Making a Connection

Making a connection in parallel or SPI mode is no different than in UART mode. The application layer should keep track of whether the ISOmodem is in command mode or data mode to determine whether to send an escape before sending commands. The steps for making a connection are as follows:

1. Clear the HIR1 ESC bit by calling `setControl( SiESC, DISABLE, NOW )`.

2. Push the dial string into the transmit buffer, and begin monitoring for the CONNECT response.

3. The ISOmodem is now in data mode when the connect/protocol response is received.

4. The application layer can begin pushing data to the modem for transmission over the phone line. Received data will accumulate in the receive buffer as a result of polling or interrupts.

Data Bursts

The ISOmodem has internal buffering of approximately one kilobyte in each of the receive and transmit directions. The modem attempts to empty and fill these buffers as quickly as possible. This results in transmit and receive data bursts at a much faster rate than the modem connection. The receive bursts are limited by the V.42 frame size and the V.42bis data compression ratio. The higher the compression ratio, the longer the burst will be. The transmit bursts can be as large as one kilobyte when transmission first begins. Once the buffer is full, the transmit bursts are also limited by the V.42 frame size and compression ratio.

Modem Interrupt Service Sample Code

The following is the C code for the modem ISR. Also refer to "Figure 76. Parallel- or SPI-Port Interrupt-Service Flowchart" for more explanations. Please contact Silicon Labs to obtain a complete C8051F12xx project bundle.

```c
// Macros for modem ISR readability
#define RXFInterrupt        ( modem_status & SiRXF )
#define TXEInterrupt        ( modem_status & ( SiTXE & modem_control ) )
#define TimerInterrupt ( !( modem_status & SiREM ) && !RXFInterrupt && !rxf_processed )
#define U70Interrupt        ( modem_status & ( SiINT & ( modem_status >> 1 ) ) )
#define RTSIsSet            ( modem_status & SiRTSb )
#define ClearRTS            ( modem_control &= ~SiRTSb )
#define ClearRXF            ( modem_control &= ~SiRXF )
#define ClearTXE            ( modem_control &= ~SiTXE )
#define ClearINTM           ( modem_control &= ~SiINTM )
#define rxBufferSize        gModemToUARTBufferSize
#define ReadModemStatus     modem_status = readModem( HIR1 )
#define readModemByte       pushByteToUART( readModem( HIR0 ) )


//-----------------------------------------------------------------------------
// Interrupt service routine
//-----------------------------------------------------------------------------
// modemInterrupt()
//-----------------------------------------------------------------------------
// Invoked whenever the modem issues an interrupt: this is meant as reference
// code for parallel-port/SPI interrupt service.
//
// Parameters:   None
// Return value: None
//-----------------------------------------------------------------------------
void modemInterrupt( void ) interrupt 2
{
    char modem_status;
    char modem_control; // Modem control before writing (written only if modifed)
    char control_update = 0;  // Tracks whether control register was modified, needs updating
    char rxf_processed = 0;
    int BytesSent;
    int BytesReceived = 0;
    char SFRPAGE_SAVE;

    EA = 0;                     // Disable global interrupt
    EA = 0;                     // Dummy operation required by MCU, as per MCU data sheet
    SFRPAGE_SAVE = SFRPAGE;     // Save Current SFR page
    ReadModemStatus;            // Read HIR1 to get current status

    // Set default write value. Always write the RXF and TXE bits to 1 by default
    // to avoid inadvertently clearing those interrupts
    modem_control = modem_status | SiTXE | SiRXF;

    // Clear the RTS bit if it's set. The part comes out of reset with RTS set.
    // RTS will have no effect unless the modem gets the AT\Q3 command.
    // If RTS isn't needed this code can be removed.
    if ( RTSIsSet )
    {
        ClearRTS;        // Clear the RTSb so data enters FIFO
        control_update = 1;
```

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```
    }

// This is the main ISR handler loop: stay in it until all interrupts are cleared
while ( RXFInterrupt || TXEInterrupt || TimerInterrupt || U70Interrupt )
{
    // ***RXF INTERRUPT***
    // Separate RXF interrupt from timer interrupt to reduce the number of HIR1 reads.
    if ( RXFInterrupt )
    {
        // MODULUS_MASK is BUFFERSIZE - 1
        while ( ( rxBufferSize < MODULUS_MASK ) && ( BytesReceived < 10 ) )
        {
            readModemByte;
            // Set a flag to know that RXF was serviced
            rxf_processed = 1;
            BytesReceived++;
        }

        // Clear the RXF interrupt if fewer than 3 bytes were read. If more than 3 bytes
        // were read from the FIFO the interrupt will be cleared automatically.
        if (BytesReceived < 3)
        {
            ClearRXF;         // Clear RXF since we didn't empty the FIFO
            control_update = 1;
        }
    }
    // ***TIMER INTERRUPT***
    // If there wasn't an RXF interrupt, but the receive FIFO isn't empty,
    // the interrupt may have been caused by the receive timer interrupt.
    // Note: If the host cannot empty its queue fast enough to keep up with the
    // modem or if it is going to have a long period of time (>:U6F setting) where
    // there won't be room in the FIFO, it would be better to completely disable
    // the interrupt until the host has made room for more data. The timer interrupt
    // can only be cleared by reading a byte from the FIFO; if there is no room
    // in the FIFO, the interrupt will not be cleared. Alternatively, the routine
    // could read a byte to clear the interrupt and then discard the data.
    // MODULUS_MASK is BUFFERSIZE - 1
    while ( TimerInterrupt && ( rxBufferSize < MODULUS_MASK ) )
    {
        // Read a byte
        readModemByte;
        BytesReceived++;
        // Check the status to see if the FIFO is empty
        ReadModemStatus;
    }
    // ***U70 INTERRUPT***
    // Check for a "software" interrupt. "software" refers to any of the interrupts
    // described in U70 in the modem datasheet.  Only do this if the
    // software interrupt is not masked. This is the reason for the bit shift.
    if ( U70Interrupt )
    {
        // Mask the interrupt so that it doesn't cause another interrupt
        // until the host software clears it with AT:I and tells us to
        // turn it back on
        ClearINTM;
        control_update = 1;
```

```
            // Insert code here to inform the host of the U70 interrupt
            // or service it application dependent), e.g.
            gU70Interrupt = 1;
        }


        // ***TXE INTERRUPT***
        if ( TXEInterrupt )
        {
            // Clear the data sent counter
            BytesSent = 0;

            // The transmit FIFO is fourteen bytes deep, therefore upon TXE interrupts
            // (two bytes or fewer in the transmit FIFO), it is possible to send up to
            // twelve bytes to the part without risking overflow.
            while ( ( gUARTToModemBufferSize > 0 ) && ( BytesSent < 12 ) )
            {
                writeModem( HIR0, pullByteForModem(), 0xFF );
                BytesSent++;
            }

            // If there weren't enough data sent to clear the interrupt, clear it manually.
            if ( BytesSent < 3 )
            {
                // Clear the TXE bit to clear the interrupt
                ClearTXE;
                control_update = 1;
            }
        }
        // Check if the status register needs to be written
        if ( control_update )
        {
            writeModem( HIR1, modem_control, 0xFF );
            control_update = 0;
        }

        // Read register 1 to get current status
        ReadModemStatus;

        // Reset receiver counter for a subsequent RXF condition in this loop
        BytesReceived = 0;
    }
    SFRPAGE = SFRPAGE_SAVE;      // Restore SFR page
    EA = 1;                      // Enable global interrupt
}
```

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DOCUMENT CHANGE LIST

Revision 0.5 to Revision 0.6

- Added Si2493 to title.
- Added V.92 information.
- Added V.44 information.
- Added and expanded several AT+ commands.
- Added U71 and U9F-UAA registers.
- Corrected CTS* trigger points.
- Added note for U70 configuration for Australia and Brazil
- Expanded "5.14. Legacy Synchronous DCE Mode/ V.80 Synchronous Access Mode".
- Added "2.5. PCM/Voice Mode (24-Pin TSSOP and 38-Pin QFN Only)".
- Added "6.4. SMS Support".
- Added "6.5. Type II Caller ID/SAS Detection".
- Added "6.7. Modem-On-Hold".
- Added "6.12. V.92 Quick Connect".

Revision 0.6 to Revision 0.7

- Added V.29 FC to Table 1.
- Updated part numbers in "4.3. Bill of Materials".
- Updated EE section and example code.
- Updated Table 46, "U-Register Descriptions," on page 91.
- Updated U63 bit map.
- Updated U7D bit map
- Updated "22.1. Country Register Settings for CTR/ TBR21 ATAAB and CTR21 Type Countries" on page 138.
- Corrected New Zealand Pulse dial settings in "22.20 Country Register Settings for New Zealand" on page 147.
- Updated Table 102 on page 163.
- Deleted references to U69 (now for internal use only).

Revision 0.7 to Revision 0.8

- Updates to Registers CALT and GEND.

Revision 0.8 to Revision 0.9

- Document format changes.
- Minor text edits.
- Deleted Legacy-Synchronous mode.
- Updated layout guidelines.
- Updated country configuration tables.
- Added "Appendix C—Si3008 Supplement".
- Added "Appendix D—EPOS Application".

Revision 0.9 to Revision 1.0

- Added "Appendix D—Si3006/3009 Supplement" for for 3006 and 3009 DAA support.

Revision 1.0 to Revision 1.1

- Major revision to reflect the latest Si24xx ISOmodem product offerings.
- Added support for new product features: SPI interface and 32.768 kHz clock input.
- Added software support for parallel and SPI interfaces.

Revision 1.1 to Revision 1.2

- Correction to SPI and 32.768 kHz and SPI strapping tables.
- Added several registers.
- Removed Appendix D.
- Updated for Si2493/57/34/15/04 Revision D.
- Added Si2493 and Si2439 configuration and voice functions.

Revision 1.2 to Revision 1.3

- Added Si2494 and Si2439 configuration and voice functions.
- Added "2.5. SSI/Voice Mode (24-Pin TSSOP and 38-Pin QFN Only)" on page 30.
- Added "5.13. EPOS (Electronic Point of Sale) Applications" on page 125.
- Added "7. Handset, TAM, and Speakerphone Operation" on page 173.
- Added "8. Security Protocols" on page 224.
- Added "9. Chinese ePOS SMS" on page 234.

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